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# Extending piecewise polynomial functions in two variables 

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#### Abstract

We study the extensibility of piecewise polynomial functions defined on closed subsets of $\mathbb{R}^{2}$ to all of $\mathbb{R}^{2}$. The compact subsets of $\mathbb{R}^{2}$ on which every piecewise polynomial function is extensible to $\mathbb{R}^{2}$ can be characterized in terms of local quasi-convexity if they are definable in an o-minimal expansion of $\mathbb{R}$. Even the noncompact closed definable subsets can be characterized if semialgebraic function germs at infinity are dense in the Hardy field of definable germs. We also present a piecewise polynomial function defined on a compact, convex, but undefinable subset of $\mathbb{R}^{2}$ which is not extensible to $\mathbb{R}^{2}$.

Résumé. - Nous étudions le prolongement des fonctions polynômes par morceaux définies sur des sous-ensembles fermés de $\mathbb{R}^{2}$ à tout $\mathbb{R}^{2}$. Les sous-ensembles compacts de $\mathbb{R}^{2}$ sur lesquels chaque fonction polynôme par morceaux est prolongeable à $\mathbb{R}^{2}$ peuvent être caractérisés en termes de quasi-convexité locale si ils sont définissables dans une expansion o-minimale de $\mathbb{R}$. Même les sous-ensembles non compacts fermés définissables peuvent être caractérisés si les germes de fonctions semialgébriques à l'infini sont denses dans le corps de Hardy des germes définissables. Nous présentons également une fonction polynôme par morceaux définie sur un sous-ensemble compact, convexe, mais indéfinissable de $\mathbb{R}^{2}$, et qui n'est pas prolongeable à $\mathbb{R}^{2}$.


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## 1. Introduction

Let $A \subset \mathbb{R}^{n}$. A piecewise polynomial function is a continuous function $f: A \rightarrow \mathbb{R}$ for which there exist finitely many polynomials $p_{1}, \ldots, p_{k}$ in the polynomial ring $\mathbb{R}\left[X_{1}, \ldots, X_{n}\right]$ such that for every $a \in A, f(a)=p_{i}(a)$ for some $i$. In short, we say that $f$ is a $p w p$ function. We assume the reader is familiar with basic semialgebraic geometry, as covered in [1, Chapitre 2] for example. For clarity we note the following:

Lemma 1.1. - Let $A \subset \mathbb{R}^{n}$ be a semialgebraic set. Then every pwp function $f: A \rightarrow \mathbb{R}$ is semialgebraic.

Proof. - Let $p_{1}, \ldots, p_{k} \in \mathbb{R}\left[X_{1}, \ldots, X_{n}\right]$ be the polynomials appearing in the description of $f: A \rightarrow \mathbb{R}$. If $k=1$ the result is trivial, so we assume $k \geqslant 2$. By induction on $k$ the restriction of $f$ to $\left\{p_{i}=p_{j}\right\} \cap A$ is semialgebraic, for each $1 \leqslant i<j \leqslant k$, so $f$ restricted to the set

$$
X=\cup_{1 \leqslant i<j \leqslant k}\left\{p_{i}=p_{j}\right\} \cap A
$$

is semialgebraic. The semialgebraic set $A \backslash X$ has just finitely many connected components $U_{1}, \ldots, U_{m}$ and, for each $1 \leqslant \ell \leqslant m, U_{\ell}$ is semialgebraic [1, Théorème 2.4.5]. Also $U_{\ell}$ is the disjoint union of the relatively closed sets $\left\{f=p_{i}\right\} \cap U_{\ell}, i=1, \ldots, k$. Thus $f=p_{i}$ on $U_{\ell}$ for some unique $i$, so $f$ restricted to $U_{\ell}$ is semialgebraic. Since $U_{1} \cup \ldots \cup U_{m} \cup X=A$, we are done.

It follows from Lemma 1.1 that if $A$ is semialgebraic then the definition of $p w p$ function $f: A \rightarrow \mathbb{R}$ coincides with the standard definition $[2,10,11]$ which a priori requires each set $\left\{f=p_{i}\right\}$ to be semialgebraic. The definition we have adopted, however, allows us to study pwp functions not just on semialgebraic sets but also on larger classes of subsets of $\mathbb{R}^{n}$. Here, we are mainly interested in subsets of $\mathbb{R}^{2}$ that are definable in an o-minimal expansion $\mathcal{M}$ of the real field, as in this case we always obtain extensibility for compact convex definable sets, while this is not true anymore without the definability assumption. Here and in the following, definable always means definable in $\mathcal{M}$ with parameters of $\mathbb{R}$. See [5] for an introduction to o-minimal structures.

Our studies are closely related to the Pierce-Birkhoff conjecture, which asserts that every $p w p$ function on $\mathbb{R}^{n}$ is sup / inf definable from polynomials. Actually, if $f$ is sup / inf definable on $A$, then the extensibility of $f$ as $p w p$ function is trivial.

A proof of the Pierce-Birkhoff conjecture for functions in two variables was sketched by Mahé in [11]; see [12] for a more detailed demonstration.

The Pierce-Birkhoff conjecture is still an open question for $p w p$ functions of three and more variables. Note that pwp functions can be studied over real closed fields and ordered fields; see, for example, [2, 8, 10, 13, 15]. However, our discussions require at least an Archimedean real closed field, which can always be imbedded into $\mathbb{R}$. Here we only treat the field of real numbers.

