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2-FRIEZE PATTERNS AND THE CLUSTER STRUCTURE OF THE SPACE OF POLYGONS

by Sophie MORIER-GENOUD, Valentin OVSIENKO & Serge TABACHNIKOV

ABSTRACT. — We study 2-frieze patterns generalizing that of the classical Coxeter-Conway frieze patterns. The geometric realization of this space is the space of *n*-gons (in the projective plane and in 3-dimensional vector space) which is a close relative of the moduli space of genus 0 curves with *n* marked points. We show that the space of 2-frieze patterns is a cluster manifold and study its algebraic and arithmetic properties.

RÉSUMÉ. — Nous étudions une variante des frises de Coxeter-Conway appelée 2-frises. La réalisation géométrique de l'espace des 2-frises est l'espace des modules de polygones, dans le plan projectif ou dans l'espace vectoriel de dimension 3, qui est un analogue de l'espace des modules des courbes de genre 0 avec n points marqués. Nous montrons que l'espace des 2-frises admet une structure de variété amassée et nous en étudions les propriétés algébriques et arithmétiques.

1. Introduction

The space C_n of *n*-gons in the projective plane (over \mathbb{C} or over \mathbb{R}) modulo projective equivalence is a close relative of the moduli space $\mathcal{M}_{0,n}$ of genus zero curves with *n* marked points. The space C_n was considered in [25] and in [21] as the space on which the *pentagram map* acts.

The main idea of this paper is to identify the space C_n with the space \mathcal{F}_n of combinatorial objects that we call 2-*friezes*. These objects first appeared in [23] as generalization of the Coxeter friezes [6]. We show that C_n is isomorphic to \mathcal{F}_n , provided n is not a multiple of 3. This isomorphism leads to remarkable coordinate systems on C_n and equips C_n with the structure of

Keywords: Frieze patterns, Coxeter-Conway friezes, moduli space, cluster algebra, pentagram map.

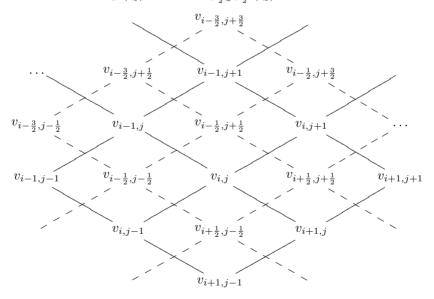
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cluster manifold. The relation between 2-friezes and cluster algebras is not surprising, since 2-friezes can be viewed as a particular case of famous recurrence relations known as the discrete Hirota equation, or the octahedron recurrence. The particular case of 2-friezes is a very interesting subject; in this paper we make first steps in the study of algebraic and combinatorial structures of the space of 2-friezes.

The pentagram map $T : \mathcal{C}_n \to \mathcal{C}_n$, see [24, 25] and also [21, 16], is a beautiful dynamical system which is a time and space discretization of the Boussinesq equation. Complete integrability of the pentagram map for a larger space of twisted *n*-gons was proved in [21]; recently, integrability of T on \mathcal{C}_n was established, by different methods, in [27] and [20]. The desire to better understand the structure of the space of closed polygons was our main motivation.

1.1. 2-friezes

We call a 2-frieze pattern a grid of numbers, or polynomials, rational functions, etc., $(v_{i,j})_{(i,j)\in\mathbb{Z}^2}$ and $(v_{i+\frac{1}{2},j+\frac{1}{2}})_{(i,j)\in\mathbb{Z}^2}$ organized as follows



such that every entry is equal to the determinant of the 2×2 -matrix formed by its four neighbours:

$$\begin{array}{c} \swarrow & B & F \\ A & E & D & H \\ & \swarrow & & \\ & & & & \\ & & & \\ & & & \\ & & & \\ & & & & \\ & & & \\ & & &$$

Generically, two consecutive rows in a 2-frieze pattern determine the whole 2-frieze pattern.

The notion of 2-frieze pattern is a variant of the classical notion of Coxeter-Conway frieze pattern [6, 5]. Similarly to the classical frieze patterns, 2-frieze patterns constitute a particular case of the 3-dimensional octahedron recurrence:

$$T_{i+1,j,k} T_{i-1,j,k} = T_{i,j+1,k} T_{i,j-1,k} - T_{i,j,k+1} T_{i,j,k-1},$$

which may be called the Dodgson condensation formula (1866) and which is also known in the mathematical physics literature as the discrete Hirota equation (1981). More precisely, assume $T_{-1,j,k} = T_{2,j,k} = 1$ and $T_{i,j,k} = 0$ for $i \leq -2$ and $i \geq 3$. Then $T_{0,j,k}$ and $T_{1,j,k}$ form a 2-frieze. More general recurrences called the *T*-systems and their relation to cluster algebras were studied recently, see [17, 8, 18] and references therein. In particular, periodicity and positivity results, typical for cluster algebras, were obtained.

The above 2-frieze rule was mentioned in [23] as a variation on the Coxeter-Conway frieze pattern. What we call a 2-frieze pattern also appeared in [2] in a form of duality on SL_3 -tilings. To the best of our knowledge, 2-frieze patterns have not been studied in detail before.

We are particularly interested in 2-frieze patterns bounded from above and from below by a row of 1's and two rows of 0's:

•••	0	0	0	0	0	• • •
•••	0	0	0	0	0	
	1	1	1	1	1	•••
• • •	$v_{0,0}$	$v_{\frac{1}{2},\frac{1}{2}}$	$v_{1,1}$	$v_{\frac{3}{2},\frac{3}{2}}$	$v_{2,2}$	
	:	:	÷	÷	÷	
• • •	1	1	1	1	1	
	0	0	0	0	0	

that we call *closed* 2-frieze patterns. We call the *width* of a closed pattern the number of rows between the two rows of 1's. In the sequel, we will often omit the rows of 0's in order to simplify the notation.

We introduce the following notation:

$$\mathcal{F}_n = \{ \text{closed 2-friezes of width } n-4 \}$$

for the space of all closed (complex or real) 2-frieze patterns. Here and below the term "space" is used to identify a set of objects that we wish to endow with a geometric structure of (algebraic, smooth or analytic) variety. We denote by $\mathcal{F}_n^0 \subset \mathcal{F}_n$ the subspace of closed friezes of width n-4 such that all their entries are *real positive*.

Along with the octahedron recurrence, the space of all 2-frieze patterns is closely related to the theory of cluster algebras and cluster manifolds [12]. In this paper, we explore this relation.

1.2. Geometric version: moduli spaces of *n*-gons

An *n*-gon in the projective plane is given by a cyclically ordered *n*-tuple of points $\{v_1, \ldots, v_n\}$ in \mathbb{P}^2 such that no three consecutive points belong to the same projective line. In particular, $v_i \neq v_{i+1}$, and $v_i \neq v_{i+2}$. However, one may have $v_i = v_j$, if $|i - j| \ge 3$. We understand the *n*-tuple $\{v_1, \ldots, v_n\}$ as an infinite cyclic sequence, that is, we assume $v_{i+n} = v_i$, for all $i = 1, \ldots, n$.

We denote the space of all *n*-gons modulo projective equivalence by C_n :

$$\mathcal{C}_n = \left\{ (v_1, \dots, v_n) \in \mathbb{P}^2 \mid \det(v_i, v_{i+1}, v_{i+2}) \neq 0, \ i = 1, \dots, n \right\} / \text{PSL}_3.$$

The space C_n is a (2n-8)-dimensional algebraic variety.

Similarly, one defines an *n*-gon in 3-dimensional vector space (over \mathbb{R} or \mathbb{C}): this is a cyclically ordered *n*-tuple of vectors $\{V_1, \ldots, V_n\}$ satisfying the unit determinant condition

$$\det(V_{i-1}, V_i, V_{i+1}) = 1$$

for all indices i (understood cyclically). The group SL₃ naturally acts on n-gons. The space of equivalence classes is denoted by $\tilde{\mathcal{C}}_n$; this is also a (2n-8)-dimensional algebraic variety.

Projectivization gives a natural map $\tilde{\mathcal{C}}_n \to \mathcal{C}_n$. It is shown in [21] that this map is bijective if n is not divisible by 3; see Section 2.3.

We show that the space of closed 2-frieze patterns \mathcal{F}_n is isomorphic to the space of polygons $\tilde{\mathcal{C}}_n$. This also means that \mathcal{F}_n is isomorphic to \mathcal{C}_n , provided *n* is not a multiple of 3.

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An *n*-gon $\{V_1, \ldots, V_n\}$ in \mathbb{R}^3 is called *convex* if, for each *i*, all the vertices $V_j, j \neq i-1, i$, lie on the positive side of the plane generated by V_{i-1} and V_i , that is, det $(V_{i-1}, V_i, V_j) > 0$. See Figure 1.1. Let $\tilde{\mathcal{C}}_n^0 \subset \tilde{\mathcal{C}}_n$ denote the space of convex *n*-gons in \mathbb{R}^3 . We show that the space of positive real 2-friezes \mathcal{F}_n^0 is isomorphic to the space of convex polygons $\tilde{\mathcal{C}}_n^0$.

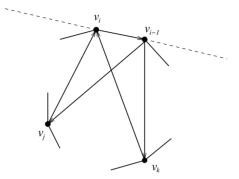


Figure 1.1. A convex polygon.

Remark 1.1. — A more general space of *twisted n*-gons in \mathbb{P}^2 (and similarly in 3-dimensional vector space) was considered in [25, 21]. A twisted *n*-gon in \mathbb{P}^2 is a map $\varphi : \mathbb{Z} \to \mathbb{P}^2$ such that no three consecutive points, $\varphi(i), \varphi(i+1), \varphi(i+2)$, belong to the same projective line and

$$\varphi(i+n) = M(\varphi(i)),$$

where $M \in PSL_3$ is a fixed element, called the *monodromy*. If the monodromy is trivial, M = Id, then the twisted *n*-gon is an *n*-gon in the above sense. In [25, 21] two different systems of coordinates were introduced and used to study the space of twisted *n*-gons and the transformation under the pentagram map.

1.3. Analytic version: the space of difference equations

Consider a difference equation of the form

(1.1)
$$V_i = a_i V_{i-1} - b_i V_{i-2} + V_{i-3},$$

where $a_i, b_i \in \mathbb{C}$ or \mathbb{R} are *n*-periodic: $a_{i+n} = a_i$ and $b_{i+n} = b_i$, for all *i*. A solution $V = (V_i)$ is a sequence of numbers $V_i \in \mathbb{C}$ or \mathbb{R} satisfying (1.1). The space of solutions of (1.1) is 3-dimensional. Choosing three independent

solutions, we can think of V_i as vectors in \mathbb{C}^3 (or \mathbb{R}^3). The *n*-periodicity of (a_i) and (b_i) then implies that there exists a matrix $M \in SL_3$ called the *monodromy matrix*, such that

$$V_{i+n} = M\left(V_i\right).$$

The space of all the equations (1.1) is nothing other than the vector space \mathbb{C}^{2n} (or \mathbb{R}^{2n} , in the real case), since (a_i, b_j) are arbitrary numbers. The space of equations with trivial monodromy, M = Id, is an algebraic manifold of dimension 2n - 8, since the condition M = Id gives eight polynomial equations (of degree n - 3).

We show that the space of closed 2-frieze patterns \mathcal{F}_n is isomorphic to the space of equations (1.1) with trivial monodromy.

1.4. The pentagram map and cluster structure

The pentagram map, T, see Figure 1.2, was initially defined by R. Schwartz [24] on the space of (convex) closed *n*-gons in \mathbb{RP}^2 . This map associates to an *n*-gon another *n*-gon formed by segments of the shortest diagonals. Since T commutes with the SL(3, \mathbb{R})-action, it is well-defined on the quotient space C_n . Complete integrability of T on C_n was conjectured and partially established in [25].

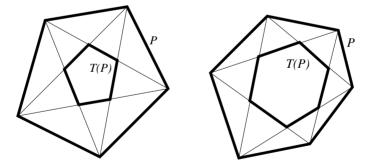


Figure 1.2. The pentagram map.

The integrability results on the pentagram map were originally established in the case of the space of twisted *n*-gons (see Remark 1.1). Complete integrability of T on this space was proved in [21] and the relation to cluster algebras was noticed. Explicit formulas for iterated pentagram map T^k were recently found [16] using an alternative system of parametrizations of the twisted *n*-gons. These formulas involve the theory of cluster algebras and *Y*-patterns. Here, we describe a structure of cluster manifold on the space of closed *n*-gons, which is a different question. The relation of our approach with the one by Glick deserves a thorough study; we plan to consider this question in near future. It is not clear, at the time of writing, how the cluster structure on the space C_n that we describe in this paper is related to complete integrability of the map T on C_n proved in [27] and [20].

2. Definitions and main results

2.1. Algebraic and numerical friezes

It is important to distinguish the *algebraic* 2-frieze patterns, where the entries are algebraic functions, and the *numerical* ones where the entries are real numbers.

Our starting point is the algebraic frieze bounded from above by a row of 1's (we also assume that there are two rows of 0's above the first row of 1's). We denote by A_i, B_i the entries in the first non-trivial row:

The entries A_i, B_i are considered as formal free variables.

