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Skorokhod Imbedding via Stochastic Integrals

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Given a Brownian motion L_t and a probability measure μ on \mathbb{R} with mean 0, a Skorokhod imbedding of μ is a stopping time T adapted to the sigma fields of L_t such that L_T has distribution μ . We give here a new method of constructing such an imbedding using results from the representation of martingales as stochastic integrals.

We first construct a Brownian motion N_t and a stopping time W such that N_W has law μ . We then show how, given an arbitrary Brownian motion L_t , one can construct a stopping time T such that L_{τ} has law μ .

Define $p_t(y) = (2\pi t)^{-1/2} e^{-y^2/2t}$, $q_t(y) = \partial p_t(y)/\partial y = -(2\pi t)^{-1/2} (y/t) e^{-y^2/2t}$.

Let X_t be a Brownian motion, \underline{F}_t its filtration, and g a real-valued function.

- - b) $g(X_1) = Eg(X_1) + \int_0^1 a(s, X_s) dX_s$, where $a(s, y) = \int q_{1-s}(z-y)g(z) dz$ for s < 1; furthermore $\int_0^1 a^2(s, X_s) ds < \infty$, a.s.

c)
$$\mathbb{E}(g(X_1)|F_s) = b(s,X_s)$$
 for $s < 1$, where $b(s,y) = \int p_{1-s}(z-y)g(z)dz$.

<u>Proof</u>. a) follows from the formula for the normal density and the fact that $|z-y|^k e^{-(z-y)^2/2t} \le e^{-z^2/2}$ for z large.

b) Suppose first that g is bounded, has compact support, and is in C^2 . By Clark's formula [1] applied to the functional $g(X_1)$,

$$g(X_1) = Eg(X_1) + \int_0^1 E[g'(X_1)|_{=s}^F] dX_s$$

(Another derivation of this representation is to use Ito's lemma to take care of the case $g(x) = e^{iux}$ and then use linearity and a limiting process.)

By the Markov property, if s < 1,

$$E[g'(X_1)|_{F_s}] = \int g'(z)p_{1-s}(X_s - z)dz$$
.

An integration by parts gives the result for such g; the result for general g follows by a limit argument.

c) By the Markov property, if s < 1,

$$\mathbb{E}[g(X_1)|_{=s}] = \int g(z)p_{1-s}(X_s - z)dz . \square$$

Lemma 2. Suppose g is nondecreasing and not identically constant. Then

- a) On compact subsets of $[0,1) \times \mathbb{R}$, a(s,y) is bounded above, bounded below away from 0, and uniformly Lipschitz in s and y.
- b) For each s < 1 , b(s,y) is continuous and strictly increasing as a function of y .</p>
- c) For each s < 1, let B(s, •) be the inverse of b(s, •); then on compact subsets of its domain, B(s,y) is uniformly Lipschitz in s and jointly continuous in s and y.

<u>Proof</u>. a) Suppose $|y| \le y_0$, $s \le s_0 < 1$. a(s,y) is bounded above by lemma 1a. An integration by parts argument shows that $a(s,y) = \int p_{1-s}(y-z)dg(z)$, hence a is bounded below. Using the definition of a(s,y), appropriate bounds on $\partial q_{1-s}/\partial s$ and $\partial q_{1-s}/\partial y$, and lemma 1a gives the uniformly Lipschitz result.

b) The definition of b shows that $b(s, \cdot)$ is continuous. Since we also have $b(s,y) = \int g(y+z)p_{1-s}(z)dz$, it follows that $b(s, \cdot)$ is nondecreasing, and in fact, strictly increasing since g is not constant. Note that this implies that the range of $b(s, \cdot)$ must be an open (possibly infinite) interval.

c) Since $b(s, \cdot)$ is continuous and strictly increasing, we can define its inverse $B(s, \cdot)$ on the range of $b(s, \cdot)$. B(s, y) will be continuous in y.

Integrating by parts,

 $\partial b/\partial y = \int p_{1-s}(y-z)dg(z)$,

which is uniformly > 0 for s,y in a compact subset of $[0,1) \times \mathbb{R}$. $\partial b/\partial s$ is bounded above on compact sets since $\partial p_{1-s}/\partial s$ is, using lemma la again.

We now show that B is uniformly Lipschitz in s , s,y in a compact subset of the domain of B. Let w = B(s+h,y), x = B(s,y), and suppose $w \le x$,

the other case being similar. Then

or

$$0 = b(s+h,w) - b(s,x) = b(s+h,w) - b(s,w) + b(s,w) - b(s,x) \le C|h| - c(x-w),$$
$$|x-w| \le C|h| /c ,$$

where C and c are upper and lower bounds for $\partial b/\partial s$ and $\partial b/\partial y$, respectively. This proves that B is uniformly Lipschitz in s, and it follows immediately that B is jointly continuous.