Mahé presented a semialgebraic $p w p$ function of two variables that cannot be extended to $\mathbb{R}^{2}$ as $p w p$ function, in [11, Remarks]. This example motivates the following question:

What are the subsets of $\mathbb{R}^{2}$ for which every pwp function is extensible?
We give an answer to this question for sets that are definable in an ominimal expansion of the real field. The definable compact sets of $\mathbb{R}^{2}$ for which the answer to the above question is affirmative are precisely those that are locally quasi-convex. Let us make this notion precise.

We denote by $\|\cdot\|$ the Euclidean norm on $\mathbb{R}^{n}$, for $n>0$. For $a \in \mathbb{R}^{n}$ and $r>0$ we denote by $B_{r}(a)$ the open ball with radius $r$ and center $a$.

Definition 1.2. - $A$ set $A$ is said to be locally quasi-convex at a point $a \in A$ if there exists an $\varepsilon>0$ and an $L>0$ such that all points $\xi, \eta \in$ $B_{\varepsilon}(a) \cap A$ can be joined by a rectifiable path $\gamma$ in $B_{\varepsilon}(a) \cap A$ of length less than or equal to $L\|\xi-\eta\|$. We will say $A$ is locally quasi-convex if $A$ is locally quasi-convex at each $a \in A$.

For $L=1$ we obtain the locally convex sets, so every locally convex set is locally quasi-convex. The first main result of the present paper gives a complete characterization of the compact definable subsets on which every $p w p$ functions is extensible. We shall prove the following theorem.

Theorem 1.3. - Let $A \subset \mathbb{R}^{2}$ be a compact definable set. Then every pwp function on $A$ can be extended to a pwp function on $\mathbb{R}^{2}$ if and only if $A$ is locally quasi-convex.

We do not know whether there exists any undefinable, compact, locally quasi-convex set $A$ for which every $p w p$ function on $A$ can still be extended to $\mathbb{R}^{2}$. However, we will present a $p w p$ function defined on an undefinable compact, convex subset of $\mathbb{R}^{2}$ that is not extensible; see Example 3.9.

To obtain extensibility for non-compact definable closed sets we have to restrict ourselves to a small class of polynomially bounded o-minimal structures, that is, every unary definable germ at infinity is ultimately bounded by some polynomial. Let $\mathcal{H}(\mathbb{R})$ and $\mathcal{H}(\mathcal{M})$ denote the Hardy field of semialgebraic and definable unary function germs at $+\infty$, respectively. Let $\mathcal{H}(\mathcal{M})$
be endowed with the topology induced by its ordering. Then the characterization of o-minimal structures for which every $p w p$ function on a locally quasi-convex closed definable subset of $\mathbb{R}^{2}$ is extensible reads as follows.

ThEOREM 1.4. - Let $\mathcal{H}(\mathbb{R})$ be dense in $\mathcal{H}(\mathcal{M})$. Let $A \subset \mathbb{R}^{2}$ be closed and definable. Then every pwp function on $A$ can be extended to a pwp function on $\mathbb{R}^{2}$ if and only if $A$ is locally quasi-convex.

Examples of such o-minimal structures are the structure $\mathbb{R}_{\text {an }}$ of restricted analytic functions, cf. [4], and the structures generated in [14]; see [7, Proposition 2.3]. Theorem 1.4 is sharp in the sense that if $\mathcal{H}(\mathbb{R})$ is not dense in $\mathcal{H}(\mathcal{M})$, there exists always a $p w p$ function defined on a locally quasi-convex closed definable subset of $\mathbb{R}^{2}$ which is not extensible; see section 4.3.

In section 2 we note that $p w p$ functions on $\mathbb{R}^{2}$ are locally Lipschitz continuous. In section 3 we study properties of definable, locally quasi-convex sets, and we prove the "only if" direction of Theorem 1.3 and 1.4. In section 4 we prove the "if" direction of Theorem 1.3 and Theorem 1.4.

## 2. Local Lipschitz continuity

Before we give some examples of $p w p$ functions, we note that sums, products and compositions of $p w p$ functions are again $p w p$ functions. Of course, polynomials are $p w p$ functions, but also the absolute value function is $p w p$. Moreover, the infimum and the supremum of two $p w p$ functions are also $p w p$.

We recall the definition of a locally Lipschitz continuous function.

Definition 2.1 Let $A \subset \mathbb{R}^{n}$. A function $f: A \rightarrow \mathbb{R}$ is called locally Lipschitz continuous if for every $a \in A$ there exists an $\varepsilon>0$ and an $L>0$ such that

$$
\|f(x)-f(y)\| \leqslant L\|x-y\|
$$

for all $x, y \in B_{\varepsilon}(a) \cap A$.

An analytic property of $p w p$ functions is the fact that they are locally Lipschitz continuous. We state this in the following proposition, which is a version of $[3$, Theorem $0.1(\mathrm{c})]$. Let $\nabla$ denote the gradient operator.

Proposition 2.2. - Let $A \subset \mathbb{R}^{n}$ be convex. Then every pwp function $f: A \rightarrow \mathbb{R}$ is locally Lipschitz continuous.

Proof. - Let $x \in A, \varepsilon>0$, and let $f$ be defined by the polynomials $p_{1}, \ldots, p_{r}$. Then,

$$
M:=\sup \left\{\left\|\nabla p_{i}(y)\right\|: y \in B_{\varepsilon}(x), i=1, \ldots, r\right\}
$$

is a real number. Moreover, for every $y, z \in B_{\varepsilon}(x) \cap A$, the function $f$ is piecewise differentiable along the segment connecting $y$ and $z$. Hence, by the Mean Value Theorem,

$$
\|f(z)-f(y)\| \leqslant M\|y-z\| .
$$

## 3. Locally quasi-convex sets

We fix an o-minimal expansion $\mathcal{M}$ of the real field. Definable always means definable in $\mathcal{M}$ with parameters from $\mathbb{R}$.