PROPOSITION 2.1. — The first two non-zero rows of (2.1) uniquely define an unbounded (from below, left and right) 2-frieze pattern. Every entry of this pattern is a polynomial in A_i, B_i .

This statement will be proved in Section 3.

We denote the defined 2-frieze by $F(A_i, B_i)$.

Given a sequence of real numbers $(a_i, b_i)_{i \in \mathbb{Z}}$, we define a numerical 2frieze pattern $F(a_i, b_i)$ as the evaluation

$$F(a_i, b_i) = F(A_i, B_i) \Big|_{A_i = a_i, B_i = b_i}.$$

Note that one can often recover the whole numerical frieze $F(a_i, b_i)$ directly from the two first rows (of 1's and (a_i, b_i)) by applying the pattern rule but this is not always the case. For instance this is not the case if there are too many zeroes among $\{a_i, b_i\}$. In other words, there exist numerical friezes that are not evaluations of $F(A_i, B_i)$. Example 2.2. — The following 2-frieze pattern:

•••	1	1	1	1	1	
• • •	0	0	0	0	0	
• • •	0	0	0	0	0	
• • •	0	0	0	0	0	
•••	1	1	1	1	1	

is not an evaluation of some $F(A_i, B_i)$. Indeed, if $a_i = b_i = 0$ for all $i \in \mathbb{Z}$, then the 4-th row in $F(a_i, b_i)$ has to be a row of 1's. This follows from formula (3.2) below.

The above example is not what we called a numerical 2-frieze pattern and we will not consider such friezes in the sequel. We will restrict our considerations to evaluations of $F(A_i, B_i)$.

2.2. Closed frieze patterns

A numerical 2-frieze pattern $F(a_i, b_i)$ is closed if it contains a row of 1's followed by two rows of zeroes:

	 1	1	1	1	1	•••
	 b_i	a_i	b_{i+1}	a_{i+1}	b_{i+2}	
	÷	÷	:	:	:	
(2.2)	 1	1	1	1	1	• • •
	 0	0	0	0	0	• • •
	 0	0	0	0	0	•••
	÷	÷	÷	÷	÷	

The following statement is proved in Section 4.

PROPOSITION 2.3. — A closed 2-frieze pattern of width (n-4) has the following properties.

(i) It is 2n-periodic in each row, i.e., $v_{i+n,j+n} = v_{i,j}$, in particular $a_{i+n} = a_i$ and $b_{i+n} = b_i$.

(ii) It is n-periodic in each diagonal, i.e., $v_{i+n,j} = v_{i,j}$ and $v_{i,j+n} = v_{i,j}$. (iii) It satisfies the following additional glide symmetry: $v_{i,j} = v_{j+n-\frac{5}{2},i+\frac{5}{2}}$.

The statement of part (iii) means that, after n steps, the pattern is reversed with respect to the horizontal symmetry axis.

As a consequence of Proposition 2.3, a closed 2-frieze of width n - 4 consists of periodic blocks of size $(n - 2) \times 2n$. Taking into account the

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symmetry of part (iii), the 2-frieze is determined by a fragment of size $(n-2) \times n$.

Example 2.4. — (a) The following fragment completely determines a closed 2-frieze of width 2.

 1	1	1	1	1	1	1	1	1	1	1	1	
 1	1	4	6	2	1	2	3	2	2	4	3	
 2	3	2	2	4	3	1	1	4	6	2	1	
 1	1	1	1	1	1	1	1	1	1	1	1	

The additional symmetry from Proposition 2.3, part (iii), switches the rows every 6 steps.

(b) The following integral numerical 2-frieze pattern

 1	1	1	1	1	1	1	1	1	1	1	1	
 1	3	5	2	1	3	5	2	1	3	5	2	
 5	2	1	3	5	2	1	3	5	2	1	3	· · · · · · ·
 1	1	1	1	1	1	1	1	1	1	1	1	

is closed of width 2. This corresponds to n = 6 so that this 2-frieze pattern is understood as 12-periodic (and not as 4-periodic!).

2.3. Closed 2-friezes, difference equations and *n*-gons

Consider an arbitrary numerical 2-frieze pattern $F(a_i, b_i)$. By Proposition 2.3, a necessary condition of closeness is:

$$a_{i+n} = a_i, \qquad b_{i+n} = b_i$$

that we assume from now on. We then say that $F(a_i, b_i)$ is 2*n*-periodic.

Associate to $F(a_i, b_i)$ the difference equation (1.1). The first main result of this paper is the following criterion of closeness. The statement is very similar to a result of [5].

THEOREM 2.5. — A 2n-periodic 2-frieze pattern $F(a_i, b_i)$ is closed if and only if the monodromy of the corresponding difference equation (1.1) is trivial: M = Id.

This theorem will be proved in Section 4.

The variety \mathcal{F}_n of closed 2-frieze patterns (2.2) is thus identified with the space of difference equations (1.1) with trivial monodromy. The latter space was considered in [21]. In particular, the following geometric realization holds.

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PROPOSITION 2.6. — [21] The space of difference equations (1.1) with trivial monodromy is isomorphic to the space of SL₃-equivalence classes of polygons \tilde{C}_n in 3-space. If n is not divisible by 3, then this space is also isomorphic to the space C_n of projective equivalence classes of polygons in the projective plane.

For completeness, we give a proof in Section 4.

It follows from Theorem 2.5 that the variety \mathcal{F}_n is isomorphic to $\tilde{\mathcal{C}}_n$, and also to \mathcal{C}_n , provided *n* is not a multiple of 3. In order to illustrate the usefullness of this isomorphism, in Section 4.5, we prove the following statement.

PROPOSITION 2.7. — All the entries of a real 2-frieze pattern are positive if and only if the corresponding n-gon in \mathbb{R}^3 is convex.

We understand convex *n*-gons in \mathbb{RP}^2 as polygons that lie in an affine chart and are convex therein. If *n* is not a multiple of 3, then convexity of an *n*-gon in \mathbb{R}^3 is equivalent to convexity of its projection to \mathbb{RP}^2 , see Section 4.5. In Section 4.6, we show that the space of convex 3m-gons is isomorphic to the space of pairs of 2m-gons inscribed one into the other. This space was studied by Fock and Goncharov [11, 10].

2.4. Cluster structure

The theory of cluster algebras introduced and developed by Fomin and Zelevinsky [12]-[14] is a powerful tool for the study of many classes of algebraic varieties. This technique is crucial for the present paper. Note that the relation of octahedron recurrence and T-systems to cluster algebras is well-known, see, e.g., [30, 7, 9, 8, 18]. Some of our statements are very particular cases of known results and are given here in a more elementary way for the sake of completeness.

It was first proved in [3] that the space of the classical Coxeter-Conway friezes has a cluster structure related to the simplest Dynkin quiver A_n (see also Appendix). In Section 5, we prove a similar result.

Consider the following oriented graph (or quiver) that we denote by Q: (2.3)



if n is even, or with the opposite orientation of the last square if n is odd (note that in the case n = 5 the graph consists only in two vertices linked by one arrow). The graph Q is the product of two Dynkin quivers: $Q = A_2 * A_{n-4}$.

Example 2.8. — The graph (2.3) is a particular case of the graphs related to the cluster structure on Grassmannians, see [26]. The cluster algebra considered in Section 5 can be viewed as a specialization of the one considered by Scott. In particular, for n = 5, this is nothing else but the simplest Dynkin graph A_2 . For n = 6, 7, 8, the graph Q is equivalent (by a series of mutations) to D_4, E_6, E_8 , respectively. The graph Q is of infinite type for $n \ge 9$. For n = 9, the graph Q is equivalent to the infinite-type graph $E_8^{1,1}$. The relation of our approach with the one by Scott deserves a thorough study.

The cluster algebra associated to Q is of infinite type for $n \ge 9$. In Section 5.3, we define a finite subset Z in the set of all clusters associated to Q. More precisely, the subset Z is the set of all clusters that can be obtained from the initial cluster by series of mutations at vertices that do not belong to two 3-cycles.

Theorem 2.9.

(i) The cluster coordinates $(x_1, \ldots, x_{n-4}, y_1, \ldots, y_{n-4})_{\zeta}$, where $\zeta \in \mathbb{Z}$, define a biregular isomorphism between $(\mathbb{C}^*)^{2n-8}$ and a Zariski open subset of \mathcal{F}_n .

(ii) The coordinates $(x_1, \ldots, x_{n-4}, y_1, \ldots, y_{n-4})_{\zeta}$ restrict to a bijection between $\mathbb{R}^{2n-8}_{>0}$ and \mathcal{F}^0_n .

Theorem 2.9 provides good coordinate systems for the study of the space C_n , different from the known coordinate systems described in [25, 21].

We think that the "restricted" set of cluster coordinates \mathcal{Z} is an interesting object that perhaps has a more general meaning, this question remains open. In Section 5.4, we define the so-called smooth cluster-type manifold corresponding to the subset \mathcal{Z} . The space of all 2-friezes \mathcal{F}_n is precisely this manifold completed by some singular points.

The following proposition is a typical statement that can be obtained using the cluster structure. A double zig-zag is a choice of two adjacent entries in each row of a pattern so that the pair of entries in each next row is directly underneath the pair above it, or is offset of either one position right or left, see Section 5.3 below for details. PROPOSITION 2.10. — Every frame bounded from the left by a double zig-zag of 1's:

can be completed (in a unique way) to a closed 2-frieze pattern with positive integer entries.

This statement will be proved in Section 5.3. This is a direct generalization of a Coxeter-Conway result [5].

2.5. Arithmetic 2-friezes

Let us consider closed 2-frieze patterns of period 2n consisting of positive integers (like in Example 2.4); we call such 2-friezes *arithmetic*. The classification of such patterns is a fascinating problem formulated in [23]. This problem remains open.

In Section 6, we present an inductive method of constructing a large number of arithmetic 2-frieze patterns. This is a step towards the classification.

Consider two closed arithmetic 2-frieze patterns, $F(a_i, b_i)$ and $F(a'_i, b'_i)$, one of them of period 2n and the other one of period 2k, with coefficients

$$b_1, a_1, b_2, a_2, \ldots, b_n, a_n = b'_1, a'_1, b'_2, a'_2, \ldots, b'_k, a'_k,$$

respectively. We call the *connected summation* the following way to glue them together and obtain a 2-frieze pattern of period 2(n + k - 3).

- (1) Cut the first one at an arbitrary place, say between b_2 and a_2 .
- (2) Insert 2(k-3) integers: $a'_2, b'_3, \ldots, a'_{k-2}, b'_{k-1}$.
- (3) Replace the three left and the three right neighbouring entries by:

(2.4)

leaving the other 2(n-3) entries $b_4, a_4, \ldots, b_n, a_n$ unchanged.

In Section 6, we will prove the following statement.

THEOREM 2.11. — Connected summation yields a closed 2-frieze pattern of period 2(n + k - 3). If $F(a_i, b_i)$ and $F(a'_i, b'_i)$ are closed arithmetic 2-frieze patterns, then their connected sum is also a closed arithmetic 2frieze pattern.

In Sections 6.3 and 6.4, we explain the details in the first non-trivial cases: k = 4 and 5, that we call "stabilization".

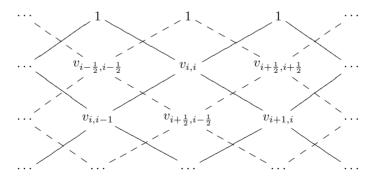
The classical Coxeter-Conway integral frieze patterns were classified in [5] with the help of a similar stabilization procedure. In particular, a beautiful relation with triangulations of an *n*-gon (and thus with the Catalan numbers) was found making the result more attractive. Unfortunately, the above procedure of connected summation does not lead to classification of arithmetic 2-frieze patterns. This is due to the fact that, unlike the Coxeter-Conway integral frieze patterns, not every integral 2-frieze pattern is a connected sum of smaller ones, see examples below.

3. Algebraic 2-friezes

The goal of this section, is to describe various ways to calculate the frieze (2.1). This will imply Proposition 2.1.

3.1. The pattern rule

Recall that we denote by $(v_{i,j})_{(i,j)\in\mathbb{Z}^2}$ and $(v_{i+\frac{1}{2},j+\frac{1}{2}})_{(i,j)\in\mathbb{Z}^2}$ the entries of the frieze organized as follows



In the algebraic frieze, we assume:

$$v_{i,i} = A_i$$
 $v_{i-\frac{1}{2},i-\frac{1}{2}} = B_i$

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see (2.1).

The first way to calculate the entries in the frieze (2.1) is a direct inductive application of the pattern rule.

3.2. The determinant formula

The most general formula for the elements of the pattern is the following determinant formula generalizing that of Coxeter-Conway [5].

$$(3.1) v_{i,j} = \begin{vmatrix} A_j & B_{j+1} & 1 \\ 1 & A_{j+1} & B_{j+2} & 1 \\ & \ddots & \ddots & \ddots \\ & & 1 & A_{i-2} & B_{i-1} & 1 \\ & & & 1 & A_{i-1} & B_i \\ & & & & 1 & A_i \end{vmatrix}$$

for $i \ge j \in \mathbb{Z}$. The element $v_{i+\frac{1}{2},j+\frac{1}{2}}$ is obtained from $v_{i,j}$ by replacing $(A_k, B_{k+1}) \to (B_{k+1}, A_{k+1})$.

