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# On Tartar's conjecture 

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Abstract. - We prove that the only probability measures supported at connected subsets of $2 \times 2$ matrices without rank-one connections and commuting with the determinant are Dirac masses. We also prove some regularity results for fully nonlinear $2 \times 2$ elliptic systems of the first order.

Key words : Young measures, compactness, regularity.
Résume. - Soit K un sous-ensemble connexe de matrices deux par deux sans connexion de rang un et soit $v$ une mesure de probabilité concentrée sur K qui commute avec le déterminant. On démontre que $v$ est une masse de Dirac. On démontre aussi quelques résultats de régularité pour des systèmes elliptiques deux par deux du premier ordre.

## 1. INTRODUCTION

Let $\boldsymbol{\Omega} \subset \mathbf{R}^{2}$ be open an bounded. For functions $v: \Omega \rightarrow \mathbf{R}^{2}$ we consider nonlinear systems given by $\mathrm{D} v(x) \in \mathrm{K}$, where K is a submanifold of the
set $M^{2 \times 2}$ of all $2 \times 2$ matrices. We shall be interested in regularity of solutions of these systems and also in the following question: if $v_{j}: \Omega \rightarrow \mathbf{R}^{\mathbf{2}}$ is a sequence of functions such that $\left|\mathrm{D} v_{j}\right| \leqq c$ and $\operatorname{dist}\left(\mathrm{D} v_{j}(), \mathrm{K}.\right) \rightarrow 0$ in $\mathrm{L}^{p}$, what can be said about compactness of the sequence $\mathrm{D} v_{j}$ in $\mathrm{L}^{p}$ ? Since for every $A, B \in M^{2 \times 2}$ with rank $(A-B)=1$ we can construct a sequence of piecewise linear functions whose gradients oscillate between A and B , a necessary condition to get some positive results is that $\operatorname{rank}(A-B) \geqq 2$ for any two distinct matrices $A, B \in K$. Tartar's conjecture (see [14]) in our special situation says that this condition should be also sufficient for the compactness of the sequences above. Here we prove that this holds true under the additional assumption that K is connected. (Without additional assumptions the conjecture fails. For a counterexample with K consisting of four matrices see [7]. Counterexamples in higher dimensions can be found in [2].) We also give a simple proof of the fact that if $K$ is connected, rank $(A-B) \geqq 2$ for each $A, B \in K$ distinct, and the system $\mathrm{D} v(x) \in K$ is elliptic (i.e. planes tangent to K do not contain rank-one directions), then the solutions which are Lipschitzian belong to $\mathrm{C}^{1, \alpha}$ for some $\alpha>0$. If, moreover, K is smooth, then the solutions are smooth. A priori estimates for the $\mathrm{C}^{1, \alpha}$-norm of twice differentiable solutions of the systems considered here are well-known. (See, for example, [8], Chapter 12.) I am not aware of any previous regularity results for Lipschitzian solutions, with the exception of the Monge-Ampère equation, which, of course, can be considered as a first-order elliptic system. In general, if K is two dimensional and is contained in symmetric matrices, then the equation $\mathrm{D} v(x) \in \mathrm{K}$ can be viewed as a fully nonlinear scalar equation of the second order for the potential of the vector field v. A priori estimates for solutions of such equations in arbitrary dimensions have been obtained in [5]. See also [8], Chapter 17.

## 2. PRELIMINARIES

Throughout this paper $\Omega$ denotes a nonempty, bounded, open subset of $\mathbf{R}^{2}$. The Lebesgue spaces $\mathrm{L}^{p}$, the Sobolev spaces $\mathrm{W}^{k, p}$ and the spaces $C^{k, \alpha}$ of Hölder continuous functions are defined in the usual way.