For a set $A \subset \mathbb{R}^{n}$ we denote by $\bar{A}, A^{o}$, and $\partial A$, the closure, interior and boundary of $A$, respectively.

### 3.1. Stratification

Definable sets can be partitioned into finitely many sets of a suitable form. One says that such partition is a stratification, and calls the sets strata, if for any two sets $C$ and $D$ of the partition, we have that $C \subset \bar{D}$ or $D \subset \bar{C}$ or $C \cap \bar{D}=\emptyset$ or $\bar{C} \cap D=\emptyset$. Here we are only interested in stratification of boundaries of definable subsets of $\mathbb{R}^{2}$. Lipschitz cells; these are sets, that are either a single point or, after some suitable rotation, the graph $\Gamma(h)$ of a definable Lipschitz continuous $\mathcal{C}^{1}$ function $h: I \rightarrow \mathbb{R}$ where $I$ is an open interval; see [6] or [9].

If, furthermore, for given definable sets $A_{1}, \ldots, A_{k} \subset \mathbb{R}^{2}$, we have that for each Lipschitz cell $C$ and each $1 \leqslant i \leqslant k$ either $C \subset A_{i}$ or $C \cap A_{i}=\emptyset$, we say that the stratification is compatible with the sets $A_{1}, \ldots, A_{k}$. Altogether we have the following proposition.

Proposition 3.1 ([6] Theorem 1.4 or [9]). - Let $A, A_{1}, \ldots, A_{k} \subset \mathbb{R}^{2}$ be definable sets, and let $f: \partial A \rightarrow \mathbb{R}$ be a definable function. Then there is a stratification of $\partial A$ into Lipschitz cells $S_{1}, \ldots, S_{m}$ which is compatible with the sets $A_{1}, \ldots, A_{k}$ such that $f$ restricted to $S_{j}$ is a $\mathcal{C}^{1}$ function for $j=1, \ldots, m$.

### 3.2. Angles

Let $a$ be a boundary point of a definable set $A \subseteq \mathbb{R}^{2}$. If $a$ is an isolated point of $A$ there is, by definition, just one outside angle at $a$ (which is equal to $2 \pi$ ) and no inside angle. If $a$ is not an isolated point of $A$ then the germ of the boundary of $A$ at $a$ is a union of finitely many definable half-branches at $a$, say $\Gamma_{1}, \ldots, \Gamma_{m}, m \geqslant 1$ listed in counterclockwise order. Set $\Gamma_{m+1}=\Gamma_{1}$. For $1 \leqslant i \leqslant m$ the angle between $\Gamma_{i}$ and $\Gamma_{i+1}$ is defined to be the angle between the corresponding half-tangents at $a$, measured counterclockwise. The germ at $a$ of the open region between $\Gamma_{i}$ and $\Gamma_{i+1}$ is either entirely outside of $A$ or entirely inside of $A$. In the former case the angle is called an outside angle at $a$; in the latter case it is called an inside angle at $a$.

### 3.3. Locally quasi-convex definable sets

The local quasi-convexity of a definable subset of $\mathbb{R}^{2}$ can be graphically described as follows.

At each boundary point of a closed definable subset of $\mathbb{R}^{2}$ there are finitely many well defined outside angles. For example, the set $A=\{(x, y)$ : $\left.x \geqslant 0,|y|=x^{2}\right\}$ has two outside angles at $(0,0)$, one is equal to 0 the other is $2 \pi$. But this set is not locally quasi-convex at the origin. This is easily seen by the following lemma.

Lemma 3.2. - $A$ closed definable set $A \subset \mathbb{R}^{2}$ is locally quasi-convex at $a \in \partial A$ if and only if each outside angle at $a$ is strictly positive.

Proof. - $(\Rightarrow)$ Let $a \in \partial A$ and assume that there is a vanishing outside angle at $a$. The dimension of $\partial A$ is at most 1 so that the boundary at $a$ is locally given by the union of the graphs of continuous function germs of one independent variable. After some rotation and translation, we may describe the part of the boundary at $a=(0,0)$ which causes the vanishing angle by two continuous definable function germs $f, g:[0, \delta) \rightarrow \mathbb{R}$ such that $f(0)=g(0)$. The half-tangents of $f$ and $g$ at 0 have the same slope, so

$$
\begin{equation*}
f(x)-g(x) \text { is } o(x) \text { as } x \searrow 0 . \tag{3.1}
\end{equation*}
$$

By choosing $\delta$ small enough, we may assume that $f(x)>g(x)$ for $0<x<\delta$, that both functions $f$ and $g$ are continuously differentiable in $(0, \delta)$, and that

$$
A \cap\{(x, y): 0<x<\delta, g(x)<y<f(x)\}=\emptyset
$$

Assume now that $A$ is locally quasi-convex at 0 with constant $L>0$. Take the points $\xi:=(x, f(x))$ and $\eta:=(x, g(x))$, where $0<x<\delta / 2$ is small
enough. Then

$$
\|\xi-\eta\|=f(x)-g(x)
$$

Any path $\gamma$ of minimal length in $A$ connecting $\xi$ and $\eta$ passes through $a$. Hence

$$
\text { length }(\gamma) \geqslant\|\xi-a\|+\|a-\eta\| \geqslant 2 x
$$

Thus

$$
2 x \leqslant \operatorname{length}(\gamma) \leqslant L\|\xi-\eta\|=L(f(x)-g(x))
$$