Proof. — The 2-frieze pattern rule for $v_{i-1/2,j+1/2}$ reads

$$v_{i-1,j} v_{i,j+1} = v_{i-1,j+1} v_{i,j} + v_{i-\frac{1}{2},j+\frac{1}{2}}.$$

Using induction on i - j, understood as the row number, we assume that the formula for $v_{k,\ell}$ holds for $k - \ell < i - j$, so that all the terms of the above equality except $v_{i,j}$ are known. The result then follows from the Dodgson formula.

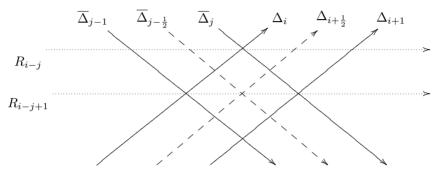
The algebraic frieze looks as follows: (3.2)

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3.3. Recurrence relations on the diagonals

Let us introduce the following notation.

- (1) The diagonals pointing "North-East" (that contain all the elements $v_{i,.}$ with *i* fixed); are denoted by Δ_i .
- (2) The diagonals pointing "South-East" (that contain all the elements $v_{..i}$ with j fixed) are denoted by $\overline{\Delta}_i$.
- (3) The (horizontal) rows $\{v_{i,j} \mid i-j = \text{const}\}\$ are denoted by R_{i-j} .



PROPOSITION 3.2. — One has the following recurrence relations. For all $i \in \mathbb{Z}$,

(3.3)
$$\begin{aligned} \Delta_i &= A_i \Delta_{i-1} - B_i \Delta_{i-2} + \Delta_{i-3}, \\ \overline{\Delta}_i &= A_i \overline{\Delta}_{i+1} - B_{i+1} \overline{\Delta}_{i+2} + \overline{\Delta}_{i+3}. \end{aligned}$$

and

(3.4)
$$\begin{aligned} \Delta_{i+\frac{1}{2}} &= B_{i+1}\Delta_{i-\frac{1}{2}} - A_i\Delta_{i-\frac{3}{2}} + \Delta_{i-\frac{5}{2}}, \\ \overline{\Delta}_{i+\frac{1}{2}} &= B_{i+1}\overline{\Delta}_{i+\frac{3}{2}} - A_{i+1}\overline{\Delta}_{i+\frac{5}{2}} + \overline{\Delta}_{i+\frac{7}{2}}. \end{aligned}$$

Proof. — Straighforward using the determinant formula (3.1).

Note also that the difference equations (3.3) and (3.4) are *dual* to each other, see [21].

3.4. Relation to SL₃-tilings

An SL_k-tiling is an infinite matrix such that any principal $k \times k$ -minor (i.e., a minor with contiguous row and column indices) is equal to 1. These SL_k-tilings were introduced and studied in [2]. Following [2], we note that an algebraic 2-frieze pattern contains two SL₃-tilings.

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PROPOSITION 3.3. — The subpatterns $(v_{i,j})_{i,j\in\mathbb{Z}}$ and $(v_{i,j})_{i,j\in\mathbb{Z}+\frac{1}{2}}$ of $F(A_i, B_i)$ are both SL₃-tilings.

Proof. — Using Dodgson's formula, one obtains

$$\begin{vmatrix} v_{i-1,j-1} & v_{i-1,j} & v_{i-1,j+1} \\ v_{i,j-1} & v_{i,j} & v_{i,j+1} \\ v_{i+1,j-1} & v_{i+1,j} & v_{i+1,j+1} \end{vmatrix} v_{i,j}$$

$$= \begin{vmatrix} v_{i-1,j-1} & v_{i-1,j} \\ v_{i,j-1} & v_{i,j} \end{vmatrix} \begin{vmatrix} v_{i,j} & v_{i,j+1} \\ v_{i+1,j} & v_{i+1,j+1} \end{vmatrix}$$

$$- \begin{vmatrix} v_{i-1,j} & v_{i-1,j+1} \\ v_{i,j} & v_{i,j+1} \end{vmatrix} \begin{vmatrix} v_{i,j-1} & v_{i,j} \\ v_{i+1,j-1} & v_{i+1,j} \end{vmatrix}$$

$$= v_{i-\frac{1}{2},j-\frac{1}{2}} v_{i+\frac{1}{2},j+\frac{1}{2}} - v_{i-\frac{1}{2},j+\frac{1}{2}} v_{i+\frac{1}{2},j-\frac{1}{2}}$$

$$= v_{i,j}.$$

If follows from Proposition 3.1, that $v_{i+1,j-1} \neq 0$. One obtains

$$\begin{vmatrix} v_{i,j-2} & v_{i,j-1} & v_{i,j} \\ v_{i+1,j-2} & v_{i+1,j-1} & v_{i+1,j} \\ v_{i+2,j-2} & v_{i+2,j-1} & v_{i+2,j} \end{vmatrix} = 1.$$

 \square

Hence the result.

The two SL_3 -tilings are dual to each other in the sense of [2]. The converse statement also holds: one can construct a 2-frieze pattern from an SL_3 -tiling by superimposing the tiling on its dual, see [2].

4. Numerical friezes

In this section, we prove Propositions 2.3, 2.6, 2.7 and Theorem 2.5. We also discuss a relation with a moduli space of Fock-Goncharov [11, 10].

4.1. Entries of a numerical frieze

Consider a numerical 2-frieze $F(a_i, b_i)$. Its entries $v_{i,j}$ can be expressed as determinants involving solutions of the corresponding difference equation (1.1), understood as vectors in 3-space.

LEMMA 4.1. — One has

(4.1)
$$v_{i,j} = |V_{j-3}, V_{j-2}, V_i|, \quad v_{i-\frac{1}{2},j-\frac{1}{2}} = |V_{i-1}, V_i, V_{j-3}|,$$

where $V = (V_i)$ is any solution of (1.1) such that $|V_{i-2}, V_{i-1}, V_i| = 1$.

Proof. — Consider the diagonal $\overline{\Delta}_j$ of the frieze, its elements $v_{i,j}$ are labeled by one index $i \in \mathbb{Z}$. We proceed by induction on i.

The base of induction is given by the three trivial elements $v_{j-3,j} = v_{j-2,j} = 0$ and $v_{j-1,j} = 1$ which obviously satisfy (4.1).

The induction step is as follows. According to formula (3.3), the elements $v_{i,j}$ satisfy the recurrence (1.1). One then has

$$\begin{aligned} v_{i,j} &= a_i \, v_{i-1,j} - b_i \, v_{i-2,j} + v_{i-3,j} \\ &= a_i \, |V_{j-3}, \, V_{j-2}, \, V_{i-1}| - b_i \, |V_{j-3}, \, V_{j-2}, \, V_{i-2}| + |V_{j-3}, \, V_{j-2}, \, V_{i-3}| \\ &= |V_{j-3}, \, V_{j-2}, \, a_i V_{i-1} - b_i V_{i-2} + V_{i-3}| \\ &= |V_{j-3}, \, V_{j-2}, \, V_i.| \end{aligned}$$

Hence the result.

The proof in the half-integer case is similar.

4.2. Proof of Proposition 2.3

Consider a numerical frieze $F(a_i, b_i)$ and assume that this frieze is closed, as in (2.2), of width n - 4. Choosing the diagonal $\overline{\Delta}_i$, let us determine the last non-trivial element $v_{i+n-5,i}$:

1	1	1	1	1	1	1
	a_i					
		·				
			$\mathbf{v_{i+n-5,i}}$			
1	1	1	v _{i+n-5,i} 1	1	1	1
$1 \\ 0$	1 0	1 0		1 0	1 0	$1 \\ 0$

Using the first recurrence relation in (3.3), one has

$$v_{i+n-2,i} = a_{i+n-2} v_{i+n-3,i} - b_{i+n-2} v_{i+n-4,i} + v_{i+n-5,i}.$$

This implies $v_{i+n-5,i} = b_{i+n-2}$, since $v_{i+n-2,i} = v_{i+n-3,i} = 0$ and $v_{i+n-4,i} = 1$. On the other hand, using the second recurrence relation in (3.3), one has

$$v_{i+n-5,i-3} = a_{i-3} v_{i+n-5,i-2} - b_{i-2} v_{i+n-5,i-1} + v_{i+n-5,i-1}$$

This implies $v_{i+n-5,i} = b_{i-2}$. Combining these two equalities, one has *n*-periodicity:

$$b_{i+n-2} = b_{i-2}.$$

Similarly, choosing the diagonal $\overline{\Delta}_{i+\frac{1}{2}}$, one obtains *n*-periodicity of the a_i . Finally, 2*n*-periodicity on the first two rows implies 2*n*-periodicity on each row. Part (i) is proved.

In order to prove Part (ii), we continue to determine the entries of $\overline{\Delta}_i$:

$$v_{i+n-5,i}$$
1
0
0
1
 $v_{i+n,i}$

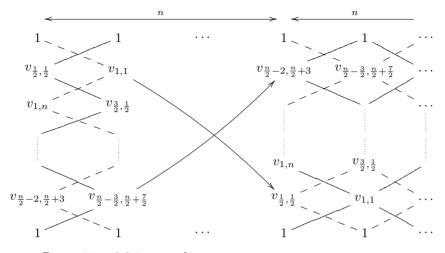
Using (3.3), we deduce that $v_{i+n-1,i} = 1$ and, using this relation again,

$$v_{i+n,i} = a_{i+n} = a_i = v_{i,i}, \qquad i \in \mathbb{Z}$$

and similarly for $i \in \mathbb{Z} + \frac{1}{2}$. Part (ii) is proved.

Part (iii) follows from the equalities $v_{i+n-5,i} = b_{i+n-2} = b_{i-2}$ proved in Part (i). Indeed, in the first non-trivial row, $b_{i-2} = v_{i-\frac{5}{2},i-\frac{5}{2}}$, so that we rewrite the above equality as follows: $v_{i,i} = v_{i+n-\frac{5}{2},i+\frac{5}{2}}$. This means that the first non-trivial row is related to the last one by the desired glide symmetry. Then using the 2-frieze rule we deduce that the same glide symmetry

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relates the second row with the one before the last, etc.

Proposition 2.3 is proved.

4.3. Proof of Theorem 2.5

Given a closed numerical frieze $F(a_i, b_i)$, let us show that all the solutions of the corresponding difference equation (1.1) are periodic. Proposition 2.3, Part (ii) implies that all the diagonals $\overline{\Delta}_j$ are *n*-periodic. Take three consecutive diagonals, say $\overline{\Delta}_1, \overline{\Delta}_2, \overline{\Delta}_3$, they provide linearly independent periodic solutions $(v_{i,1}, v_{i,2}, v_{i,3})$ to (1.1). It follows that every solution is periodic, so that the monodromy matrix M is the identity.

Conversely, suppose that all the solutions of (1.1) are periodic, i.e. the monodromy is the identity. Consider the frieze $F(a_i, b_i)$. We have proved that the diagonals Δ_i with $i \in \mathbb{Z}$ satisfy the recurrence equation (3.3), which is nothing else but (1.1). Add formally two rows of zeroes above the first row of 1's:

One checks immediately that this changes nothing in the recurrence relation. It follows that the diagonals Δ_i with $i \in \mathbb{Z}$ are periodic.

The diagonals Δ_i with $i \in \mathbb{Z} + \frac{1}{2}$ satisfy the recurrence equation (3.4). This is precisely the difference equation dual to (1.1). The corresponding monodromy is the conjugation of the monodromy of (1.1), so that it is again equal to the identity. It follows that the half-integer diagonals are also periodic.

In particular, two consecutive rows of 0's followed by a row of 1's will appear again. These rows are necessarily preceded by a row 1's in order to satisfy (3.3) and (3.4). The 2-frieze pattern is closed.

4.4. Difference equations, and polygons in space and in the projective plane

In this section, we prove Proposition 2.6.

The relation between the difference equations (1.1) and polygons was already established in Section 1.3 (combined with Section 1.2). A difference equation has a 3-dimensional space of solutions, and these solutions form a sequence of vectors satisfying (1.1). If the monodromy is trivial then the sequence of vectors is *n*-periodic. The sequence of the V_i (as vector in 3dimensional space) then gives a closed polygon (otherwise, it is twisted). It follows from (1.1) that the determinant of every three consecutive vectors is the same. One can scale the vectors to render this determinant unit, and then the SL₃-equivalence class of the polygon is uniquely determined.

Conversely, a polygon satisfying the unit determinant condition gives rise to a difference equation (1.1): each next vector is a linear combination of the previous three, and one coefficient is equal to 1, due to the determinant condition. Two SL₃-equivalent polygons yield the same difference equation, and a closed polygon yields an equation with trivial monodromy.

To prove that the projection $\tilde{\mathcal{C}}_n \to \mathcal{C}_n$ is bijective for n not a multiple of 3, let us construct the inverse map. Given an n-gon (v_i) in the projective plane, let \tilde{V}_i be some lift of the point v_i to 3-space. We wish to rescale, $V_i = t_i \tilde{V}_i$, so that the unit determinant relation holds: $\det(V_{i-1}, V_i, V_{i+1}) = 1$ for all i. This is equivalent to the system of equations

$$t_{i-1}t_i t_{i+1} = 1/\det(V_{i-1}, V_i, V_{i+1})$$

(the denominators do not vanish because every triple of consecutive vertices of a polygon is not collinear). This system has a unique solution if n is not a multiple of 3. Furthermore, projectively equivalent polygons in the projective plane yield SL_3 -equivalent polygons in 3-space. This completes the proof of Proposition 2.6.