Let us briefly recall basic facts concerning Young measures. (We refer the reader to [1] or [14] for more details.) Let $z_{j}: \Omega \rightarrow \mathbf{R}^{n}$ be a sequence of functions bounded in $\mathrm{L}^{\infty}(\Omega)$. It is possible to prove that there exists a subsequence $z_{\mu}$ of $z_{j}$ such that for any continuous function $f: \mathbf{R}^{n} \rightarrow \mathbf{R}$ the sequence $f^{\circ} z_{\mu}$ converges weakly* in $\mathrm{L}^{\infty}(\Omega)$ to some function $h_{f}$. Moreover, it is also possible to prove that there is a subset S of $\Omega$ of measure zero and a family $\left\{v_{x}, x \in \Omega \backslash S\right\}$ of probability measures on $\mathbf{R}^{n}$ such that for
each continuous $f: \mathbf{R}^{n} \rightarrow \mathbf{R}$ we have $h_{f}(x)=\int_{\mathbf{R}^{n}} f(\lambda) d v_{x}(\lambda)$ for almost every $x \in \boldsymbol{\Omega}$. We shall use the notation $\int_{\mathbf{R}^{n}} f(\lambda) d v_{x}(\lambda)=\left\langle v_{x}, f\right\rangle$. If almost all of the measures $v_{x}$ are Dirac masses, then the sequence $z_{\mu}$ is compact in $L^{r}(\Omega)$ for any $r<\infty$ and vice versa. The measures $v_{x}$ are called Young measures.

We shall use the following lemma.

Lemma 1. - Let K be a connected topological space and let $g: \mathrm{K} \times \mathrm{K} \rightarrow \mathbf{R}$ be a continuous function such that $g(x, y)=g(y, x) \neq 0$ for every $x, y \in \mathrm{~K}$, $x \neq y$ and $g(x, x)=0$ for every $x \in \mathrm{~K}$. Then either $g(x, y) \geqq 0$ for every $x, y \in \mathrm{~K}$ or $g(x, y) \leqq 0$ for every $x, y \in \mathrm{~K}$.

Proof. - We notice that if $g$ changes sign on $\mathrm{K} \times \mathrm{K}$, then there exists $y \in \mathrm{~K}$ such that $g(\cdot, y)$ changes sign on K . Indeed, supposing this is not the case, we consider the sets $\mathrm{K}^{+}=\{y \in \mathrm{~K}, g(\cdot, y) \geqq 0$ on K$\}$ and $\mathrm{K}^{-}=\{y \in \mathrm{~K}, g(\cdot, y) \leqq 0$ on K$\}$. These sets are clearly closed and $\mathrm{K}^{+} \cap \mathrm{K}^{-}=\varnothing$. Since K is connected, we cannot have $\mathrm{K}^{+} \cup \mathrm{K}^{-}=\mathrm{K}$. Therefore the lemma will be proved if we show that under our assumptions the function $g(\cdot, y)$ does not change sign for any $y \in K$. Suppose this is not true and let $y_{0} \in \mathrm{~K}$ be such that $g\left(\cdot, y_{0}\right)$ changes sign. Let $\mathbf{K}_{+}=\left\{x \in \mathrm{~K}, g\left(x, y_{0}\right) \geqq 0\right\}$ and $\mathrm{K}_{-}=\left\{x \in \mathrm{~K}, g\left(x, y_{0}\right) \leqq 0\right\}$. We claim that $\mathrm{K}_{+}$and $\mathrm{K}_{-}$are connected. To see this, suppose that $\mathrm{K}_{+}=\mathbf{U} \cup \mathbf{V}$, where $\mathrm{U}, \mathrm{V}$ are nonempty disjoint closed subsets of $\mathrm{K}_{+}$. We can suppose $y_{0} \notin \mathrm{~V}$. We now consider the sets $\tilde{\mathrm{U}}=\mathrm{K}_{-} \cup \mathrm{U}$ and $\tilde{\mathrm{V}}=\mathrm{V}$. These are closed sets covering K , i.e. $\tilde{\mathrm{U}} \cup \tilde{\mathrm{V}}=\mathrm{K}$. We have

$$
\tilde{\mathrm{U}} \cap \tilde{\mathrm{~V}}=\left(\mathrm{K}_{-} \cap \mathrm{V}\right) \cup(\mathrm{U} \cap \mathrm{~V}) \subset\left(\mathrm{K}_{-} \cap \mathrm{K}_{+}\right) \backslash\left\{y_{0}\right\} .
$$