which contradicts (3.1).
$(\Leftarrow)$ Let $a \in \partial A$. Assume the outside angles at $a$ are strictly positive. Fix a constant $L \geqslant 1$ so large that $L>\csc \left(\frac{\theta}{2}\right)$ for each outside angle $\theta$ satisfying $\theta \leqslant \pi$. Then, for $\epsilon>0$ sufficiently close to zero, $\xi, \eta \in B_{\epsilon}(a) \cap A$ can be joined by a rectifiable path $\gamma$ in $B_{\epsilon}(a) \cap A$ with length $(\gamma) \leqslant L\|\xi-\eta\|$. It is easy to construct $\gamma$ : If the whole line segment joining $\xi$ and $\eta$ belongs to $A$, take $\gamma$ to be this line segment. Otherwise, take $\xi^{\prime}$ (resp., $\eta^{\prime}$ ) to be the point on the line segment joining $\xi$ and $\eta$ intersected with $\partial A$ closest to $\xi$ (resp., $\eta$ ) and take $\gamma$ to be the line segment joining $\xi$ and $\xi^{\prime}$ followed by the arc of $\partial A$ joining $\xi^{\prime}$ and $a$ followed by the arc of $\partial A$ joining $a$ and $\eta^{\prime}$ followed by the line segment joining $\eta^{\prime}$ and $\eta$. It remains to verify that length $(\gamma) \leqslant L\|\xi-\eta\|$, for $\epsilon>0$ sufficiently small. It suffices to consider the case where some part of the line segment joining $\xi$ and $\eta$ is not in $A$. One may also reduce further to the case where $\xi^{\prime}=\xi$ and $\eta^{\prime}=\eta$. In this case the result follows by applying the following variant of the triangle inequality.

Proposition 3.3. - If $a, b$ and $c$ are sides of a triangle, then $\frac{a+b}{c} \leqslant$ $\csc \left(\frac{\theta}{2}\right)$, where $\theta$ denotes the angle opposite the side $c$.

Remark 3.4. - The standard triangle inequality asserts that $1 \leqslant \frac{a+b}{c}$.
Proof. - We have

$$
\begin{aligned}
\frac{c^{2}}{(a+b)^{2}} & =\frac{a^{2}+b^{2}-2 a b \cos \theta}{(a+b)^{2}}=1-\frac{2 a b}{(a+b)^{2}}(1+\cos \theta) \\
& \geqslant 1-\frac{1+\cos \theta}{2}=\frac{1-\cos \theta}{2}=\sin ^{2}\left(\frac{\theta}{2}\right)
\end{aligned}
$$

Here we are using the law of cosines $c^{2}=a^{2}+b^{2}-2 a b \cos \theta$, the half-angle formula $\frac{1-\cos \theta}{2}=\sin ^{2}\left(\frac{\theta}{2}\right)$, and the standard inequality $\sqrt{a b} \leqslant \frac{a+b}{2}$ relating the geometric mean and the arithmetic mean.

The union of locally quasi-convex sets is not necessarily quasi-convex.

Example 3.5. - Both the graph of the standard parabola and the $x$-axis in $\mathbb{R}^{2}$ are locally quasi-convex sets, but their union is not quasi-convex at the origin, as one of the outside angles at the origin vanishes.

Lemma 3.2 implies that finite intersections of locally quasi-convex definable subsets of $\mathbb{R}^{2}$ are again locally quasi-convex. This is false without the sets being definable in some o-minimal structure expanding $\mathbb{R}$.

Example 3.6. - Let $A \subset \mathbb{R}^{2}$ be the union of the sets $[0,1] \times\{0\},\{0\} \times$ $[0,1]$ and the line segments connecting the points $\left(2^{-n}, 0\right)$ and $\left(0,2^{-n}\right)$ for $n=0,1, \ldots, \infty$. So $A$ is compact and connected. Moreover, this set is locally quasi-convex. However, the intersection of $A$ and the diagonal $\{x=y\}$ is the set $\left\{\left(2^{-n-1}, 2^{-n-1}\right) ; n \in \mathbb{N}\right\} \cup\{(0,0)\}$, which is not locally quasi-convex at $(0,0)$.

For $n \geqslant 3$, the intersection of locally quasi-convex definable subsets of $\mathbb{R}^{n}$ is not necessarily again locally quasi-convex (though, this does hold, for all $n \geqslant 1$, if locally quasi-convex is replaced by locally convex.)

Example 3.7. - Let $A$ be the solution of $z^{4}=x^{2}+y^{2}, z \geqslant 0$, then $A$ is locally quasi-convex at every point, in particular at the origin. But the intersection of $A$ with the $z x$-plane is the graph of $z=\sqrt{|x|}$ which is not locally quasi-convex at the origin, because one outside angle vanishes.

For two continuous function $f, g: U \rightarrow \mathbb{R}$ with $f<g$ on $U$ we set

$$
(f, g)_{U}:=\{(x, y): x \in U, f(x)<y<g(x)\} .
$$

Local quasi-convexity is a necessary condition to obtain extensibility.
Proposition 3.8. - Let $A \subset \mathbb{R}^{2}$ be a closed definable set that is not locally quasi-convex at some point $a \in A$. Then there exists a pwp function $F$ on $A$ that is not extensible to $\mathbb{R}^{2}$ as a pwp function.