Remark 4.2. — Two points in \mathbb{RP}^2 determine not one, but two segments, and a polygon in \mathbb{RP}^2 , defined as a cyclic collection of vertices, does not automatically have sides, i.e., segments connecting consecutive vertices. For example, three points in general position determine four different triangles, thought of as triples of segments sharing end-points. In contrast, for a polygon (V_i) in \mathbb{R}^3 , the sides are the segments V_iV_{i+1} . Thus, using the above described lifting, one can make a canonical choice of sides of an *n*gon in \mathbb{RP}^2 , provided that *n* is not a multiple of 3. Changing the orientation of a polygon does not affect the choice of the segments. The choice of the segments does not depend on the orientation of \mathbb{R}^3 either.

4.5. Convex polygons in space and in the projective plane

The proof of Proposition 2.7 is immediate now. According to formula (4.1), all the entries of a real 2-frieze pattern are positive if and only if the respective polygon in \mathbb{R}^3 is convex, as claimed.

We shall now discuss the relation between convexity in space and in the projective plane. An *n*-gon (v_i) in \mathbb{RP}^2 is called convex if there exists an affine chart in which the closed polygonal line $v_1v_2...v_n$ is convex. The space of convex *n*-gons in \mathbb{RP}^2 is denoted by \mathcal{C}_n^0 .

LEMMA 4.3. — If (V_i) is a convex *n*-gon in space then its projection to \mathbb{RP}^2 is a convex *n*-gon. Conversely, if *n* is not a multiple of 3 and (v_i) is a convex *n*-gon in \mathbb{RP}^2 then its lift to \mathbb{R}^3 is a convex *n*-gon.

Proof. — Let (V_i) be a convex *n*-gon in space. Let π be the oriented plane spanned by V_1 and V_2 . Let V_1^{ε} and V_2^{ε} be points on the negative side of π that are ε -close to V_1 and V_2 . Let π_{ε} be the plane spanned by V_1^{ε} and V_2^{ε} . If ε is a sufficiently small positive number, all the points V_i lie on one side of π_{ε} . Without loss of generality, we may assume that π_{ε} is the horizontal plane and all points V_i are in the upper half-space. Consider the radial projection of the polygon (V_i) on the horizontal plane at height one. This plane provides an affine chart of \mathbb{RP}^2 . The resulting polygon, (v_i) , has the property that, for every *i* and every $j \neq i-1, i$, the vertex v_j lies on the positive side of the line $v_{i-1}v_i$. Hence this projection is a convex polygon in this plane.

Conversely, let (v_i) be a convex polygon in the projective plane. As before, we assume that the vertices are located in the horizontal plane in \mathbb{R}^3 at height one. Convexity implies that the polygon lies on one side of the line through each side, that is, with the proper orientation, that $\det(v_{i-1}, v_i, v_j) > 0$ for all i and $j \neq i - 1, i$. One needs to rescale the vectors, $V_i = t_i v_i$, to achieve the unit determinant condition on triples of consecutive vectors. Since the determinants are already positive, it follows that $t_i > 0$ for all i. Therefore $\det(V_{i-1}, V_i, V_j) > 0$ for all i and $j \neq i - 1, i$, and (V_i) is a convex polygon. \Box

4.6. The space C_{3m} and the Fock-Goncharov variety

Consider the special case of the space C_n with n = 3m. As already mentioned, in this case, the space C_n is not isomorphic to the space of difference equations (1.1) and therefore it is not isomorphic to the space of closed 2-frieze patterns. We discuss this special case for the sake of completeness and because it provides an interesting link to another cluster variety.

In [11, 10] (see also [22], Section 6.5) Fock and Goncharov introduced and thoroughly studied the space \mathcal{P}_n consisting of pairs of convex *n*-gons (P, P') in \mathbb{RP}^2 , modulo projective equivalence, such that P' is inscribed into P.

The following statement relates the space \mathcal{P}_{2m} and the space \mathcal{C}_{3m}^0 of convex 3m-gons.

PROPOSITION 4.4. — The space \mathcal{C}_{3m}^0 is isomorphic to the space \mathcal{P}_{2m} .

Proof. — The proof consists of a construction, see Figure 4.1. Consider a convex 3m-gon.

- (1) Choose a vertex v_i and draw the short diagonal (v_{i-1}, v_{i+1}) .
- (2) Extend the sides (v_i, v_{i+1}) and (v_{i+2}, v_{i+3}) to their intersection point.
- (3) Repeat the procedure starting from v_{i+3} .

One obtains a pair of 2m-gons inscribed one into the other. The procedure is obviously bijective and commutes with the $SL(3, \mathbb{R})$ -action.

Remark 4.5. — Choosing the vertex v_{i+1} or v_{i+2} in the above construction, one changes the identification between the spaces C_{3m}^0 and \mathcal{P}_{2m} . This, in particular, defines a map τ from \mathcal{P}_{2m} to \mathcal{P}_{2m} , such that $\tau^3 = \text{Id}$.

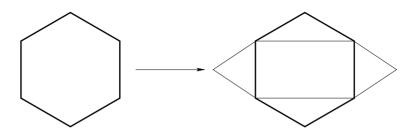


Figure 4.1. From a hexagon to a pair of inscribed quadrilaterals

5. Closed 2-friezes as cluster varieties

We now give a description of the space of all closed 2-frieze patterns. This is an 8-codimensional subvariety of the space \mathbb{C}^{2n} (or \mathbb{R}^{2n}) identified with the space of 2n-periodic patterns. We will characterize this variety using the technique of cluster manifolds.

5.1. Cluster algebras

Let us recall the construction of Fomin-Zelevinsky's cluster algebras [12]. A cluster algebra \mathcal{A} is a commutative associative algebra. This is a subalgebra of a field of rational fractions in N variables, where N is called the rank of \mathcal{A} . The algebra \mathcal{A} is presented by generators and relations. The generators are collected in packages called *clusters*, the relations between generators are obtained by applying a series of specific elementary relations called the *exchange relations*. The exchange relations are encoded via a matrix, or an oriented graph with no loops and no 2-cycles.

The explicit construction of the (complex or real) cluster algebra $\mathcal{A}(\mathcal{Q})$ associated to a finite oriented graph \mathcal{Q} is as follows. Let N be the number of vertices of \mathcal{Q} , the set of vertices is then identified with the set $\{1, \ldots, N\}$. The algebra $\mathcal{A}(\mathcal{Q})$ is a subalgebra of the field of fractions $\mathbb{C}(x_1,\ldots,x_N)$ in N variables x_1, \ldots, x_N (or over \mathbb{R} , in the real case). The generators and relations of $\mathcal{A}(\mathcal{Q})$ are given using a recursive procedure called *seed mutations* that we describe below.

A *seed* is a couple

$$\Sigma = \left(\{ t_1, \ldots, t_N \}, \ \mathcal{R} \right),$$

where \mathcal{R} is an arbitrary finite oriented graph with N vertices and where t_1,\ldots,t_N are free generators of $\mathbb{C}(x_1,\ldots,x_N)$. The mutation at vertex k of the seed Σ is a new seed $\mu_k(\Sigma)$ defined by

$$\mu_k(\{t_1, \dots, t_N\}) = \{t_1, \dots, t_{k-1}, t'_k, t_{k+1}, \dots, t_N\} \text{ where}$$
$$t'_k = \frac{1}{t_k} \left(\prod_{\substack{\text{arrows in } \mathcal{R} \\ i \to k}} t_i + \prod_{\substack{\text{arrows in } \mathcal{R} \\ i \leftarrow k}} t_i\right)$$

- $\mu_k(\mathcal{R})$ is the graph obtained from \mathcal{R} by applying the following transformations
 - (a) for each possible path $i \to k \to j$ in \mathcal{R} , add an arrow $i \to j$,
 - (b) reverse all the arrows leaving or arriving at k,
 - (c) remove all the possible 2-cycles,

(see Example 5.1 below for a seed mutation).

Starting from the initial seed $\Sigma_0 = (\{x_1, \ldots, x_N\}, \mathcal{Q})$, one produces N new seeds $\mu_k(\Sigma_0), k = 1, \ldots, N$. Then one applies all the possible mutations to all of the created new seeds, and so on. The set of rational functions appearing in any of the seeds produced during the mutation process is called a *cluster*. The functions in a cluster are called *cluster variables*. The cluster algebra $\mathcal{A}(\mathcal{Q})$ is the subalgebra of $\mathbb{C}(x_1, \ldots, x_N)$ generated by all the cluster variables.

Example 5.1. — In the case n = 4, consider the seed

$$\Sigma = (\{t_1, t_2, t_3, t_4\}, \mathcal{R}),$$

where

$$\mathcal{R} = \begin{array}{ccc} 1 \longrightarrow 2 \\ \uparrow & & \downarrow \\ 3 \longleftarrow 4 \end{array}$$

The mutation at vertex 1 gives

$$\mu_1(\{t_1, t_2, t_3, t_4\}) = \left\{\frac{t_2 + t_3}{t_1}, t_2, t_3, t_4\right\}$$

and

$$\mu_1(\mathcal{R}) = \begin{array}{c} 1 & \underbrace{2} \\ & 1 \\ & 1 \\ & 2 \\ & 3 \\ & 4 \end{array}$$

In this example, one can show that the mutation process is finite. This means that applying all the possible mutations to all the seeds leads to a finite number of seeds and therefore to a finite number (24) of cluster variables. One can also show that among the graphs obtained through iterated mutations is the Dynkin graph of type D_4 . The cluster algebra $A(\mathcal{R})$ in this example is referred to as the cluster algebra of type D_4 .

5.2. The algebra of regular functions on \mathcal{F}_n

In the case of the oriented graph (2.3), the cluster algebra $\mathcal{A}(\mathcal{Q})$ has an infinite number of generators (for $n \ge 9$). In this section, we consider the algebra of regular functions on \mathcal{F}_n and show that this is a subalgebra of $\mathcal{A}(\mathcal{Q})$. From now on, \mathcal{Q} always stands for the oriented graph (2.3).

The space of closed 2-friezes \mathcal{F}_n is an algebraic manifold, $\mathcal{F}_n \subset \mathbb{C}^{2n}$ (or \mathbb{R}^{2n} in the real case), defined by the trivial monodromy condition M = Id, that can be written as 8 polynomial identities. The algebra of regular functions on \mathcal{F}_n is then defined as

$$\mathcal{A}_n = \mathbb{C}[A_1, \dots, A_n, B_1, \dots, B_n]/\mathcal{I},$$

where \mathcal{I} is the ideal generated by $(M - \mathrm{Id})$. Let us describe the algebra \mathcal{A}_n in another way.

We define the following system of coordinates on the space \mathcal{F}_n . Consider 2n - 8 independent variables $(x_1, \ldots, x_{n-4}, y_1, \ldots, y_{n-4})$ and place them into two consecutive columns on the frieze:

	1	1	1	1	1	•••
	x_1	y_1				
	y_2	x_2	•••			
(5.1)	x_3	y_3	•••			
	y_4	x_4				
	÷	÷				
	1	1	1	1	1	

Applying the recurrence relations, complete the 2-frieze pattern by rational functions in x_i, y_j . Since the 2-frieze pattern (5.1) is closed, Proposition 2.3 implies that the closed 2-frieze pattern (5.1) contains n(n-4) distinct entries modulo periodicity.

Example 5.2. — Case n = 5... 1 1 1 1 1 1 1 1 $x \ y \ \frac{y+1}{x} \ \frac{x+y+1}{xy} \ \frac{x+1}{y} \ x \ y \ \cdots$... 1 1 1 1 1 1 ...

In this case, $\mathcal{A}_5 \simeq \mathcal{A}(1 \rightarrow 2)$.

Example 5.3. — Case n = 61 1 1 1 1 1 1 1 $(y_1+x_2)(y_2+x_1)$ $(x_1+y_2)(x_2+y_1)$ $y_1 + x_2$ $x_1 + y_2$ x_1 x_2 y_1 u_2 $x_1 y_1 y_2$ $x_2 y_1 y_2$ x_2 x_1 $x_2 + y_1$ $(x_2+y_1)(x_1+y_2)$ $(y_2+x_1)(y_1+x_2)$ $y_2 + x_1$ x_2 x_1 y_2 y_1 y_2 $y_2 x_2 x_1$ $y_1 x_1 x_2$ y_1 1 1 1 1 1 1 1 1

In this case, the algebra \mathcal{A}_6 is isomorphic to a proper subalgebra of $\mathcal{A}(D_4)$.

PROPOSITION 5.4. — (i) The algebra \mathcal{A}_n is isomorphic to the subalgebra of the algebra of rational functions $\mathbb{C}(x_1, \ldots, x_{n-4}, y_1, \ldots, y_{n-4})$ generated by the entries of the 2-frieze (5.1).

(ii) The algebra \mathcal{A}_n is a subalgebra of the cluster algebra $\mathcal{A}(\mathcal{Q})$, where \mathcal{Q} is the graph (2.3).

