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## Skorokhod Imbedding via Stochastic Integrals

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Given a Brownian motion $L_{t}$ and a probability measure $\mu$ on $\mathbb{R}$ with mean 0 , a Skorokhod imbedding of $\mu$ is a stopping time $T$ adapted to the sigma fields of $L_{t}$ such that $L_{T}$ has distribution $\mu$. We give here a new method of constructing such an imbedding using results from the representation of martingales as stochastic integrals.

We first construct a Brownian motion $N_{t}$ and a stopping time $W$ such that $N_{W}$ has law $\mu$. We then show how, given an arbitrary Brownian motion $L_{t}$, one can construct a stopping time $T$ such that $L_{T}$ has law $\mu$.

Define $p_{t}(y)=(2 \pi t)^{-1 / 2} e^{-y^{2} / 2 t}, q_{t}(y)=\partial p_{t}(y) / \partial y=-(2 \pi t)^{-1 / 2}(y / t) e^{-y^{2} / 2 t}$.
Let $X_{t}$ be a Brownian motion, ${\underset{F}{t}}^{t}$ its filtration, and $g$ a real-valued function.
Lemma 1. Suppose $E\left|g\left(X_{1}\right)\right|<\infty$. Then
a) $\sup _{|y| \leq y_{0}} \int g(z)|z-y|^{k} e^{-(z-y)^{2} / 2 t} d z<\infty \quad \underline{\text { for }}$ all positive $k$, all $y_{0}$, all $t<1$.
b) $g\left(X_{1}\right)=E g\left(X_{1}\right)+\int_{0}^{1} a\left(s, X_{s}\right) d X_{s}$, where $a(s, y)=\int q_{1-s}(z-y) g(z) d z$ for $s<1$; furthermore $\int_{0}^{1} a^{2}\left(s, X_{s}\right) d s<\infty$, a.s.
c) $E\left(g\left(X_{1}\right) \mid \underline{\underline{F}}_{s}\right)=b\left(s, X_{s}\right)$ for $s<1$, where $b(s, y)=\int p_{1-s}(z-y) g(z) d z$.

Proof. a) follows from the formula for the normal density and the fact that $|z-y|^{k} e^{-(z-y)^{2} / 2 t} \leq e^{-z^{2} / 2}$ for $z$ large.
b) Suppose first that $g$ is bounded, has compact support, and is in $C^{2}$. By Clark's formula [1] applied to the functional $\mathrm{g}\left(\mathrm{X}_{1}\right)$,

$$
g\left(X_{1}\right)=E g\left(X_{1}\right)+\int_{0}^{1} E\left[g^{\prime}\left(X_{1}\right) \mid \underline{E}_{s}\right] d X_{s}
$$

(Another derivation of this representation is to use Ito's lemma to take care of the case $g(x)=e^{i u x}$ and then use linearity and a limiting process.)

By the Markov property, if $\mathrm{s}<1$,

$$
E\left[g^{\prime}\left(X_{1}\right) \mid{\underset{\underline{F}}{s}}\right]=\int g^{\prime}(z) p_{1-s}\left(X_{s}-z\right) d z
$$

An integration by parts gives the result for such $g$; the result for general g follows by a limit argument.
c) By the Markov property, if $s<1$,

$$
\mathrm{E}\left[g\left(X_{1}\right) \mid \underline{\underline{F}}_{s}\right]=\int g(z) p_{1-s}\left(X_{s}-z\right) d z
$$

Lemma 2. Suppose $g$ is nondecreasing and not identically constant. Then
a) On compact subsets of $[0,1) \times \mathbb{R}, a(s, y)$ is bounded above, bounded below away from 0 , and uniformly Lipschitz in $s$ and $y$.
b) For each $s<1, b(s, y)$ is continuous and strictly increasing as a function of $y$.
c) For each $s<1$, let $B(s, \cdot)$ be the inverse of $b(s, \cdot)$; then on compact subsets of its domain, $B(s, y)$ is uniformly Lipschitz in $s$ and jointly continuous in $s$ and $y$.