Since $g$ does not vanish outside the diagonal, the last set is empty. Since $K$ is connected and $\tilde{\mathrm{U}}$ is nonempty, the set $\mathrm{V}=\tilde{\mathrm{V}}$ must be empty. This shows that $\mathbf{K}_{+}$is connected. The proof for $\mathbf{K}_{-}$is the same. Let $x_{+} \in \mathbf{K}_{+} \backslash\left\{y_{0}\right\}$ and $x_{-} \in \mathrm{K}_{-} \backslash\left\{y_{0}\right\}$. The function $g\left(x_{+},.\right)$is positive at $y_{0}$ and does not vanish on the connected set $\mathrm{K}_{-}$containing $y_{0}$. Therefore it is positive on $\mathrm{K}_{-}$and in particular $g\left(x_{+}, x_{-}\right)>0$. On the other hand, the function $g\left(x_{-}, \cdot\right)$ is negative at $y_{0}$ and does not vanish on the connected set $K_{+}$ containing $y_{0}$ and therefore $g\left(x_{-}, x_{+}\right)=g\left(x_{+}, x_{-}\right)<0$, a contradiction. The proof is finished.

## 3. COMPACTNESS

Lemma 2. - Let K be a connected subset of $\mathrm{M}^{2 \times 2}$ and suppose that $\operatorname{rank}(\mathrm{X}-\mathrm{Y}) \geqq 2$ for every two distinct matrices $\mathrm{X}, \mathrm{Y} \in \mathrm{K}$. Then either $\operatorname{det}(\mathrm{X}-\mathrm{Y}) \geqq 0$ for all $\mathrm{X}, \mathrm{Y} \in \mathrm{K}$ or $\operatorname{det}(\mathrm{X}-\mathrm{Y}) \leqq 0$ for all $\mathrm{X}, \mathrm{Y} \in \mathrm{K}$.

Proof. - This is an obvious consequence of Lemma 1.
Lemma 3. - Let K be a bounded Borel measurable subset of $\mathrm{M}^{2 \times 2}$ such that $\operatorname{rank}(\mathrm{X}-\mathrm{Y}) \geqq 2$ for any two distinct $\mathrm{X}, \mathrm{Y} \in \mathrm{K}$ and suppose that $\operatorname{det}(\mathrm{X}-\mathrm{Y})$ does not change sign on $\mathrm{K} \times \mathrm{K}$. Let $v$ be a probability measure on $\mathrm{M}^{2 \times 2}$ carried by K (i.e. $\mathrm{v}\left(\mathrm{M}^{2 \times 2} \backslash \mathrm{~K}\right)=0$ ) and satisfying $\langle v, \operatorname{det}\rangle=\operatorname{det}\langle v$, identity $\rangle$. Then $v$ is a Dirac mass, i. e. $v=\delta_{\mathrm{A}}$ for some $A \in K$.

Proof. - Let $\mathrm{A}=\langle v$, identity $\rangle$ be the centre of mass of $v$. Let $b$ be the symmetric bilinear form on $\mathrm{M}^{2 \times 2}$ determined by det $\mathrm{X}=\frac{1}{2} b(\mathbf{X}, \mathrm{X})$. We can write