Proof. - We may assume that $a=(0,0)$. The point $a$ is obviously a non-isolated boundary point. Since $A$ is not locally quasi-convex at $a$, there is a vanishing outside angle at $a$. Therefore, we may assume that after some rotation a part of $\partial A$ is given by the graphs of two definable continuous functions $f, g:[0, \delta) \rightarrow \mathbb{R}$ such that

$$
\begin{aligned}
& f(0)=g(0)=0 \\
& g(x)-f(x) \text { is } o(x) \text { for } x \searrow 0, \\
& f<g \text { on }(0, \delta) \\
& (f, g)_{(0, \delta)} \cap A=\emptyset
\end{aligned}
$$

Define $F: A \rightarrow \mathbb{R}$ as follows. For $(x, y) \in A$ such that $x \leqslant 0$ or $x \geqslant \delta$, or $0<x<\delta$ and $y \leqslant f(x)$, let $F(x, y)=0$. For $0<x<\delta$ and $y \geqslant g(x)$, let $F(x, y):=\min (x, \delta-x)$. Then $F$ is a $p w p$ function on $A$. For $0 \leqslant x \leqslant \delta / 2$,

$$
|F(x, g(x))-F(x, f(x))|=x
$$

while

$$
\|(x, g(x))-(x, f(x))\| \text { is } o(x) \text { as } x \searrow 0 .
$$

Hence $F$ is not locally Lipschitz continuous at $a$. Therefore Proposition 2.2 implies that $F$ is not extensible to $\mathbb{R}^{2}$ as a $p w p$ function.

### 3.4. A counterexample

It is easy to construct a $p w p$ function on a locally quasi-convex closed set with infinitely many connected components that is not extensible. Such a set is never definable in any o-minimal structure and is also not compact. Take for example $A=\mathbb{N} \times\{0\}$ and $f: A \rightarrow \mathbb{R}$, with $f(x, 0)=1$ if $x$ is odd, and $f(x, 0)=0$ if $x$ is even.

One can also define a $p w p$ function on the compact set $A$ of Example 3.6 which is not extensible. Let $f: A \rightarrow \mathbb{R}$ be defined as follows: $f(x, y)=0$ if $(x, y)$ belongs to $[0,1] \times\{0\},\{0\} \times[0,1]$ or the line segments connecting the points $\left(2^{-n}, 0\right)$ and $\left(0,2^{-n}\right)$ for odd $n$, and let $f(x, y)=x y$ otherwise. However, the set $A$ has no well-defined outside angles at the origin.

The question arises whether the restriction to o-minimal sets in Theorem 1.3 is necessary or not.

It seems that the o-minimality is almost necessary to obtain extensibility of $p w p$ functions. Note that every convex set is locally quasi-convex with constant $L=1$. Next we present an example of a $p w p$ function defined on an undefinable, compact, convex set that is not extensible.

Example 3.9. - The function $h:[0,1] \rightarrow \mathbb{R}$,

$$
h(x)= \begin{cases}x^{6} \sin \left(x^{-1}\right)+x^{6}+x^{5}+x^{4} & \text { if } x>0 \\ 0 & \text { if } x=0\end{cases}
$$

is strictly increasing and convex. Thus, the set

$$
A=\{(x, y) ; 0 \leqslant x \leqslant 1, h(x) \leqslant y \leqslant h(1)\}
$$

is a compact convex set, and even all outside angles are well defined. Define the $p w p$ function $f$ on $A$ as follows: For $(x, y) \in A$ with

$$
\frac{1}{4 k \pi+2 \pi} \leqslant x \leqslant \frac{1}{4 k \pi+\pi} \text { for some integer } k \geqslant 0 \text { and } y \leqslant x^{6}+x^{5}+x^{4}
$$

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let

$$
f(x, y)=x^{6}+x^{5}+x^{4}-y
$$

Otherwise, let $f(x, y)=0$. Hence $f$ is a $p w p$ function on $A$.
Let us assume now that there is a pwp function $F: \mathbb{R}^{2} \rightarrow \mathbb{R}$ with $F=f$ on $A$. Then $F$ is semialgebraic. Consider the function $g: \mathbb{R} \rightarrow \mathbb{R}$ defined by

$$
g(x):=F\left(x, x^{5}+x^{4}\right) .
$$

Then $g$ vanishes for

$$
x=\left(4 k \pi+\frac{7}{2} \pi\right)^{-1}, \quad k \in \mathbb{N}
$$

and $g$ is positive for

$$
x=\left(4 k \pi+\frac{3}{2} \pi\right)^{-1}, \quad k \in \mathbb{N}
$$

So the function $g$ cannot be semialgebraic, which contradicts the assumption.

Remark 3.10. - The function $f$ in the previous example is actually Lipschitz continuous; however, the domain is not definable in any o-minimal structure. We do not know whether Lipschitz continuity of a pwp function on a compact definable set implies extensibility, and leave this question as an open problem.

## 4. Proof of the Theorems

### 4.1. Preliminary Lemma

We agree to the following notation. For two continuous function $f, g$ : $U \rightarrow \mathbb{R}$ with $f<g$ on $U$ we set

$$
\begin{aligned}
{[f, g]_{U} } & :=\{(x, y) ; x \in U, f(x) \leqslant y \leqslant g(x)\} \\
(f)_{U} & :=\{(x, y) ; x \in U, y=f(x)\}
\end{aligned}
$$

We prepare for the proof of Theorem 1.3 by proving the following technical lemma.

Lemma 4.1. - Let $a<b$ and let $p \in \mathbb{R}[x, y]$ be a polynomial such that

$$
p(a, 0)=0 \text { and } p(b, 0)=0 .
$$

Then for every semi-linear open neighbourhood $V$ of $(a, b) \times\{0\}$ there is a pwp-function $f: \mathbb{R}^{2} \rightarrow \mathbb{R}$ such that

1. $f$ vanishes outside of $V$
2. $f=p$ on $[a, b] \times\{0\}$.