Proof. — (i) The entries of (5.1) are polynomials in 2n consecutive entries of the first row (see Proposition 3.1). The isomorphism is then obtained by sending $B_1, A_1, \ldots, B_n, A_n$ to the entries of the first line.

(ii) Consider $\Sigma_0 = (\{x_1, \ldots, x_{n-4}, y_1, \ldots, y_{n-4}\}, \mathcal{Q})$ as an initial seed. The variable x_i is associated to the vertex i of \mathcal{Q} and the variable y_i to the vertex n - 4 + i. We need to prove that all the entries of (5.1) are cluster variables.

The graph Q is bipartite. One can associate a sign $\varepsilon(i) = \pm$ to each vertex of the graph so that any two connected vertices in Q have different signs. Let us assume that $\varepsilon(1) = +$ (this determines automatically all the signs of the vertices).

Following Fomin-Zelevinsky [14], consider the iterated mutations

$$\mu_+ = \prod_{i:\varepsilon(i)=+} \mu_i, \qquad \mu_- = \prod_{i:\varepsilon(i)=-} \mu_i.$$

Note that μ_i with $\varepsilon(i)$ fixed commute with each other.

It is important to notice that the result of the mutation of the graph (2.3) by μ_+ and μ_- is the same graph with reversed orientation:

$$\mu_+(\mathcal{Q}) = \mathcal{Q}^{\mathrm{op}}, \qquad \mu_-(\mathcal{Q}^{\mathrm{op}}) = \mathcal{Q}.$$

This is a straightforward verification.

Consider the seeds of $\mathcal{A}(\mathcal{Q})$ obtained from Σ_0 by applying successively μ_+ or μ_- :

(5.2)
$$\Sigma_0, \quad \mu_+(\Sigma_0), \quad \mu_-\mu_+(\Sigma_0), \quad \dots, \quad \mu_\pm\mu_\mp\cdots\mu_-\mu_+(\Sigma_0), \quad \dots$$

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This set is called the bipartite belt of $\mathcal{A}(\mathcal{Q})$, see [14]. The cluster variables in each of the above seeds correspond precisely to two consecutive columns in the 2-frieze pattern (5.1).

Proposition 5.4 is proved.

Remark 5.5. — Periodicity of the sequence (5.2) follows from Proposition 2.3. This periodicity of closed 2-frieze patterns, expressed in cluster variables, is a particular case of the general periodicity theorem in cluster algebra, see [30, 18] and references therein. Our proof of this result is based on simple properties of solutions of the difference equation (1.1) and is given for the sake of completeness.

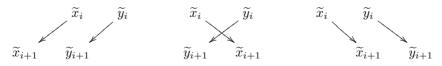
5.3. Zig-zag coordinates

In this section, we prove Theorem 2.9 and Proposition 2.10. To this end, we introduce a number of coordinate systems on the space of 2-friezes.

We define another system of coordinates on \mathcal{F}_n . Draw an arbitrary *double zig-zag* in the 2-frieze (5.1) and denote by $(\tilde{x}_1, \ldots, \tilde{x}_{n-4}, \tilde{y}_1, \ldots, \tilde{y}_{n-4})$ the entries lying on this double zig-zag:

in such a way that \tilde{x}_i stay at the entries with integer indices and \tilde{y}_i stay at the entries with half-integer indices.

More precisely, a double zig-zag of coordinates is defined as follows. The coordinates \tilde{x}_i and \tilde{y}_i in the *i*-th row, are followed by the coordinates \tilde{x}_{i+1} and \tilde{y}_{i+1} in one of the three possible ways:



Denote by \mathcal{Z} the set of all double zig-zags. For an arbitrary double zigzag $\zeta \in \mathcal{Z}$, the corresponding functions $(\tilde{x}_1, \ldots, \tilde{x}_{n-4}, \tilde{y}_1, \ldots, \tilde{y}_{n-4})_{\zeta}$ are rational expressions in (x_i, y_i) .

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PROPOSITION 5.6. — (i) For every double zig-zag $\zeta \in \mathbb{Z}$, the coordinates $(\widetilde{x}_i, \widetilde{y}_i)_{\ell}$ form a cluster in the algebra $\mathcal{A}(\mathcal{Q})$, where \mathcal{Q} is the graph (2.3).

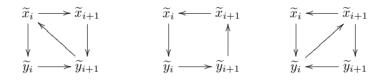
(ii) A cluster in $\mathcal{A}(\mathcal{Q})$ coincides with the coordinate system $(\tilde{x}_i, \tilde{y}_i)_{\zeta}$ for some $\zeta \in \mathcal{Z}$, if and only if it is obtained from the initial cluster (x_i, y_i) by mutations at vertices that do not belong to two 3-cycles.

Proof. — (i) For every double zig-zag ζ , we define a seed Σ_{ζ} = $((x_i, y_i)_{\zeta}, \mathcal{Q}_{\zeta})$ in the algebra $\mathcal{A}(\mathcal{Q})$, where \mathcal{Q}_{ζ} is the oriented graph associated to ζ defined as follows.

The fragments of zig-zags:

$$\begin{aligned} & \widetilde{x}_i \quad \widetilde{y}_i & \widetilde{x}_i \quad \widetilde{y}_i & \widetilde{x}_i \quad \widetilde{y}_i \\ & \widetilde{x}_{i+1} \quad \widetilde{y}_{i+1} & \widetilde{y}_{i+1} & \widetilde{x}_{i+1} & \widetilde{x}_{i+1} & \widetilde{x}_{i+1} & \widetilde{y}_{i+1} \end{aligned}$$

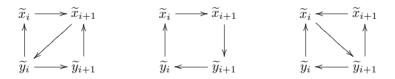
correspond, respectively, to the following subgraphs:



for i even and with reversed orientation for i odd. Similarly, the fragments

 $\begin{array}{ccccc} \widetilde{y}_i & \widetilde{x}_i & \widetilde{y}_i & \widetilde{x}_i & \widetilde{y}_i & \widetilde{x}_i \\ \widetilde{y}_{i+1} & \widetilde{x}_{i+1} & & \widetilde{x}_{i+1} & \widetilde{y}_{i+1} & & & \widetilde{y}_{i+1} & \widetilde{x}_{i+1} \end{array}$

correspond to

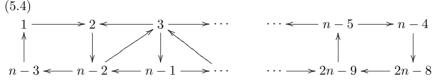


for i even and with reversed orientation for i odd. Applying this recurrent procedure, one defines an oriented graph \mathcal{Q}_{ζ} .

For every double zig-zag ζ , there is a series of zig-zags $\zeta_1, \zeta_2, \ldots, \zeta_k$ such that ζ_i and ζ_{i+1} differ in only one place, say $\widetilde{x}_{\ell_i}, \widetilde{y}_{\ell_i}$, and such that ζ_k is the double column (5.1). It is easy to check that every "elementary move" $\zeta_i \to \zeta_{i+1}$ is obtained by a mutation of coordinates $(\widetilde{x}_i, \widetilde{y}_i)_{\zeta_i}$, while the corresponding graph $\mathcal{Q}_{\zeta_{i+1}}$ is a mutation of \mathcal{Q}_{ζ_i} .

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(ii) Every graph Q_{ζ} that we construct in the seeds corresponding to zig-zag coordinates is of the form



That is, Q_{ζ} is the initial graph (2.3) with some diagonals added (such that the triangles and empty squares are cyclically oriented). Conversely, from every such graph, one immediately constructs a double zig-zag.

A graph of the form (5.4) can be obtained from the initial graph Q by a series of mutations at the vertices that do not belong to triangles. Conversely, a mutation at a vertex on a triangle changes the nature of the graph (it removes sides of squares).

Example 5.7. — Consider a double-diagonal, it can be "redressed" to a double-column by a series of elementary moves, for instance in the case n = 7,

The corresponding graphs are:

We are ready to prove Theorem 2.9.

Part (i). It follows from the Laurent phenomenon for cluster algebras [13] that all the entries of the frieze (5.3) are Laurent polynomials in any zigzag coordinates $(\tilde{x}_i, \tilde{y}_i)_{\zeta}$. Therefore, for every double zig-zag ζ , we obtain a well-defined map from the complex torus $(\mathbb{C}^*)^{2n-8}$ to the open dense subset of \mathcal{F}_n consisting of 2-friezes with non-vanishing entries on ζ . Hence the result.

Part (ii). Assume that the coordinates $(\tilde{x}_i, \tilde{y}_i)_{\zeta}$ are positive real numbers. It then follows from the 2-frieze rule that all the entries of the frieze are positive. Therefore, every system of coordinates $(\tilde{x}_i, \tilde{y}_i)_{\zeta}$ identifies the subspace \mathcal{F}_n^0 with $\mathbb{R}_{>0}^{2n-8}$.

Theorem 2.9 is proved.

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Let us also prove Proposition 2.10. Consider an arbitrary double zigzag ζ . The set of coordinates $(\tilde{x}_1, \ldots, \tilde{x}_{n-4}, \tilde{y}_1, \ldots, \tilde{y}_{n-4})_{\zeta}$ forms a cluster. Proposition 2.10 then follows from the Laurent phenomenon.

5.4. The cluster manifold of closed 2-friezes

The two systems of coordinates $(\tilde{x}_i, \tilde{y}_i)_{\zeta}$ and $(\tilde{x}_i, \tilde{y}_i)_{\zeta'}$, where ζ and ζ' are two double zig-zags, can be reached from one another by a series of mutations.

Consider all the coordinate systems corresponding to different double zig-zags. We call the *cluster manifold of 2-friezes* the smooth analytic (complex) manifold obtained by gluing together the complex tori $(\mathbb{C}^*)^{2n-8}$ via the consecutive mutations.

The cluster manifold of 2-friezes is not the entire algebraic variety \mathcal{F}_n . Indeed, the smooth cluster manifold of 2-friezes consists of the 2-friezes that have at least one double zig-zag with non-zero entries. However, the full space \mathcal{F}_n also contains singular points.

To give an example, consider n = km with $k, m \ge 3$ and take an *n*-gon obtained as an *m*-gon traversed k times. The corresponding closed 2-frieze pattern (of width n-4) contains double rows of zeroes (this readily follows from formula (4.1)). This 2-frieze pattern does not belong to the smooth cluster manifold of 2-friezes.

Remark 5.8. — In the cases n = 6, 7, 8, Scott [26] proved that the cluster algebra built out of the graph (2.3) is isomorphic to the coordinate ring of the Grassmannian Gr(3, n). In these algebras, Plücker coordinates form a proper subset of the set of cluster variables (14 Plücker coordinates among 16 cluster variables for n = 6, 28 among 42 for n = 7 and 48 among 128 for n = 8). It can be checked that the n(n - 4) cluster variables arising in the 2-frieze of width n - 4 are also Plücker coordinates. However, we do not know if there is a nice way to characterize them using Scott's approach (in terms of Postnikov arrangement or root correspondence).

5.5. The symplectic structure

The complete integrability of the pentagram map [21] was deduced from the existence of an invariant Poisson structure on the space of twisted ngons. In general, completely integrable dynamics is usually associated with invariant symplectic or Poisson structure - thus our interest in this question. Every cluster manifold has a canonical (pre)symplectic form, i.e., a closed differential 2-form, see [15]. Let us recall here the general definition. For an arbitrary seed $\Sigma = (\{t_1, \ldots, t_N\}, \mathcal{R})$ on a cluster manifold, the 2-form is as follows:

(5.5)
$$\omega = \sum_{\substack{\text{arrows in } \mathcal{R} \\ i \to j}} \frac{dt_i}{t_i} \wedge \frac{dt_j}{t_j}.$$

It is then easy to check that the 2-form ω is well-defined, that is, does not change under mutations. The 2-form ω is obviously closed (since it is constant in the coordinates $\log t_i$). However, this form is not always symplectic and may be degenerate.

One of the consequence of the defined cluster structure is the existence of such a form on the cluster manifold of 2-friezes. It turns out that this form is *non-degenerate*, for $n \neq 3m$.

PROPOSITION 5.9. — (i) The differential 2-form (5.5) on \mathcal{F}_n is symplectic if and only if $n \neq 3m$.

(ii) If n = 3m, then the form (5.5) is a presymplectic form of corank 2.

Proof. — It suffices to check the statement for the initial seed $\Sigma_0 = (\{x_1, \ldots, x_{n-4}, y_1, \ldots, y_{n-4}\}, \mathcal{Q})$, where \mathcal{Q} is the graph (2.3). The form (5.5) then corresponds to the following skew-symmetric $(2n-8) \times (2n-8)$ -matrix

$$\omega(n) = \begin{pmatrix} 0 & 1 & 0 & 0 & \cdots & 0 & 0 & -1 \\ -1 & 0 & -1 & 0 & \cdots & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & \cdots & -1 & 0 & 0 \\ & & & \ddots & & & \\ 0 & 0 & 1 & 0 & \cdots & 0 & -1 & 0 \\ 0 & -1 & 0 & 0 & \cdots & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 & \cdots & 0 & -1 & 0 \end{pmatrix}$$

which is nothing other than the incidence matrix of the graph (2.3) (for technical reasons we inverse the labeling of the second line). We need to check that this matrix is non-degenerate if and only if $n \neq 3m$ and has corank 2 otherwise.