$$
\begin{aligned}
& \int_{\mathrm{M}^{2 \times 2}} d v(\mathrm{X}) \int_{\mathrm{M}^{2 \times 2}} d v(\mathrm{Y}) \operatorname{det}(\mathrm{X}-\mathrm{Y}) \\
& \quad=\int_{\mathrm{M}^{2 \times 2}} d v(\mathrm{X}) \int_{\mathrm{M}^{2 \times 2}} d v(\mathrm{Y})(\operatorname{det} \mathrm{X}+\operatorname{det} \mathrm{Y}-b(\mathrm{X}, \mathrm{Y})) \\
& \quad=\int_{\mathrm{M}^{2 \times 2}} d v(\mathrm{X})(\operatorname{det} \mathrm{X}+\operatorname{det} \mathrm{A}-b(\mathrm{X}, \mathrm{~A})) \\
& \quad=\operatorname{det} \mathrm{A}+\operatorname{det} \mathrm{A}-b(\mathrm{~A}, \mathrm{~A})=0
\end{aligned}
$$

Since $\operatorname{det}(\mathbf{X}-\mathrm{Y})$ does not change sign and vanishes only at the diagonal of $K \times K$, we see that the measure $v \otimes v$ is supported at the diagonal of $\mathrm{K} \times \mathrm{K}$ and therefore it must be a Dirac mass. The proof is finished.

Theorem 1. - Let $\mathrm{U}^{(j)}=\left(\begin{array}{cc}u_{1}^{(j)} & u_{2}^{(j)} \\ v_{1}^{(j)} & v_{2}^{(j)}\end{array}\right)$ be a uniformly bounded sequence of matrix-valued functions on $\Omega$ and suppose that the sequences curl $u^{(j)}$ and curl $v^{(j)}$ are compact in $\mathrm{H}^{-1}(\Omega)$. Let K be a closed connected subset of $\mathrm{M}^{2 \times 2}$ such that $\mathrm{rank}(\mathrm{X}-\mathrm{Y}) \geqq 2$ for any two distinct $\mathrm{X}, \mathrm{Y} \in \mathrm{K}$ and suppose that $\operatorname{dist}\left(\mathrm{U}^{(j)}(x), \mathrm{K}\right) \rightarrow 0$ for a. e. $x \in \Omega$. Then the sequence $\mathrm{U}^{(j)}$ is compact in $\mathrm{L}^{p}(\Omega)$ for every $1 \leqq p<\infty$.

Proof. - Following L. Tartar [14] we consider a family of Young measures $v_{x}$ associated to a subsequence of the sequence $\mathrm{U}^{(j)}$ we and use the div-curl lemma (see [14]) to infer that $\left\langle v_{x}\right.$, $\left.\operatorname{det}\right\rangle=\operatorname{det}\left\langle v_{x}\right.$, identity $\rangle$ for almost every $x \in \Omega$. Our assumptions clearly imply that $v_{x}$ is supported
on a bounded subset of K for a.e. $\boldsymbol{x} \in \boldsymbol{\Omega}$. From Lemma 2 and Lemma 3 we see that $v_{x}$ is a Dirac mass for almost every $x \in \Omega$. The proof is finished.

## 4. RANK-ONE CONNECTIONS IN SETS OF GRADIENTS

The results of Section 3 can be used to generalize some results of [2], Section 5.

Theorem 2. - Let u: $\boldsymbol{\Omega} \rightarrow \mathbf{R}^{2}$ be a Lipschitzian function which coincides with an affine function A at the boundary of $\Omega$ and suppose that $\mathrm{D} u$ is continuous in $\Omega$. If $u$ is not affine, then there exist $x, y \in \Omega$ such that $\operatorname{rank}(\mathrm{D} u(x)-\mathrm{D} u(y))=1$.