Now let μ be a probability measure on \mathbb{R} and suppose $\int |x| d\mu(x) < \infty$ and $\int x d\mu(x) = 0$. Let $F(x) = \mu(-\infty, x]$, let $F^{-1}(y) = \inf\{x: F(x) \ge y\}$, let $\Phi(x) = \int_{-\infty}^{x} p_1(y) dy$, and let $g(x) = F^{-1}(\Phi(x))$. Then $g(X_1)$ has distribution μ and $Eg(X_1) = 0$.

Define $M_t = \int_0^t a(s, X_s) dX_s$, where a(s, y) is given by lemma 1 for s < 1, a(s, y) = 1 for $s \ge 1$. Note $M_1 = g(X_1)$ has law μ , and if s < 1, $M_s = b(s, X_s)$. Let $R(t) = \int_0^t a^2(s, X_s)$, define $S(t) = \inf\{r: R(r) \ge t\}$, and let $N_t = M_{S(t)}$. Since the quadratic variation of the continuous martingale N is t, N is a Brownian motion.

 $N_{R(1)} = M_1$, which has law μ . Letting W = R(1), it suffices to show that R(1) is a stopping time of the N_+ process.

<u>Proposition</u> 3. (cf. Yershov, [2]). ($W \ge u$) is in the right continuous completion of $\sigma(N_s; s \le u)$.

<u>Proof.</u> Since $W = R(1) = \lim_{s \to 1} R(s)$ by monotone convergence, it suffices to consider R(s), s < 1. $(R(s) \ge u) = (s \ge S(u))$.

It is not hard to see that S(t) satisfies the equation

$$\frac{dS(t)}{dt} = a^{-2}(S(t), X_{S(t)})$$

if S(t) < 1. But $X_{S(t)} = B(S(t), M_{S(t)}) = B(S(t), N_t)$. Thus, for each ω , S(t) satisfies the ordinary differential equation

(1)
$$\frac{dS(t)}{dt} = a^{-2}(S(t), B(S(t), N_t))$$
.

For each ω , {(S(t), N_t): S(t) \leq s} is contained in a compact subset of the domain of B. This, lemma 2, and a theorem on uniqueness of solutions of differential equations [3, pp.1-6] show that there is a unique solution S(t) to (1) up to the first t for which S(t) = s. Moreover, this solution may be constructed via Picard iteration. But then $(s \ge S(u))$ is in the right continuous completion of $\sigma(N_c; s \le u)$ as required.

Suppose now that L is any Brownian motion. We construct an L-measurable stopping time T such that L has law μ . Let V(t) be the unique solution to

$$\frac{dV(t)}{dt} = a^{-2}(V(t), B(V(t), L_t))$$

for each ω . (Since L_t has the same law as N_t , {(V(t), L_t): V(t) \leq s} will be in a compact subset of the domain of B, a.s.) Let $U(t) = V^{-1}(t)$, $t \leq 1$ and let $T = U(1) = \sup_{s \leq 1} U(s)$. Clearly the law of (L,T) is the same as the law of (N,W), and so L_T has distribution μ .

$$\begin{split} & T^{1/2} \quad \text{will satisfy certain moment conditions if } \mu \quad \text{does. For example,} \\ & \text{suppose } \Psi\colon [0,\infty) \to [0,\infty) \text{ is continuous, } \int \Psi(|\mathbf{x}|) \mathrm{d}\mu(\mathbf{x}) < \infty \text{ , and for some} \\ & \varepsilon > 0 \text{ , } \Psi^{1/(1+\varepsilon)} \text{ is convex and increasing. By Doob's inequality applied to} \\ & \text{the submartingale } \Psi^{1/(1+\varepsilon)}(|\mathbf{M}_{S}|) \text{ , } \mathbb{E}\sup_{s\leq 1}\Psi(|\mathbf{M}_{S}|) < \infty \text{ since } \mathbb{E}\Psi(|\mathbf{M}_{1}|) < \infty \text{ .} \\ & \text{Then by Burkholder's inequality, } \mathbb{E}\Psi(\mathbf{W}^{1/2}) < \infty \text{ .} \end{split}$$

If Y_t is a d-dimensional Brownian motion, $d \ge 2$, it is known that there are measures μ for which one cannot find a stopping time T with μ the law of Y_T : just take μ atomic and recall that d-dimensional Brownian motion does not hit points. However, one can always find $f: \mathbb{R} \rightarrow \mathbb{R}^d$ such that the law of $f(X_1)$ is μ , X_t a l-dimensional Brownian motion. (The coordinate functions of f are not assumed to be nondecreasing.) One can then use lemma 1 to find a vector-valued function $A:[0,1) \times \mathbb{R} \rightarrow \mathbb{R}^d$ such that $f(X_1) = Ef(X_1) + \int_0^1 A(s, X_s) dX_s$.

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