Proof. - Let $q(x)=p(x, 0) \in \mathbb{R}[x]$. The set $V$ is semi-linear. Hence there is an $\varepsilon>0$ such that

$$
V^{\prime}:=\{(x, y) ; x \in(a, b),|y|<\varepsilon \min \{x-a, b-x\}\}
$$

is contained in $V$. We define $f: \mathbb{R}^{2} \rightarrow \mathbb{R}$ by

$$
f(x, y):=\left\{\begin{array}{lc}
q(x)\left(1-\frac{|y|}{\varepsilon \min \{x-a, b-x\}}\right) & \text { if }(x, y) \in V^{\prime} \\
0 & \text { otherwise }
\end{array}\right.
$$

Step 1: The function $f$ is continuous.
The factor

$$
1-\frac{|y|}{\varepsilon \min \{x-a, b-x\}}
$$

is bounded on $V^{\prime}$ and vanishes if $|y|=\varepsilon \min \{x-a, b-x\}$ and $x \in(a, b)$. The polynomial $q$ vanishes at $a$ and $b$. Hence $f$ is continuous.

Step 2: $f$ is a $p w p$ function.
Since $q$ vanishes at $a$ and $b, x-a$ and $x-b$ divide $q$ in $\mathbb{R}[x]$. The absolute value function is $p w p$, so $f$ is $p w p$.

### 4.2. The compact case

Let $A$ be a compact definable locally quasi-convex set. Let $S$ be a onedimensional stratum of a stratification (compatible with $\overline{A^{\circ}}$ ) of $\partial A$ into Lipschitz cells. As explained in Section 3.1, we can assume, after making a suitable rotation, that $S=(h)_{I}$, where $h: I \rightarrow \mathbb{R}$ is definable Lipschitz continuous function, and where $I$ is an open interval. Then $S$ can be a onesided or a two-sided boundary piece. Hence, there is a definable continuous function $\varepsilon: I \rightarrow(0, \infty)$ and, because of local quasi-convexity, a continuous semilinear function $\delta: I \rightarrow(0, \infty)$ such that $\delta(x) \rightarrow 0$ as $x \searrow a$ and as $x \nearrow b$, where $I=(a, b)$, such that exactly one of the following cases holds:
(i) $(h, h+\varepsilon)_{I} \subset A$ and $(h-\delta, h)_{I} \cap A=\emptyset$,
(ii) $(h-\varepsilon, h)_{I} \subset A$ and $(h, h+\delta)_{I} \cap A=\emptyset$,
(iii) $(h-\delta, h+\delta)_{I} \cap A=S$.

Since $\delta$ is a continuous strictly positive semilinear function with bounded domain, there are continuous semilinear functions $h^{ \pm}: I \rightarrow \mathbb{R}$ such that

$$
h-\delta<h^{-}<h<h^{+}<h+\delta
$$

on $I$. This implies that $\left(h^{+}\right)_{I}$ and $\left(h^{-}\right)_{I}$ are semilinear sets, $A \cap U=S$ and $A \cup U$ is a compact definable locally quasi-convex set, where $U=\left[h^{-}, h\right]_{I}$ in case (i), resp., $U=\left[h, h^{+}\right]_{I}$ in case (ii), resp., $U=\left[h^{-}, h^{+}\right]_{I}$ in case (iii). We refer to the set $U$ obtained in this way as a semilinarization of $A$ at $S$.

We complete the proof of Theorem 1.3 by proving the following proposition.

Proposition 4.2. - Let $A \subset \mathbb{R}^{2}$ be a locally quasi-convex compact definable set, and let $f: A \rightarrow \mathbb{R}$ be a pwp function. Then there is a pwp function $F: \mathbb{R}^{2} \rightarrow \mathbb{R}$ such that $F=f$ on $A$.

Proof. - Let $S_{1}, \ldots, S_{r}$ be a stratification of $\partial A$ into Lipschitz cells such that $\left.f\right|_{S_{i}}$ is the restriction of some polynomial $p_{i}$ to $S_{i}$ for $i=1, \ldots, r$. We may assume that $\operatorname{dim}\left(S_{i}\right)=1$ if and only if $i=1, \ldots, s$ (some $s \leqslant$ $r)$. We extend $f$ inductively to a $p w p$ function on a compact semilinear neighbourhood $B$ of $A$ as follows: Take $B=A \cup U_{1} \cup \ldots \cup U_{s}$ where $U_{i}$ is a semilinearization of $A \cup U_{1} \cup \ldots \cup U_{i-1}$ at $S_{i}, i=1, \ldots, s$, and extend $f$ to $B$ by setting $f=p_{i}$ on $U_{i} \backslash A$. Take a stratification $T_{1}, \ldots, T_{t}$ of $\partial B$ into Lipschitz cells such that $\left.f\right|_{T_{i}}$ is the restriction of some polynomial to $T_{i}$ for each $i$. The sets $T_{i}$ are semilinear. Let $C$ be the union of those $T_{i}$ with $\operatorname{dim}\left(T_{i}\right)=0$. Then $C$ is a finite set. Let $p$ be a polynomial that equals $f$ on $C$. Then $g=f-p$ is a $p w p$ function on $B$, and $g$ restricted to each 1-dimensional $T_{i}$ is the restriction of some polynomial $q_{i}$ that vanishes on $\overline{T_{i}} \backslash T_{i}$. By applying Lemma 4.1 to the function $q_{i}$ and the set $\overline{T_{i}}$ in place of $p$ and $[a, b] \times\{0\}$, we obtain for every open semilinear neighbourhood $V_{i}$ of $T_{i}$ a $p w p$ function $g_{i}: \mathbb{R}^{2} \rightarrow \mathbb{R}$ such that $g_{i}$ vanishes outside of $V_{i}$ and $g_{i}=q_{i}$ on $\overline{T_{i}}$ for each 1-dimensional $T_{i}$. Choosing the $V_{i}$ small enough we can assume that $\overline{V_{i}} \cap \overline{V_{j}} \backslash B=\emptyset$ for all 1-dimensional $T_{i}$ and $T_{j}, i \neq j$. Define the compact semilinear neighbourhood $D$ of $B$ to be the union of $B$ and the sets $\bar{V}_{i} \backslash B, T_{i}$ 1-dimensional, and define $G: D \rightarrow \mathbb{R}$ by $G=g$ on $B$ and $G=g_{i}$ on $\bar{V}_{i} \backslash B$. Thus $G$ coincides with $g$ on $B$ and vanishes on $\partial D$. Thus $G$ extends to a $p w p$ function on $\mathbb{R}^{2}$ by setting $G=0$ outside of $D$. Finally, take $F=G+p$.