Proof. - Let us first assume that $\Omega$ is connected and $\mathrm{A}=0$. Let $\mathrm{K}=\{\mathrm{D} u(x), x \in \Omega\}$ and let $v$ be the probability measure on $\mathrm{M}^{2 \times 2}$ given by

$$
\langle v, f\rangle=\frac{1}{\operatorname{meas} \Omega} \int_{\Omega} f(\mathrm{D} u(x)) d x
$$

for every continuous function $f: \mathbf{M}^{2 \times 2} \rightarrow \mathbf{R}$. Under our assumptions the set $K$ is bounded and connected. The measure $v$ is carried by $K$. We claim that $\langle v, \operatorname{det}\rangle=\operatorname{det}\langle v$, identity $\rangle$. For this it is enough to prove that under our assumptions we have $\int_{\Omega} \mathrm{D} u(x) d x=0$ and $\int_{\Omega} \operatorname{det} \mathrm{D} u(x) d x=0$. This is well known if $u$ is Lipschitzian and compactly supported in $\Omega$. (See, for example, [11].) The general case can be brought to this case by extending $u$ by 0 outside $\Omega$ and integrating over a sufficiently large ball in which $\Omega$ is compactly contained. We can now apply Lemma 2 and Lemma 3 and we see that if $\mathrm{D} u$ is not constant, then there must be rank-one connections in $K$. The proof in the case when $\Omega$ is connected and $A=0$ is finished. The general case follows easily, since clearly $u=\mathrm{A}$ on the boundary of every connected component of $\Omega$ and since we can replace $u$ by $u-\mathrm{A}$, if necessary.

Remarks. - 1. For any open set $\Omega \subset \mathbf{R}^{2}$ it is possible to construct a Lipschitzian function $u: \Omega \rightarrow \mathbf{R}^{2}$ vanishing at the boundary of $\Omega$ and a bounded countable set $S \subset M^{2 \times 2}$ such that there are no rank-one connections in the closure K of $\mathrm{S}, 0 \notin \mathrm{~K}$, and $\mathrm{D} u \in \mathrm{~S}$ a.e. in $\Omega$. See [13].
2. For examples showing that Theorem 2 fails in higher dimensions (except, perhaps, for mappings from $\Omega \subset \mathbf{R}^{2}$ to $\mathbf{R}^{3}$ ) see [2].

## 5. REGULARITY

Theorem 3. - Let K be a bounded subset of $\mathrm{M}^{2 \times 2}$ and suppose that there is $\lambda>0$ such that either $\operatorname{det}(\mathrm{X}-\mathrm{Y}) \geqq \lambda|\mathrm{X}-\mathrm{Y}|^{2}$ for each $\mathrm{X}, \mathrm{Y} \in \mathrm{K}$ or $\operatorname{det}(\mathrm{X}-\mathrm{Y}) \leqq-\lambda|\mathrm{X}-\mathrm{Y}|^{2}$ for each $\mathrm{X}, \mathrm{Y} \in \mathrm{K}$. Let $v: \Omega \rightarrow \mathbf{R}^{2}$ be a Lipschitzian function satisfying $\mathrm{D} v(x) \in \mathrm{K}$ for almost every $x \in \mathrm{~K}$. Then there is $p>2$ such that $v$ belongs to $\mathrm{W}_{\mathrm{loc}}^{2, p}(\Omega)$. In particular, the gradient $\mathrm{D} v$ of $v$ is Hölder continuous.

Proof. - We will consider only the case $\operatorname{det}(\mathrm{X}-\mathrm{Y}) \geqq \lambda|\mathrm{X}-\mathrm{Y}|^{2}$. For the proof in the case $\operatorname{det}(\mathrm{X}-\mathrm{Y}) \leqq-\lambda|\mathrm{X}-\mathrm{Y}|^{2}$ it is enough to replace det by - det in the formulae below. Let $a \in \mathbf{R}^{2}$ and for $h>0$ let $v_{h}(x)=(v(x+h a)-v(x)) / h$. (We can extend $v$ by zero outside $\Omega$, for example.) Let $\eta$ be a smooth nonnegative function compactly supported in $\Omega$. Let $b \in \mathbf{R}^{2}$. For sufficienly small $h$ we have