(i) We proceed by induction on n. First, one easily checks the statement for small n. Indeed, for n = 5, n = 6 and n = 7, the matrix $\omega(n)$ is as follows:

$$\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \quad , \quad \begin{pmatrix} 0 & 1 & 0 & -1 \\ -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 1 \\ 1 & 0 & -1 & 0 \end{pmatrix}$$

and

(0	1	0	0	0	-1
-	-1	0	-1	0	1	0
	0	1	0	-1	0	0
		0				
	0	-1	0	1	0	1
	1	0	0	0	-1	0/

respectively.

Next, the matrix $\omega(n)$ is non-degenerate if and only if $\omega(n-3)$ is nondegenerate. Indeed, denote by N = 2n-8 the size of the matrix $\omega(n)$. Add the columns (N-2) and N to the column 2, and add rows (N-2) and N to row 2. One obtains

(0	0	0				0	0	-1
	0	0	0			-1	0	-1	0
	0	0	0	1			-1	0	0
			-1						
					$-\omega(n-3)$				
		1					1		
	0	0	1			-1	0	-1	0
	0	1	0				1	0	1
	1	0	0				0	-1	0 /

Then, one can subtract column 2 from column N - 2, add column 1 to column N - 1 and do similar operations on the rows. This leads to a block of zeroes in the right down corner. Then one can easily remove the extra

± 1 's	to	finally	y obtain

(0	0	0		0	0	-1
	0	0	0	(0)	0	-1	0
	0	0	0		-1	0	0
		(0)		$-\omega(n-3)$		(0)	
	0	0	1		0	0	0
	0	1	0	(0)	0	0	0
	1	0	0		0	0	0)

The result follows.

(ii) Let now n = 3m. The $(2n - 10) \times (2n - 10)$ -minor:

$$(\omega(n)_{ij}), \qquad 2 \leq i, j \leq 2n - 9$$

coincides with the matrix $-\omega(n-1)$ which is non-degenerate as already proved in Part (i). Therefore, the matrix $\omega(n)$ is, indeed, of corank 2.

Remark 5.10. — In the case n = 3m, one can explicitly find a linear combination of the rows of $\omega(n)$ that vanishes:

$$\sum_{0 \leqslant i < [m/2]} \left(\ell_{6i+1} + \ell_{N-6i-1} \right) - \sum_{1 \leqslant i < [m/2]} \left(\ell_{6i-1} + \ell_{N-6i+3} \right),$$

where N = 2n - 8, so that $\omega(n)$ is, indeed, degenerate.

6. Arithmetic 2-friezes

We consider now closed numerical 2-friezes whose entries are positive integers, that is, arithmetic 2-friezes. The problem of classification of such 2-frieze patterns was formulated in [23] and interpreted as a generalization of the Catalan numbers. The problem remains open.

In this section, we describe a stabilization process that is a step toward solution of this problem. It is natural to consider a 2-frieze pattern that can be obtained by stabilization as "trivial". We thus formulate a problem of classification of those patterns that cannot be obtained this way. Likewise, it is natural to call a 2-frieze pattern *prime* if it is not the connected sum of non-trivial 2-frieze patterns. The classification of prime arithmetic 2-friezes is also a challenging problem.

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It was shown in [5] that every (classical Coxeter-Conway) arithmetic frieze pattern contains 1 in the first non-trivial row and can be obtained by a simple procedure from a pattern of lower width. This provides a complete classification of Coxeter-Conway. Our stabilization is quite similar to the classification of Coxeter-Conway stabilization. However, unlike the classical case, classification of 2-frieze patterns does not reduce to stabilization (cf. for instance Example 6.7).

We start this section with the simplest examples.

6.1. Arithmetic 2-friezes for n = 4, 5

The case n = 4 is the first case where the notion of 2-frieze pattern makes sense. The unique 8-periodic pattern is the following one

which is the most elementary 2-frieze pattern.

If n = 5, the answer is as follows.

PROPOSITION 6.1. — The 2-frieze pattern

		1	1	1	1	1	1	1	1	1	1	•••
(6.2)	•••	1	1	2	3	2	1	1	2	3	2	
		1	1	1	1	1	1	1	1	1	1	•••

is the unique arithmetic 2-frieze pattern of width 1.

Proof. — According to Proposition 2.3, Parts (ii), (iii), an integral 2-frieze pattern of width 1 is of the form

• • •	1	1	1	1	1	1	1	• • •
• • •	b_0	a_0	b_1	a_1	b_2	b_0	a_0	• • •
	1	1	1	1	1	1	1	

Let us show that every number $\{b_0, a_0, b_1, a_1, b_2\}$ is less than or equal to 3.

One has from (5.2):

$$b_1 = \frac{a_0 + 1}{b_0}, \qquad b_2 = \frac{b_0 + 1}{a_0},$$

Therefore, there exist positive integers k, ℓ such that $b_0 + 1 = k a_0$ and $a_0 + 1 = \ell b_0$. Hence

(6.3)
$$a_0 = \frac{\ell+1}{k\,\ell-1}.$$

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Assume $a_0 > 3$, then $\ell(3k - 1) < 4$. Since k, ℓ are positive integers, the only possibility is $k = \ell = 1$. This contradicts (6.3).

Once one knows that the entries do not exceed 3, the proof is completed by a brief exhaustive search. $\hfill \Box$

6.2. Arithmetic 2-friezes for n = 6

The classification in this case is as follows.

PROPOSITION 6.2. — The following 5 patterns:

(6.4)	1 2 2 1	1 2 2 1	1 2 2 1	1 2 2 1	1 2 2 1	1 2 2 1	1 2 2 1	1 2 2 1	1 2 2 1	1 2 2 1	1 2 2 1	1 2 2 1
(6.5)	$ \begin{array}{c} 1 \\ 1 \\ 5 \\ 1 \end{array} $	$ \begin{array}{c} 1 \\ 3 \\ 2 \\ 1 \end{array} $	$ \begin{array}{c} 1 \\ 5 \\ 1 \\ 1 \end{array} $	1 2 3 1	$ \begin{array}{c} 1 \\ 1 \\ 5 \\ 1 \end{array} $	$ \begin{array}{c} 1 \\ 3 \\ 2 \\ 1 \end{array} $	1 5 1 1	1 2 3 1	$ \begin{array}{c} 1 \\ 1 \\ 5 \\ 1 \end{array} $	$ \begin{array}{c} 1 \\ 3 \\ 2 \\ 1 \end{array} $	1 5 1 1	$ \begin{array}{c} 1 \\ 2 \\ 3 \\ 1 \end{array} $
(6.6)	1 1 1 1	1 1 1 1	1 2 2 1	1 4 4 1	1 4 4 1	1 2 2 1	1 1 1 1	1 1 1 1	1 2 2 1	1 4 4 1	1 4 4 1	1 2 2 1
(6.7)	1 1 1 1	1 1 2 1	1 3 3 1	$ \begin{array}{c} 1 \\ 6 \\ 3 \\ 1 \end{array} $	1 3 3 1	1 1 2 1	1 1 1 1	1 2 1 1	$ \begin{array}{c} 1 \\ 3 \\ 3 \\ 1 \end{array} $	$egin{array}{c} 1 \\ 3 \\ 6 \\ 1 \end{array}$	$ \begin{array}{c} 1 \\ 3 \\ 3 \\ 1 \end{array} $	1 2 1 1
(6.8)	1 1 2 1	$egin{array}{c} 1 \\ 1 \\ 3 \\ 1 \end{array}$	1 4 2 1	1 6 2 1	$egin{array}{c} 1 \\ 2 \\ 4 \\ 1 \end{array}$	1 1 3 1	1 2 1 1	1 3 1 1	$egin{array}{c} 1 \\ 2 \\ 4 \\ 1 \end{array}$	$\begin{array}{c} 1 \\ 2 \\ 6 \\ 1 \end{array}$	$\begin{array}{c} 1 \\ 4 \\ 2 \\ 1 \end{array}$	1 3 1 1

is the complete (modulo dihedral symmetry) list of 12-periodic arithmetic 2-frieze patterns.

Proof. — We sketch an elementary, albeit somewhat tedious, proof. Let a be the greatest common divisor of x_1, y_2 , and b that of x_2, y_1 . Then

$$x_1 = a\bar{x}_1, \quad y_2 = a\bar{y}_2, \quad x_2 = b\bar{x}_2, \quad y_1 = b\bar{y}_1$$

where the pairs \bar{x}_1, \bar{y}_2 and \bar{x}_2, \bar{y}_1 are coprime. Set: $p = x_1 + y_2, q = x_2 + y_1$.

Consider Example 5.3. From the third column we see that $q = kx_1 = \ell y_2$ for some $k, \ell \in \mathbb{Z}_+$. Hence $k = A\bar{y}_2, \ell = A\bar{x}_1$ for $A \in \mathbb{Z}_+$, and $q = Aa\bar{x}_1\bar{y}_2$. Likewise, $p = Bb\bar{x}_2\bar{y}_1$. Thus

$$a(\bar{x}_1 + \bar{y}_2) = Bb\,\bar{x}_2\bar{y}_1, \qquad b(\bar{x}_2 + \bar{y}_1) = Aa\,\bar{x}_1\bar{y}_2.$$

Multiply these two equations, cancel *ab*, and rewrite in an equivalent form:

(6.9)
$$AB = \left(\frac{1}{\bar{x}_2} + \frac{1}{\bar{y}_1}\right) \left(\frac{1}{\bar{x}_1} + \frac{1}{\bar{y}_2}\right).$$

This Diophantine equation has just a few solutions, and this leads to the desired classification.

Before we list the solutions of (6.9), let us remark that the 4th and 5th columns of the 2-frieze in Example 5.3 consist of the following integers:

$$\frac{AB\bar{x}_2}{a}, \quad \frac{AB\bar{y}_1}{a}, \quad \frac{AB\bar{x}_1}{b}, \quad \frac{AB\bar{y}_2}{b}.$$

Therefore, once $A, B, \bar{x}_1, \bar{x}_2, \bar{y}_1, \bar{y}_2$ are found, one can determine the denominators, a and b, by inspection.

Now we analyze equation (6.9). First of all, at least one denominator must be equal to 1. If not, then the value of each parenthesis does not exceed 1/2 + 1/3 = 5/6, and their product is less than 1. If 1 is present in the denominator in both parentheses then we have a Diophantine equation

$$\left(1+\frac{1}{x}\right)\left(1+\frac{1}{y}\right) = AB \in \mathbb{Z}_+$$

that, up to permutations, has the solutions (1,1), (2,1) and (2,3). The respective values of AB are 4, 3 and 2. These solutions correspond to the 2-friezes (6.4) and (6.6), (6.7), and (6.8), respectively.

If 1 is present in the denominator in only one parenthesis then we have a Diophantine equation

$$\left(1+\frac{1}{x}\right)\left(\frac{1}{z}+\frac{1}{y}\right) = AB \in \mathbb{Z}_+$$

where the second parenthesis does not exceed 5/6. It follows that $x \in \{1, 2, 3, 4, 5\}$. A case by case consideration yields one more solution: x = 5 and $\{y, z\} = \{2, 3\}$. The respective value of AB is 1, and this corresponds to the 2-frieze (6.5).

Remark 6.3. — Note that we have listed 2-friezes only up to dihedral symmetry. To be consistent with the case of the Coxeter-Conway friezes, where the count is given by the Catalan numbers, one should count the cases separately, that is, not to factorize by the dihedral group or its subgroups. Then the number of 2-friezes for n = 4, 5, 6, 7 is as follows: 1, 5, 51, 868. These numbers appeared in [23]. We have independently verified this using an applet created by R. Schwartz for this purpose. The 2-frieze pattern of Proposition 6.1 gives 5 different patterns. The patterns of Proposition 6.2 contribute 1,8,6,12 and 24 different patterns, respectively. We do not have a proof that 868 is the correct answer, nor can we prove that the number of arithmetic 2-friezes is finite for each n. We hope to return to this fascinating combinatorial problem in the near future. Curiously, the only appearance of the sequence 1, 5, 51, 868 in Sloane's Online Encyclopedia [29] is in connection with Propp's paper [23].

6.3. One-point stabilization procedure

Below we describe a procedure that allows one to obtain 2-frieze patterns of width m + 1 from 2-frieze patterns of width m. More precisely, we consider 2n-periodic 2-frieze patterns whose first non-trivial row contains two consecutive entries equal to 1. Such a pattern can be obtained from a 2(n-1)-periodic pattern and, in this sense, may be considered "trivial".

PROPOSITION 6.4. — Let

$$\dots b_1, a_1, b_2, a_2, b_3, a_3 \dots$$

be the first non-trivial row that generates a 2*n*-periodic arithmetic 2-frieze as in (2.2). Then the frieze with the first non-trivial row (6.10) $\dots b_n, a_n, b_1+1, a_1+b_2+1, b_2+1, 1, 1, a_2+1, b_3+a_2+1, a_3+1, b_4, a_4\dots$

is a 2(n+1)-periodic arithmetic 2-frieze.

In other words, we cut the line between b_2 and a_2 , add 1, 1 and change the three left neighbours:

$$(b_1, a_1, b_2) \rightarrow (b_1 + 1, a_1 + b_2 + 1, b_2 + 1)$$

and similarly with the three right neighbours. The other entries remain unchanged.