### 4.3. The non-compact case

If the Hardy field $\mathcal{H}(\mathbb{R})$ is not dense in $\mathcal{H}(\mathcal{M})$, then we cannot expect extensibility of $p w p$ functions defined on all closed, definable, locally quasiconvex sets. Indeed, the extensibility would imply that disjoint definable
function germs at $+\infty$ can be separated by a semialgebraic function germ at $+\infty$; i.e., that $\mathcal{H}(\mathbb{R})$ is dense in $\mathcal{H}(\mathcal{M})$.

We now assume that the Hardy field of semialgebraic germs at $+\infty$ lies dense in the Hardy field of definable germs at $+\infty$. We establish some preliminary lemmas.

Lemma 4.3. - Let $\Gamma \subset \mathbb{R}^{2}$ be an unbounded semialgebraic arc, and let $p$ be a polynomial in $\mathbb{R}[x, y]$. Then, for every open semialgebraic neighbourhood $U$ of $\Gamma$, there exists an $M>0$ and a pwp function $f$ such that

$$
f(x, y)=p(x, y) \text { on } \Gamma \backslash B_{M}(0,0),
$$

and $f$ vanishes outside of $U$.
Proof. - After some rotation we may assume that $\Gamma$ is the graph of a continuous semialgebraic function $h:[a, \infty) \rightarrow \mathbb{R}$. We may further assume that $p(x, h(x))>0$ for sufficiently large $x$, as the case $p(x, h(x))=0$ is trivial. Select a positive semialgebraic continuous function $\delta$ such that for sufficiently large $b$,

$$
[h-\delta, h+\delta]_{[b, \infty)} \subset U
$$

and $p(x, y)>0$ for all $(x, y) \in[h-\delta, h+\delta]_{[b, \infty)}$. The graph of $h+\delta$ is a semialgebraic set of dimension 1. By the definition of a semialgebraic function, there exists a nonzero polynomial $q$ in $\mathbb{R}[x, y]$ such that

$$
q(x, h(x)+\delta(x))=0
$$

and, restricting to $x$ sufficiently large, we may even take $q$ to be irreducible in $\mathbb{R}[x, y]$. After modifying $\delta$ suitably (e.g., replacing $\delta$ by $\delta / n$ for suitable $n \geqslant 1$ ), we can assume that $q(x, h(x)) \neq 0$ for sufficiently large $x$. Scaling $q$ by a suitable non-zero real, we can assume that

$$
q(x, h(x))>0
$$

for sufficiently large $x$. For $n \in \mathbb{N}$ let $q_{n}$ be the polynomial

$$
q_{n}(x, y):=\left(x^{2}+y^{2}\right)^{n} q(x, y) .
$$

Then there is an $N$ such that

$$
\begin{equation*}
q_{N}(x, h(x))>p(x, h(x)) \tag{4.1}
\end{equation*}
$$

for sufficiently large $x$, say $x \geqslant M / 2$, for some $M$, which we may take to be greater or equal to $2 \sqrt{3}$. Let $\rho_{M}: \mathbb{R}^{2} \rightarrow \mathbb{R}$ be the function defined by

$$
\begin{equation*}
\rho_{M}(x, y):=\inf \left(1, \sup \left(0, x^{2}+y^{2}-M^{2}\right)\right) \tag{4.2}
\end{equation*}
$$

Then $\rho_{M}$ is a $p w p$ function that vanishes on $B_{M}(0,0)$ and that equals 1 outside of $B_{M+1}(0,0)$. On the set $[h, h+\delta]_{[M / 2, \infty)}$ we define the $p w p$ function $f$ as

$$
f:=\rho_{M / 2} \inf \left(q_{N}, p\right)
$$

The function $f$ vanishes on the graph of $h+\delta$, and $f$ coincides with $p$ on $\Gamma \backslash B_{M}(0,0)$ because of inequality (4.1). Similarly we extend $p$ to the set $[h-\delta, h)_{[M / 2, \infty)}$. Hence there is a pwp function $f: \mathbb{R}^{2} \rightarrow \mathbb{R}$ which coincides with $p$ on the $\operatorname{arc} \Gamma \backslash B_{M}(0,0)$.

The dimension of the boundary of a semialgebraic subset of $\mathbb{R}^{2}$ is at most 1 . So we obtain a stronger version of the previous lemma.

Lemma 4.4. - Let $A \subset \mathbb{R}^{2}$ be a closed semialgebraic set, and let $f$ : $A \rightarrow \mathbb{R}$ be a pwp function. Then there is an $M>0$ and a pwp function $F: \mathbb{R}^{2} \rightarrow \mathbb{R}$ such that $F=f$ on $A \backslash B_{M}(0,0)$.