$$
\begin{aligned}
0 & =\int_{\Omega} \operatorname{det} \mathrm{D}\left(\eta\left(v_{h}-b\right)\right) d x \\
& \geqq \int_{\Omega}\left(-\eta\left|\mathrm{D} v_{h}\|\mathrm{D} \eta\| v_{h}-b\right|+\eta^{2} \operatorname{det} \mathrm{D} v_{h}\right) d x \\
& \geqq \int_{\Omega}\left(-\eta\left|\mathrm{D} v_{h}\right|\left|\mathrm{D} \eta \| v_{h}-b\right|+\lambda \eta^{2}\left|\mathrm{D} v_{h}\right|^{2}\right) d x \\
& \geqq-\frac{1}{2 \lambda} \int_{\Omega}|\mathrm{D} \eta|^{2}\left|v_{h}-b\right|^{2} d x+\frac{\lambda}{2} \int_{\Omega} \eta^{2}\left|\mathrm{D} v_{h}\right|^{2} d x
\end{aligned}
$$

We see that the $\mathrm{L}^{2}$-norm of $\mathrm{D} v_{h}$ on compact subsets of $\Omega$ is estimated by the $L^{2}$-norm of $v_{h}$. We can now use the well-known Nirenberg's Lemma to infer that $\mathrm{D} v \in \mathrm{~W}_{\text {loc }}^{1,2}(\Omega)$. It is well-known that if there exists $\mathrm{C}>0$ such that

$$
\int_{\Omega} \eta^{2}\left|\mathrm{D} v_{h}\right|^{2} d x \leqq \mathrm{C} \int_{\Omega}|\mathrm{D} \eta|^{2}\left|v_{h}-b\right|^{2} d x
$$

for every $\eta$ as above and every $b \in \mathbf{R}^{2}$, or in another words, if $v_{h}$ satisfies the Caccioppoli's inequality, then there exists a $p>2$ such that the $\mathrm{L}^{p}$-norm of $\mathrm{D} v_{h}$ on every set $\widetilde{\Omega}$ compactly contained in $\Omega$ is bounded by $\mathrm{C}_{1}\left\|v_{h}\right\|_{\mathrm{L}^{2}(\Omega)}$, where $\mathrm{C}_{1}$ depends only on $\mathrm{C}, p, \widetilde{\Omega}$ and $\Omega$. (For a proof of this which is based on the technique of reverse Hölder inequalities see [6].) Using Nirenberg's Lemma again, we see that $\mathrm{D} v$ is bounded in $\mathrm{W}_{\text {loc }}^{1, p}(\Omega)$. The Hölder continuity of $\mathrm{D} v$ follows from the Sobolev Imbedding Theorem. The proof is finished.

Corollary. - Let K be a closed connected smooth submanifold of $\mathrm{M}^{2 \times 2}$ such that $\operatorname{rank}(\mathrm{X}-\mathrm{Y}) \geqq 2$ for any two distinct $\mathrm{X}, \mathrm{Y} \in \mathrm{K}$. Suppose moreover
that K is "elliptic", or in other words, that for any $\mathrm{X} \in \mathrm{K}$ the tangent space to K passing through X does not contain rank-one directions. Then every Lipschitz function $v: \Omega \rightarrow \mathbf{R}^{2}$ satisfying $\mathrm{D} v(x) \in \mathrm{K}$ for a. e. $x \in \mathrm{~K}$ is smooth.

Proof. - We notice that the ellipticity condition together with Lemma 1 implies that for each bounded subset $K_{1}$ of $K$ there exists $\lambda>0$ such that either

$$
\operatorname{det}(X-Y) \geqq \lambda|X-Y|^{2} \quad \text { for every } \quad X, Y \in K_{1}
$$

or

$$
\operatorname{det}(X-Y) \leqq-\lambda|X-Y|^{2} \quad \text { for every } \quad X, Y \in K_{1}
$$