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Proof. — Let (V_i) be a solution to the difference equations (1.1) associated to the initial frieze. We assume that $V_i \in \mathbb{R}^3$. We wish to add an extra point $W \in \mathbb{R}^3$ so that the points

$$\widetilde{V}_i = V_i, \quad i \leq n,$$

$$\widetilde{V}_{n+1} = W,$$

give a solution to the difference equation

$$\widetilde{V}_i = \widetilde{a}_i \, \widetilde{V}_{i-1} - \widetilde{b}_i \, \widetilde{V}_{i-2} + \widetilde{V}_{i-3}.$$

Geometrically speaking, we replace the *n*-gon $\{V_1, \ldots, V_n\}$ by the (n + 1)-gon $\{V_1, \ldots, V_n, W\}$.

It is easy to check that the choice of W is unique:

(6.11)
$$W = (b_2 + a_1 + 1) V_n - (b_1 + 1) V_{n-1} + V_{n-2}.$$

The coefficients of the resulting equation are as follows

while $\tilde{b}_i = b_i$ and $\tilde{a}_i = a_i$ for $4 \leq i \leq n$. This corresponds to (6.10).

The frieze $F(\tilde{a}_i, \tilde{b}_i)$ generated by (6.10) is again integral. Indeed, the entries of this frieze are polynomials in \tilde{a}_i, \tilde{b}_i , see formula (3.1). It remains to prove positivity of the frieze $F(\tilde{a}_i, \tilde{b}_i)$.

In the frieze $F(\tilde{a}_i, \tilde{b}_i)$, we choose two consecutive diagonals $\overline{\Delta}_1$ and $\overline{\Delta}_{\frac{3}{2}}$. Their entries are $\tilde{v}_{i,1}$ and $\tilde{v}_{i+\frac{1}{2},\frac{3}{2}}$, respectively, where $1 \leq i \leq n-3$. According to formula (4.1), one has:

$$\widetilde{v}_{i,1} = |V_n, V_{n-1}, V_i|, \qquad \widetilde{v}_{i+\frac{1}{2},\frac{3}{2}} = |V_i, V_{i+1}, V_n|.$$

Therefore, these entries do not depend on $\widetilde{V}_{n+1} = W$ and, furthermore, all these entries belong to the initial frieze $F(a_i, b_i)$. Hence, $\widetilde{v}_{i,1}$ and $\widetilde{v}_{i+\frac{1}{2},\frac{3}{2}}$ are positive integers.

Finally, according to the rule of 2-friezes, the diagonals $\overline{\Delta}_1$ and $\overline{\Delta}_{\frac{3}{2}}$ determine the rest and, moreover, all the entries are positive, see Theorem 2.9.

Remark 6.5. — It is clear that in the above stabilization process, one can cut the first non-trivial line of $F(a_i, b_i)$ at an arbitrary place (and not only between b_2 and a_2).

Let us describe the geometry of one-point stabilization. The new point, W, is inserted between V_n and V_1 . One has the relation

$$V_2 = a_2 V_1 - b_2 V_n + V_{n-1};$$

it follows that

$$a_2V_1 - V_2 = b_2V_n - V_{n-1} =: U.$$

One can easily check that

(6.12)
$$W = U + V_n + V_1.$$

It follows from the definition of U that

$$det(V_{n-1}, V_n, U) = det(V_1, V_2, U) = 0, \ det(V_{n-2}, V_{n-1}, U)$$
$$= b_2 > 0, \ det(V_2, V_3, U) = a_2 > 0.$$

Hence the vector U belongs to the intersection of the two planes spanned by the pairs of vectors (V_{n-1}, V_n) and (V_1, V_2) . Furthermore, U is on the positive side of the two planes spanned by the pairs of vectors (V_{n-2}, V_{n-1}) and (V_2, V_3) . Using the same central projection as in the proof of Lemma 4.3, we conclude that the n - 1-gon $\ldots V_{n-2}, V_{n-1}, U, V_2, V_3, \ldots$ in the horizontal plane is convex, see Figure 6.1. This implies the inequalities $\det(V_{i-1}, V_i, U) > 0$ for $i \neq n, 1, 2$. In view of (6.12) and the convexity of the polygon (V_i) , these inequalities imply that $\det(V_{i-1}, V_i, W) > 0$.

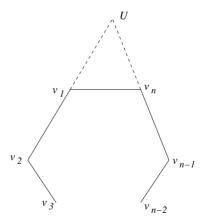


Figure 6.1. Position of point U

The following statement is a reformulation of Proposition 6.4.

COROLLARY 6.6. — An arithmetic 2-frieze pattern of width $m \ge 1$ can be obtained via one-point stabilization from a pattern of width m - 1 if and only if the second row (b_i, a_i) contains two consecutive ones.

Example 6.7. — (a) The only 10-periodic 2-frieze pattern (6.2) is obtained by stabilization from the most elementary pattern (6.1). In this sense, there are no non-trivial 10-periodic integral patterns.

(b) All the patterns of width 2, see Section 6.2, except the first and the second, are obtained by stabilization from (6.2). One therefore is left with two non-trivial 12-periodic integral patterns, namely (6.4) and (6.5).

6.4. Connected sum

We are ready to analyze the general connected summation and to prove Theorem 2.11. Let us start with an example.

Example 6.8. — Consider the connected sum of the pentagon (6.2) with the hexagon (6.4). Cut the first row of (6.2) as follows: 112 | 3211232, insert six 2's, and change the two triples of neighbors of the block of 2's as required to obtain a 16-periodic arithmetic 2-frieze pattern corresponding to an octagon:

1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
3	7	4	2	2	2	2	2	2	5	10	3	1	2	3	2
11	5	10	6	2	2	2	2	8	15	5	7	5	1	1	7
8	15	5	7	5	1	1	7	11	5	10	6	2	2	2	2
2	5	10	3	1	2	3	2	3	7	4	2	2	2	2	2
1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1

We now turn to the proof of Theorem 2.11. Let us start with the remark that the roles played by the patterns $F(a_i, b_i)$ and $F(a'_i, b'_i)$ in the definition of connected sum are the same: interchanging the two results in the same pattern.

First, we prove that the connected sum of two closed 2-frieze patterns is also closed. Let (V_i) be an *n*-gon corresponding to the difference equation (1.1), and let (U_j) be a *k*-gon corresponding to a similar equation with coefficients a'_{i}, b'_{j} . Consider a new difference equation with coefficients

$$B_{1} = b'_{1} + b_{1}, \quad A_{1} = a'_{1} + a_{1} + b'_{1}b_{2}, \quad B_{2} = b'_{2} + b_{2}, \quad A_{2} = a'_{2}, \\B_{3} = b'_{3}, \quad A_{3} = a'_{3}, \quad \dots, \quad B_{k-1} = b'_{k-1}, \quad A_{k-1} = a'_{k-1} + a_{2}, \\B_{k} = b'_{k} + b_{3} + a'_{k}a_{2}, \quad A_{k} = a'_{k} + a_{3}.$$

A solution to this equation is a sequence of points W_m in \mathbb{R}^3 ; we may choose W_{-2}, W_{-1}, W_0 to be the standard basis. The polygon (W_m) is twisted: one has $W_{m+k} = M(W_m)$ for all m. The linear transformation M is the monodromy of W_m .

Assume that the vectors V_{n-2} , V_{n-1} , V_n also constitute the standard basis (this can be always achieved by applying a transformation from SL₃).

LEMMA 6.9. — The transformation M takes V_{n-2}, V_{n-1}, V_n to V_1, V_2, V_3 .

Proof. — Let us start with some generalities about difference equations and their monodromies (see [21] for a detailed discussion). Consider the difference equation (1.1). Let us construct its solution V_i choosing the initial condition V_{-2}, V_{-1}, V_0 to be the standard basis in \mathbb{R}^3 . This is done by building a $3 \times \infty$ matrix in which each next column is a linear combination of the three previous ones, as prescribed by (1.1): (6.13)

Three consecutive columns in the matrix (6.13) are also given by the product $N_1 N_2 \dots N_r$ of 3×3 matrices of the form

(6.14)
$$N_j = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & -b_j \\ 0 & 1 & a_j \end{pmatrix}.$$

With this preparation, we can compute the monodromy M of the twisted polygon (W_m) . Thus M is given as a product of matrices as in (6.14) where all matrices, except the first two and the last two, are the same as for the polygon (U_j) . The product of the first two is: (6.15)

$$\begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & -B_1 \\ 0 & 1 & A_1 \end{pmatrix} \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & -B_2 \\ 0 & 1 & A_2 \end{pmatrix}$$
$$= \begin{pmatrix} 0 & 1 & a_2' \\ 0 & -b_1 - b_1' & -b_1a_2' + 1 - b_1'a_2' \\ 1 & a_1 + b_2b_1' + a_1' & a_1a_2' - b_2 + b_1'a_2'b_2 + a_1'a_2' - b_2' \end{pmatrix},$$

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and the product of the last two is: (6.16)

$$\begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & -B_{k-1} \\ 0 & 1 & A_{k-1} \end{pmatrix} \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & -B_k \\ 0 & 1 & A_k \end{pmatrix}$$
$$= \begin{pmatrix} 0 & 1 & a'_k + a_3 \\ 0 & -b'_{k-1} & 1 - b'_{k-1}a'_k - b'_{k-1}a_3 \\ 1 & a'_{k-1} + a_2 & a'_ka'_{k-1} + a'_{k-1}a_3 + a_2a_3 - b'_k - b_3 \end{pmatrix}$$

Next, we observe that the matrices (6.15) and (6.16) decompose as

$$\begin{pmatrix} 1 & 0 & 0 \\ -b_1 & 1 & 0 \\ a_1 & -b_2 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & a'_2 \\ 0 & -b'_1 & 1 - b'_1 a'_2 \\ 1 & a'_1 & a'_1 a'_2 - b'_2 \end{pmatrix}$$

and

$$\begin{pmatrix} 0 & 1 & a'_{k} \\ 0 & -b'_{k-1} & 1-b'_{k-1}a'_{k} \\ 1 & a'_{k-1} & a'_{k-1}a'_{k}-b'_{k} \end{pmatrix} \begin{pmatrix} 1 & a_{2} & a_{2}a_{3}-b_{3} \\ 0 & 1 & a_{3} \\ 0 & 0 & 1 \end{pmatrix}$$

respectively. Thus M is the product of k + 2 matrices, and the product of the "inner" k of them is the monodromy of the closed k-gon (U_j) , that is, the identity matrix. What remains is the product of the first and the last matrices:

$$\begin{pmatrix} 1 & 0 & 0 \\ -b_1 & 1 & 0 \\ a_1 & -b_2 & 1 \end{pmatrix} \begin{pmatrix} 1 & a_2 & a_2a_3 - b_3 \\ 0 & 1 & a_3 \\ 0 & 0 & 1 \end{pmatrix}$$
$$= \begin{pmatrix} 1 & a_2 & a_2a_3 - b_3 \\ -b_1 & -b_1a_2 + 1 & -b_1a_2a_3 + a_3 + b_1b_3 \\ a_1 & a_1a_2 - b_2 & a_1a_2a_3 - b_3a_1 - a_3b_2 + 1 \end{pmatrix}.$$

The last matrix is the fourth 3 by 3 minor in (6.13), that is, it takes V_{-2}, V_{-1}, V_0 to V_1, V_2, V_3 , as claimed.

Due to Lemma 6.9, the connected summation under consideration is the following procedure: arrange, by applying a volume preserving linear transformation, that the vertices W_{-2}, W_{-1}, W_0 of the twisted polygon (W_m) coincide with V_{n-2}, V_{n-1}, V_n , and insert k-3 vertices $W_1, W_2, \ldots, W_{k-3}$

between V_n and V_1 . By Lemma 6.9, the vertices W_{k-2}, W_{k-1}, W_k will coincide with V_1, V_2, V_3 . Thus a segment of length k + 3 of the twisted polygon (W_m) is pasted onto the polygon (V_i) over coinciding triples of vertices on both ends. We have constructed a closed (n + k - 3)-gon

 $\{W_1, W_2, \ldots, W_{k-3}, V_1, V_2, \ldots, V_n\}$

satisfying the difference equation with coefficients as described in Theorem 2.11.

Now we need to show that the connected sum of two arithmetic 2-frieze patterns is arithmetic as well. The argument is similar to the proof of Proposition 6.4. The entries of the new pattern are polynomials in the entries of the first row, hence, integers. It remains to show that they are positive. For that purpose, we show there is a positive double zig-zag and refer to the positivity of Theorem 2.9.

Consider the (n + k - 3)-gon corresponding to the connected sum, and assume that its vertices labeled 1 through n are the vertices of the n-gon V_1, \ldots, V_n . Let $V_{n+1}, \ldots, V_{n+k-3}$ be the remaining vertices. Consider the consecutive diagonals $\overline{\Delta}_{n+2}$ and $\overline{\Delta}_{n+\frac{5}{2}}$. According to formula (4.1), the entries of these two diagonals are $|V_i, V_{n-1}, V_n|$ and $|V_i, V_{i+1}, V_n|$, respectively. For $i = 1, 2, \ldots, n-3$, these determinants are positive because the points involved are vertices of a convex n-gon (V_i) .