Proof. a) Suppose $|y| \leq y_{0}, s \leq s_{0}<1$. $a(s, y)$ is bounded above by lemma 1a. An integration by parts argument shows that $a(s, y)=\int p_{1-s}(y-z) d g(z)$, hence a is bounded below. Using the definition of $a(s, y)$, appropriate bounds on $\partial q_{1-s} / \partial s$ and $\partial q_{1-s} / \partial y$, and lemma la gives the uniformly Lipschitz result.
b) The definition of $b$ shows that $b(s, \cdot)$ is continuous. Since we also have $b(s, y)=\int g(y+z) p_{1-s}(z) d z$, it follows that $b(s, \cdot)$ is nondecreasing, and in fact, strictly increasing since $g$ is not constant. Note that this implies that the range of $b(s, \cdot)$ must be an open (possibly infinite) interval.
c) Since $b(s, \cdot)$ is continuous and strictly increasing, we can define its inverse $B(s, \cdot)$ on the range of $b(s, \cdot)$. $B(s, y)$ will be continuous in $y$.

Integrating by parts,

$$
\partial b / \partial y=\int p_{1-s}(y-z) d g(z),
$$

which is uniformly $>0$ for $s, y$ in a compact subset of $[0,1) \times \mathbf{R} \cdot \partial b / \partial s$ is bounded above on compact sets since $\partial p_{1-s} / \partial s$ is, using lemma 1 a again.

We now show that $B$ is uniformly Lipschitz in $s, s, y$ in a compact subset of the domain of $B$. Let $w=B(s+h, y), x=B(s, y)$, and suppose $w \leq x$,
the other case being similar. Then

$$
0=b(s+h, w)-b(s, x)=b(s+h, w)-b(s, w)+b(s, w)-b(s, x) \leq c|h|-c(x-w)
$$

or $\quad|x-w| \leq c|h| / c$,
where $C$ and $c$ are upper and lower bounds for $\partial b / \partial s$ and $\partial b / \partial y$, respectively.
This proves that $B$ is uniformly Lipschitz in $s$, and it follows immediately that $B$ is jointly continuous.

Now let $\mu$ be a probability measure on $\mathbb{R}$ and suppose $\int\{x \mid d \mu(x)<\infty$ and $\int x \operatorname{d\mu }(x)=0$. Let $F(x)=\mu(-\infty, x]$, let $F^{-1}(y)=\inf \{x: F(x) \geq y\}$, let $\Phi(x)=\int_{-\infty}^{x} p_{1}(y) d y$, and let $g(x)=F^{-1}(\Phi(x))$. Then $g\left(X_{1}\right)$ has distribution $\mu$ and $E g\left(X_{1}\right)=0$.

Define $M_{t}=\int_{0}^{t} a\left(s, X_{s}\right) d X_{s}$, where $a(s, y)$ is given by lemma 1 for $s<1$, $a(s, y)=1$ for $s \geq 1$. Note $M_{1}=g\left(X_{1}\right)$ has law $\mu$, and if $s<1$, $M_{s}=b\left(s, X_{s}\right)$. Let $R(t)=\int_{0}^{t} a^{2}\left(s, X_{s}\right)$, define $S(t)=\inf \{r: R(r) \geq t\}$, and let $N_{t}=M_{S(t)}$. Since the quadratic variation of the continuous martingale $N$ is $t, N$ is a Brownian motion.
$N_{R(1)}=M_{1}$, which has law $\mu$. Letting $W=R(1)$, it suffices to show that $R(1)$ is a stopping time of the $N_{t}$ process.

Proposition 3. (cf. Yershov, [2]). ( $W \geq u$ ) is in the right continuous
completion of $\sigma\left(N_{s} ; s \leq u\right)$.

Proof. Since $W=R(1)=\lim _{s \rightarrow 1} R(s)$ by monotone convergence, it suffices to consider $R(s), s<1 .(R(s) \geq u)=(s \geq S(u))$.