Proof. - We choose $M \geqslant 2 / \sqrt{3}$ so big that $\partial A \backslash B_{M}(0,0)$ consists of a disjoint union of closed (semialgebraic) arcs at infinity. For each of these arcs we find open pairwise disjoint semialgebraic neighbourhoods, so that Lemma 4.3 implies the existence of a $p w p$ function $\tilde{F}: \mathbb{R}^{2} \rightarrow \mathbb{R}$ such that $\tilde{F}=f$ on $\partial A \backslash B_{M / 2}(0)$, after some further increasing of $M$. Define $g: \mathbb{R}^{2} \rightarrow \mathbb{R}$ as $g:=f$ on $A$ and $g:=\tilde{F}$ outside of $A$, and let $F:=\rho_{M / 2} g$ where $\rho_{M}$ is the function defined by (4.2).

We also need a version of Lemma 4.4 for definable sets $A$.
Lemma 4.5. - Let $\mathcal{H}(\mathbb{R}) \subset \mathcal{H}(\mathcal{M})$ be dense. Let $A \subset \mathbb{R}^{2}$ be a closed definable set, and let $f: A \rightarrow \mathbb{R}$ be a pwp function. Then there is an $M>0$ and a pwp function $g: \mathbb{R}^{2} \rightarrow \mathbb{R}$ such that $g=f$ on $A \backslash B_{M}(0,0)$.

Proof. - The dimension of the boundary of a definable subset of $\mathbb{R}^{2}$ is at most 1. Let $A_{1}, \ldots, A_{r}$ denote the one-dimensional Lipschitz cells of $\partial A \backslash B_{M}(0,0)$ for $M>0$. Choose $M$ so large that each $A_{i}$ is unbounded, and such that $f=p_{i}$ on $A_{i}$ for some polynomial $p_{i}$. We construct pairwise disjoint closed semialgebraic neighbourhoods $V_{i}$ of $A_{i}$. Fix $1 \leqslant i \leqslant r$. In some linear orthogonal coordinate system (depending on $i$ ), we may write

$$
A_{i}=\left(h_{i}\right)_{\left(a_{i}, \infty\right)}
$$

for some definable Lipschitz continuous function $h_{i}:\left(a_{i}, \infty\right) \rightarrow \mathbb{R}$. Let $\varepsilon_{i}:\left(a_{i}, \infty\right) \rightarrow \mathbb{R}$ be defined by

$$
\varepsilon_{i}(x)=\frac{1}{3} \operatorname{dist}\left(\left(x, h_{i}(x)\right), \bigcup_{j \neq i} A_{j}\right)
$$

(Here, for a point $p$ and a set $S$ in $\mathbb{R}^{2}, \operatorname{dist}(p, S)$ denotes the distance from $p$ to $S$, i.e., $\operatorname{dist}(p, S):=\inf \{\|p-q\|: q \in S\}$.) Since $\mathcal{H}(\mathbb{R}) \subset \mathcal{H}(\mathcal{M})$ is dense, there are continuous semialgebraic functions $\varphi_{i}, \psi_{i}:\left(c_{i}, \infty\right) \rightarrow \mathbb{R}, c_{i}>a_{i}$ with

$$
h_{i}-\varepsilon_{i}<\varphi_{i}<h_{i}<\psi_{i}<h_{i}+\varepsilon_{i}
$$

on $\left(c_{i}, \infty\right)$. Consider the closed semialgebraic set

$$
V_{i}:=\overline{\left(\varphi_{i}, \psi_{i}\right)_{\left(c_{i}, \infty\right)}}
$$

The sets $V_{1}, \ldots, V_{r}$ (in the original coordinate system) are closed, semialgebraic and pairwise disjoint. Choose $M$ so big that

$$
\partial A \backslash B_{M}(0,0) \subset \bigcup_{i} V_{i}
$$

Then the set

$$
B:=\left(\bigcup_{i} V_{i} \cup A\right) \backslash B_{M}(0,0)
$$

is a closed semialgebraic neighbourhood of $A \backslash B_{M}(0,0)$. Define $g: B \rightarrow \mathbb{R}$ as

$$
g(x):=\left\{\begin{array}{cl}
f(x), & \text { if } x \in A \\
p_{i}(x), & \text { if } x \in V_{i} \backslash A
\end{array}\right.
$$

This function is a semialgebraic $p w p$ function such that $g=f$ on $A \backslash$ $B_{M}(0,0)$. The result follows now from Lemma 4.4.

Theorem 1.4 is now implied by the following proposition.
Proposition 4.6. - Let $\mathcal{H}(\mathbb{R}) \subset \mathcal{H}(\mathcal{M})$ be dense. Let $A \subset \mathbb{R}^{2}$ be a closed definable locally quasi-convex set. Then every pwp function $f: A \rightarrow \mathbb{R}$ extends to a pwp function $F: \mathbb{R}^{2} \rightarrow \mathbb{R}$.

Proof. - Let $M$ be so big, that Lemma 4.5 provides us with a $p w p$ function $g: \mathbb{R}^{2} \rightarrow \mathbb{R}$ with $g=f$ on $A \backslash B_{M}(0,0)$. The set $A \cap B_{2 M}(0,0)$ is locally quasi-convex. Hence, by Proposition 4.2, there is a $p w p$ function $G: \mathbb{R}^{2} \rightarrow \mathbb{R}$ such that $G=f$ on $A \cap B_{2 M}(0,0)$. Take a pwp function $\rho: \mathbb{R}^{2} \rightarrow[0,1]$ that equals 1 outside of $B_{2 M}(0,0)$ and vanishes in $B_{M}(0,0)$. Set

$$
F:=(1-\rho) G+\rho g .
$$

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