We can use Theorem 2 to infer that $\mathrm{D} v$ is Hölder continuous and that $v$ belongs to the space $\mathrm{W}_{\mathrm{loc}}^{2,2}(\Omega)$. Since $\mathrm{D} v(x) \in \mathrm{K}$ in $\Omega$, the derivatives $\frac{\partial}{\partial x_{i}} \mathrm{D} v(x)$ belong to the tangent space of K at $\mathrm{D} v(x)$ for a.e. $x \in \Omega$. Since $\mathrm{D} v$ is Hölder continuous and K is elliptic, we see that $\frac{\partial}{\partial x_{i}} v(x)$ can be viewed as solutions of a certain linear first order elliptic system with Hölder continuous coefficients. Therefore $\mathrm{D}^{2} v$ is Hölder continuous. (See, for example, [11].) Applying the usual procedure of improving regularity we see that $v$ must be smooth. The proof is finished.

## 6. EXAMPLES

Classical examples of K's which are elliptic in the above sense are

$$
\mathbf{K}_{0}=\left\{\mathbf{X} \in \mathbf{M}^{2 \times 2}, \mathbf{X} \text { is symmetric and Trace } \mathbf{X}=0\right\}
$$

and

$$
K_{1}=\left\{X \in M^{2 \times 2}, X \text { is symmetric, positive definite, and } \operatorname{det} X=1\right\} .
$$

Clearly $\mathrm{K}_{0}$ can be viewed as the tangent space to $\mathrm{K}_{1}$ at the unit matrix.
The following examples arise in connection with problems concerning invariant "wells" which appear in the theory of microstructures. (See, for example, [3], [4], [9], and [10] for motivation). Let $A_{1}, \ldots, A_{m} \in M^{2 \times 2}$ with $\operatorname{det} \mathrm{A}_{k}>0$ for each $k=1, \ldots, m$ and let

$$
\mathrm{K}_{w}=\mathrm{SO}(2) \cdot \mathrm{A}_{1} \cup \ldots \cup \mathrm{SO}(2) \cdot \mathrm{A}_{m} .
$$

It is easy to check that if $\mathrm{K}_{w}$ does not contain rank-one connections (i.e. rank $(X-Y) \geqq 2$ for any two distinct $\left.X, Y \in K_{w}\right)$, then there exists $v>0$ such that $\operatorname{det}(\mathbf{X}-\mathrm{Y}) \geqq v|\mathrm{X}-\mathrm{Y}|^{2}$ for each $\mathrm{X}, \mathrm{Y} \in \mathrm{K}_{w}$. We see that in this case Lemma 3 and Theorem 3 can be applied to $K_{w}$. This shows, for example, that if $K_{w}$ does not contain rank-one connections, then the deformations $\varphi: \Omega \rightarrow \mathbf{R}^{2}$ satisfying $\mathrm{D} \varphi \in \mathrm{K}_{w}$ a.e. in $\Omega$ belong to $\mathrm{C}_{\mathrm{loc} .}^{1, \alpha}(\Omega)$
for some $\alpha>0$. Using this it is not difficult to see that if $K_{w}$ does not contain rank-one connections, then $\mathrm{D} \varphi \in \mathrm{K}_{w}$ a.e. in $\Omega$ implies that in fact $\mathrm{D} \varphi$ is locally constant in $\Omega$.

We can also consider continuous families of invariant wells. A simple example is the following: let $\mu:[0,1] \rightarrow \mathbf{R}$ and $\lambda:[0,1] \rightarrow \mathbf{R}$ be smooth strictly positive functions with $\mu^{\prime}(t)>0$ and $\lambda^{\prime}(t)>0$ for all $t \in[0,1]$ and let $K_{c}=\underset{t \in[0,1]}{\cup} \operatorname{SO}(2) \cdot\left(\begin{array}{cc}\lambda(t) & 0 \\ 0 & \mu(t)\end{array}\right)$. It is easy to check that $K_{c}$ satisfies the assumptions of Theorem 1 and Theorem 3.

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