We claim that $|V_i, V_{n-1}, V_n|$ and $|V_i, V_{i+1}, V_n|$ are also positive for $i = n+2, n+3, \ldots, n+k-3$. Indeed, reversing the roles of the *n*-gon and *k*-gon in the construction of connected sum, we may assume that the *k* consecutive points $V_{n-1}, V_n, \ldots, V_{n+k-3}, V_1$ are the vertices of a convex *k*-gon (U_i) . This yields the desired positivity.

Theorem 2.11 is proved.

Remark 6.10. — The procedure of connected sum can be understood directly from the friezes as a vertical gluing of two friezes. More precisely, the connected sum consists in choosing two consecutive columns in each frieze and connecting them on the pair 1 1. The connected two columns give two consecutive columns in the new frieze. For instance in Example 6.8, the new frieze is obtained by connecting the columns

1	1		1	1
2	2		T	T
-	-	and	2	3
2	2		-	
1	1		1	1
T	1			

of the friezes (6.4) and (6.2) respectively, one of the top of the other.

This procedure do not allow to obtain all the arithmetic friezes of a given width. However, there exists a more general procedure, for which the gluing is not necessarily on a pair of ones, that allows to construct more friezes. This procedure will be described in a separate work.

6.5. Examples of infinite arithmetic 2-frieze patterns

In this section, we give examples of infinite arithmetic 2-frieze patterns bounded above by a row of 1's and on the left by a double zig-zag of 1's.

Example 6.11. — In the following 2-frieze dots mean that the entries in the row stabilize.

1	1	1	1	1	1	1	1	1	1	1
	1	1	2	3	3					
		1	1	3	6	6				
			1	1	4	10	10			
				1	1	5	15	15		
					1	1	6	21	21	

The first two non-trivial South-East diagonals consist of consecutive positive integers and of consecutive binomial coefficients.

Example 6.12. — In the next example, we choose two vertical arrays of 1's as the double zig-zag. As before, dots mean stabilization.

1	1	1	1	1	1	1	1	1	1	1	1
1	1	2	4	5	5						
1	1	2	6	15	20	20					
1	1	2	6	21	56	76	76				
1	1	2	6	21	77	209	285	285			
1	1	2	6	21	77	286	780	1065	1065		
1	1	2	6	21	77	286	1066	2911	3976	3976	

The pattern is clear: all rows and all columns stabilize; the stabilization starts along two parallel South-East diagonals, and there is one other diagonal between the two, consisting of the numbers 1, 4, 15, 56, 209, 780, 2911, ... The respective numbers in the two stabilizing diagonals differ by 1. It follows that the numbers on the diagonal between the two are the differences between the consecutive numbers on either of the stabilizing diagonals.

The numbers d_n on the upper stabilizing diagonal 1, 5, 20, 76, 285, 1065, 3976, ... satisfy the relation

$$d_{n+1} = \frac{d_n(d_n - 1)}{d_{n-1}}$$

that follows from the 2-frieze relation. One learns from Sloane's Encyclopedia [29] that these numbers also satisfy a linear recurrence

$$d_{n+1} = 4d_n - d_{n-1} + 1,$$

which can be easily proved by induction on n. Solving the above linear recurrence is standard.

Example 6.13. — In the next example, the double zig-zag of 1's indeed looks like a zig-zag:

1	1	1	1	1	1	1	1	1	1	1
1	1	2	3	4	6	5	6	5	6	5
	1	1	5	14	14	31	19	31	19	31
1	1	2	3	14	70	47	157	66	157	66
	1	1	5	14	42	353	155	793	221	793
1	1	2	3	14	70	131	1782	507	4004	728
	1	1	5	14	42	353	417	8997	1652	20216
1	1	2	3	14	70	131	1782	1341	45425	5373

In this 2-frieze pattern, the horizontal and vertical stabilization is different from the previous examples: each row and each column is eventually 2periodic. There are five different South-East diagonals. Interestingly, they are all in Sloane's Encyclopedia [29]. We list them here, along with their Sloane's numbers:

$1, 2, 5, 14, 42, 131, 417, \ldots$	A080937;
$1, 3, 14, 70, 353, 1782, 8997, \ldots$	A038213;
$1, 4, 14, 47, 155, 507, 1652, \ldots$	A094789;
$1, 6, 31, 157, 793, 4004, 20216, \ldots$	A038223;
$1, 5, 19, 66, 221, 728, 2380, \ldots$	A005021.

7. Appendix: Frieze patterns of Coxeter-Conway, difference equations, polygons, and the moduli space $\mathcal{M}_{0,n}$

In this appendix we review the classical case of Coxeter-Conway frieze patterns in their relation with second order difference equations, polygons in the plane and in the projective line, and the configuration space of the projective line. We refer to [6, 5] for information on frieze patterns; see also [19] and [28] for details concerning some of our remarks.⁽¹⁾

As before, we consider the space C_n of polygons in \mathbb{P}^1 , that is, *n*-tuples of cyclically ordered points (v_i) such that $v_i \neq v_{i+1}$ for all *i*. Polygons in \mathbb{P}^1 are considered modulo projective equivalence. Let \tilde{C}_n be the space of origin symmetric 2*n*-gons (V_i) in the plane satisfying the determinant condition $|V_i, V_{i+1}| = 1$ for all *i*. Polygons in the plane are considered modulo SL₂equivalence.

Another relevant space is the moduli space $\mathcal{M}_{0,n}$ of stable curves of genus zero with *n* distinct marked points, defined as the space of ordered *n*-tuples of points in \mathbb{CP}^1 modulo projective equivalence:

$$\mathcal{M}_{0,n} = \left\{ (v_1, \dots, v_n) \in \mathbb{CP}^1 \mid v_i \neq v_j, \ i < j \right\} / \mathrm{PSL}(2, \mathbb{C}).$$

The space $\mathcal{M}_{0,n}$ is classical, and it continues to play an important role in the current research (see, e.g., [1]). We show in this Appendix that $\mathcal{M}_{0,n}$ is an open dense subset of a cluster manifold, provided n is odd (this condition is a 1-dimensional counterpart to the condition that n is not a multiple of 3 that we encountered earlier). This cluster structure is closely related to that on the Teichmuller space, see [11], but it is more difficult to construct. We did not find an appropriate reference in the literature [4]. We use the classical Coxeter-Conway friezes (with coefficients in \mathbb{C}). The space $\mathcal{M}_{0,n}$ coincides with the subset of friezes such that all the entries are different from 0. This observation is rather simple but we did not find it explicitly in the literature. Two immediate consequences are as follows.

- (1) One obtains several natural coordinate systems on $\mathcal{M}_{0,n}$, one of which is compatible with a cluster structure. More precisely, $\mathcal{M}_{0,n}$ is a smooth cluster manifold of type A_{n-3} .
- (2) Many objects related to $\mathcal{M}_{0,n}$, such as discrete versions of KdV, etc., can be formulated in terms of Coxeter-Conway friezes.

Space \hat{C}_n , difference equations and Coxeter-Conway friezes. We consider the following, infinite and row *n*-periodic, frieze pattern:

⁽¹⁾ We strongly recommend R. Schwartz's applet http://www.math.brown.edu/~res/ Java/Frieze/Main.html

where $C_i(=C_{i+n})$ are formal variables and where all the entries are polynomials determined by the first row via the frieze rule AD - BC = 1, for each elementary square:

For instance, the entries in the next row are: $C_i C_{i+1} - 1$, etc. As before, a numerical frieze $F(c_i) = F(C_i)|_{C_i = c_i}$ is obtained by evaluation.

Remark 7.1. — In order to give a correct definition of space of friezes, one has to adapt the technique of algebraic friezes and treat C_i as formal variables. Otherwise, the frieze rule does not suffice to determine the entries of the pattern (if too many of c_i vanish), cf. Section 2.1.

An *n*-periodic frieze pattern is closed if it contains a row of 1's (followed by a row of 0's).

•••		1		1		1		1		• • •
	c_i		c_{i+1}		c_{i+2}		c_{i+3}		c_{i+4}	
		1		1		1		1		

The width (the number of non-trivial rows) of the above frieze pattern is equal to n-3, see [5].

One associates a second order difference equation with periodic coefficients with a closed frieze pattern:

(7.1)
$$V_{i+1} = c_i V_i - V_{i-1}; \quad c_{i+n} = c_i$$

We understand its solutions (V_i) as vectors in the plane satisfying the relation $|V_i, V_{i+1}| = 1$. Equation (7.1) determines the polygon (V_i) uniquely, up to SL₂-action.

We label $(v_{i,j})_{i,j\in\mathbb{Z}}$ the entries of the frieze, such that $v_{i,i} = c_i$, and according to the scheme:

$$v_{i,j}$$

$$v_{i,j-1}$$

$$v_{i+1,j-1}$$

Analogs of Proposition 3.1, Proposition 3.2 and Lemma 4.1 hold true providing explicit formulæ. Namely, one has:

$$v_{i,j} = |V_i, V_j|,$$

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and

(7.2)
$$v_{i,j} = \begin{vmatrix} c_j & 1 \\ 1 & c_{j+1} & 1 \\ & \ddots & \ddots & \ddots \\ & & 1 & c_{i-1} & 1 \\ & & & 1 & c_i \end{vmatrix}$$

As a consequence of these formulæ, $V_{i+n} = -V_i$ for all *i*, that is, the monodromy of equation (7.1) is $-\text{Id} \in \text{SL}_2$. This provides the equivalence between closed frieze patterns and the space of polygons $\tilde{\mathcal{C}}_n$.

Polygons in the plane and in the projective line. As before, one has a natural projection $\tilde{\mathcal{C}}_n \to \mathcal{C}_n$ from \mathbb{R}^2 to \mathbb{RP}^1 . If *n* is odd then this is a bijection, cf. Section 4.4. This provides an equivalence between projective equivalence classes of *n*-gons in \mathbb{CP}^1 and SL_2 -equivalence classes of origin symmetric 2n-gons \mathbb{C}^2 , subject to the unit determinant condition.

Note that, over reals, there is an additional obstruction to lifting a polygon from \mathbb{RP}^1 to \mathbb{R}^2 . Let *n* be odd and (v_i) be a polygon in the projective line. Let $V_i \in \mathbb{R}^2$ be some lifting of points v_i . For the system of equations

$$t_i t_{i+1} = 1/|V_i, V_{i+1}|, i = 1, \dots, n-1, t_1 t_n = 1/|V_1, V_n|$$

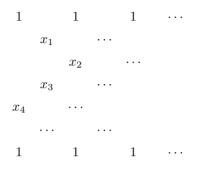
to have a real solution, one needs $\prod_{i=1}^{n} |V_i, V_{i+1}| > 0$. If this condition holds then t_i is uniquely determined, up to a common sign; otherwise there is a lifting satisfying the opposite condition $|V_i, V_{i+1}| = -1$ for all *i*.

Cluster coordinates. The space of friezes has another natural coordinate system apart from c_i . Unlike the coordinates c_i that satisfy three very non-trivial equations given by the condition that the frieze pattern is closed, the new coordinates are free. These three conditions are as follows:

$$v_{0,n-1} = 1, \qquad v_{-1,n-1} = 0, \qquad v_{0,n} = 0$$

where $v_{i,j}$ are given by the determinants (7.2) (the fourth condition, $v_{-1,n} = -1$, follows from the fact that the monodromy is area-preserving).

An arbitrary zig-zag (i.e. piecewise linear path from top to bottom such that each segment goes either down-right or down-left) filled by the variables x_1, \ldots, x_{n-3}



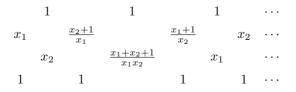
determines the rest of the pattern. The subalgebra of $\mathbb{C}(x_1, \ldots, x_{n-3})$ generated by all the rational functions arising in the pattern is the cluster algebra associated to the quiver of type A_{n-3} , see [3]. The initial zig-zag (x_1, \ldots, x_{n-3}) forms the initial cluster, and to different zig-zags correspond different clusters. However, some clusters are not obtained as zig-zags in the pattern. In type A_{n-3} there is a correspondence between clusters and triangulations of a *n*-gon [12] (see also [26]). The clusters which are not zig-zags in the frieze correspond to triangulations containing inner triangles (i.e. triangles built on three diagonals).

One then constructs a smooth cluster manifold gluing together the tori $(\mathbb{C}^*)^{n-3}$ according to the coordinate changes defined by consecutive mutations.

PROPOSITION 7.2. — The space $\mathcal{M}_{0,n}$ is a smooth submanifold of the constructed cluster manifold.

Proof. — The fact that $v_i \neq v_j$ for all $1 \leq i < j \leq n$ in the definition of $\mathcal{M}_{0,n}$, is equivalent to the fact that all the entries of the corresponding frieze $v_{i,j} \neq 0$. Therefore, the points of $\mathcal{M}_{0,n}$ are non-singular in any chart. \Box

Example 7.3. — If n = 5, then one has



which correspond to the A_2 -case, quite similarly to Example 5.2.

The cluster structure on $\mathcal{M}_{0,n}$, with n = 2m + 1, that we have just constructed, coincides with that communicated to us by F. Chapoton [4].

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