It is not hard to see that $S(t)$ satisfies the equation

$$
\begin{gathered}
\frac{d S(t)}{d t}=a^{-2}\left(S(t), X_{S(t)}\right) \\
\text { if } S(t)<1 \text {. But } X_{S(t)}=B\left(S(t), M_{S(t)}\right)=B\left(S(t), N_{t}\right) \text {. Thus, for each } \omega \text {, } \\
S(t) \text { satisfies the ordinary differential equation }
\end{gathered}
$$

(1) $\frac{\mathrm{dS}(\mathrm{t})}{\mathrm{dt}}=\mathrm{a}^{-2}\left(\mathrm{~S}(\mathrm{t}), \mathrm{B}\left(\mathrm{S}(\mathrm{t}), \mathrm{N}_{\mathrm{t}}\right)\right)$.

For each $\omega,\left\{\left(S(t), N_{t}\right): S(t) \leq s\right\}$ is contained in a compact subset of the domain of $B$. This, lemma 2, and a theorem on uniqueness of solutions of
differential equations [3, pp.1-6] show that there is a unique solution $S(t)$ to (1) up to the first $t$ for which $S(t)=s$. Moreover, this solution may be constructed via Picard iteration. But then $(s \geq S(u))$ is in the right continuous completion of $\sigma\left(N_{s} ; s \leq u\right)$ as required.

Suppose now that $L$ is any Brownian motion. We construct an L-measurable stopping time $T$ such that $L$ has law $\mu$. Let $V(t)$ be the unique solution to

$$
\frac{d V(t)}{d t}=a^{-2}\left(V(t), B\left(V(t), L_{t}\right)\right)
$$

for each $\omega$. (Since $L_{t}$ has the same law as $N_{t},\left\{\left(V(t), L_{t}\right): V(t) \leq s\right\}$ will be in a compact subset of the domain of $B$, a.s.) Let $U(t)=V^{-1}(t), t<1$ and let $T=U(1)=\sup _{s<1} U(s)$. Clearly the law of $(L, T)$ is the same as the law of $(\mathrm{N}, \mathrm{W})$, and so $\mathrm{L}_{\mathrm{T}}$ has distribution $\mu$.
$\mathrm{T}^{1 / 2}$ will satisfy certain moment conditions if $\mu$ does. For example, suppose $\Psi:[0, \infty) \rightarrow[0, \infty)$ is continuous, $\int \Psi(|x|) d \mu(x)<\infty$, and for some $\varepsilon>0, \Psi^{1 /(1+\varepsilon)}$ is convex and increasing. By Doob's inequality applied to the submartingale $\Psi^{1 /(1+\varepsilon)}\left(\left|M_{S}\right|\right), E \sup _{S \leq 1} \Psi\left(\left|M_{S}\right|\right)<\infty$ since $E \Psi\left(\left|M_{1}\right|\right)<\infty$. Then by Burkholder's inequality, $\mathrm{E} \Psi\left(\mathrm{W}^{1 / 2}\right)<\infty$.

If $Y_{t}$ is a d-dimensional Brownian motion, $d \geq 2$, it is known that there are measures $\mu$ for which one cannot find a stopping time $T$ with $\mu$ the law of $Y_{T}$ : just take $\mu$ atomic and recall that d-dimensional Brownian motion does not hit points. However, one can always find $f: \mathbb{R} \rightarrow \mathbb{R}^{\mathrm{d}}$ such that the law of $f\left(X_{1}\right)$ is $\mu, X_{t}$ a 1 -dimensional Brownian motion. (The coordinate functions of $f$ are not assumed to be nondecreasing.) One can then use lemma 1 to find a vector-valued function $A:[0,1) \times \mathbb{R} \rightarrow \mathbb{R}^{d}$ such that $f\left(X_{1}\right)=$ $E f\left(X_{1}\right)+\int_{0}^{1} A\left(s, X_{s}\right) d X_{s}$.

## REFERENCES

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