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# HITTING PROBABILITIES OF KILLED BROWNIAN MOTION; A STUDY ON GEOMETRIC REGULARITY

BY CHRISTER BORELL

## 1. Introduction

Consider a Brownian motion  $X$  in  $n$ -space with first hitting times  $\tau_A = \tau_A(X) = \inf \{ t > 0; X(t) \in A \}$  and let  $\mathcal{U}(\mathbb{R}^n)$  denote the class of all non-empty, open, and convex subsets of  $\mathbb{R}^n$ . Then, if  $x_0, x_1 \in \mathbb{R}^n$  and  $A_0, A_1, B_0, B_1 \in \mathcal{U}(\mathbb{R}^n)$ :

$$(1.1) \quad \mathbb{P}_{x_\lambda}(\tau_{B_\lambda} \geq \tau_{A_\lambda} < +\infty) \\ \geq \mathbb{P}_{x_0}(\tau_{B_0} \geq \tau_{A_0} < +\infty) \wedge \mathbb{P}_{x_1}(\tau_{B_1} \geq \tau_{A_1} < +\infty), \quad 0 < \lambda < 1,$$

where  $\xi_\lambda = (1-\lambda)\xi_0 + \lambda\xi_1$ ,  $\xi = x, A, B$ , and  $B^c = \mathbb{R}^n \setminus B$ , respectively (Borell [4]).

In this paper, the basic diffusion process is a Brownian motion  $Y$  in  $\mathbb{R}^n \cup \{\varphi\}$ , which starts in  $\mathbb{R}^n$  and behaves as an ordinary Brownian motion up till a certain random point of time when it jumps to  $\varphi$  and remains there. More explicitly, conditioned on  $X$ , the event  $Y(t) \in \mathbb{R}^n$ , has the probability  $\exp\left(-\int_0^t V(X(s)) ds\right)$ , where  $V: \mathbb{R}^n \rightarrow [0, +\infty]$  is such that  $V|_{\text{dom } V}$  is concave and  $\text{dom } V = \{V < +\infty\} \in \mathcal{U}(\mathbb{R}^n)$ . Under these assumptions (1.1) still holds with  $\tau = \tau(Y)$  (Theorem 3.1). In fact, the same result remains true if  $\mathbb{R}^n$  is replaced by an arbitrary Banach space.

About half the paper deals with various interpretations of Theorem 3.1. Thus, we discuss convexity properties of:

- (i)  $V$ -harmonic measures (Section 6, Example 7.1);
- (ii)  $V$ -Newtonian potentials (Theorem 7.1);
- (iii)  $V$ -equilibrium measures (Example 7.2) and
- (iv) logarithmic and Newtonian capacities (examples 7.3-7.5).

In the above list, perhaps the single most interesting point is the following: let  $B \in \mathcal{U}(\mathbb{R}^n)$ ,  $n \geq 2$ , be bounded and suppose  $V: B \rightarrow [0, +\infty[$  is  $-1/2$ -concave, that is,  $V^{-1/2}: B \rightarrow ]0, +\infty]$  is concave. Moreover, let  $g$  denote the Green function of

$-1/2\Delta + V$  in  $B$  with the Dirichlet boundary condition zero. Then  $g$  is quasi-concave if  $n=2$ , and if  $n \geq 3$  the function  $g^{-1/(n-2)}$  is convex. Theorem 7.1 expresses these facts as a Brunn-Minkowski inequality of appropriate potentials of  $g$ . For comparison, we here only mention that the 3-dimensional potential  $g\mu$ ,  $\mu$  being the uniform distribution of a line segment, turns out to have convex equipotential surfaces. The same thing is known to be true for a point mass if  $V=0$  (Gabriel [15], [16]). Needless to say, the beautiful works of Gabriel have played a decisive role for this and some other closely related papers of the author ([4], [5]).

Finally, in this section, let us make some remarks on the potential  $V$  above.

Again, consider a  $Y$ -process in  $\mathbb{R}^n$  now with a convex potential  $V$ . Moreover, suppose  $\text{dom } V \in \mathcal{U}(\mathbb{R}^n)$  is bounded. Then, by Brascamp and Lieb ([9], [10]), the transition densities  $p_t$ ,  $t > 0$ , of  $Y$  are log-concave for each fixed  $t > 0$ . From this we expect nice geometrical properties of the corresponding Green function:

$$g = \int_0^\infty p_t dt.$$

In fact, our fruitless attempts to understand this puzzling problem have finally led us to  $-1/2$ -concave potentials. The reader should note that a  $-1/2$ -concave function is convex. (The log-concavity of the  $p_t$  for convex  $V$  turns out to be an algebraic consequence of (1.1) but that is another uniformity!) Below we will also see that  $-1/2$ -concave potentials enter quite naturally in the hyperbolic potential theory of plane convex domains (Example 3.1).

## 2. Definitions

Throughout,  $E$  denotes a separable Banach space and  $\mathcal{C}_E([0, +\infty[)$  is the standard Fréchet space of all continuous maps of  $[0, +\infty[$  into  $E$ . A centered Gaussian random vector  $X$  in  $C_E([0, +\infty[)$  is called a Brownian motion in  $E$  or an  $E$ -valued Brownian motion if  $X$  possesses stochastically independent increments and if, for every  $t > 0$ , the law of  $X_t = [X(\cdot)](t)$  equals the law of  $t^{1/2}X_1$  (see Gross [18] (potential theory) and Chow [12] (noise theory)).

*Example 2.1.* — Suppose  $S$  is a compact metric space and let  $G = (G(s), s \in S)$  be a real-valued, centered Gaussian stochastic process with continuous paths. Then there exists a unique real-valued centered Gaussian process  $X$  with time set  $S \times [0, +\infty[$  and covariance  $[E(G(s)G(s'))](t \wedge t')$ . Moreover, a version of  $X = (X(s, t), (s, t) \in S \times [0, +\infty[)$  has continuous paths with probability one and, accordingly, induces a Brownian motion in  $\mathcal{C}(S)$  (for details, see Carmona [11]).  $\square$

The above example brings out the most general form of a Banach space-valued Brownian motion.

An  $E$ -valued Brownian motion is said to be non-degenerated if  $\text{supp } \mathcal{L}(X_1) = E$ . If  $F$  is a separable Banach space and  $A : E \rightarrow F$  is a bounded linear map, then each  $E$ -valued Brownian motion  $X$  defines an  $F$ -valued Brownian motion by the rule  $[AX]_t = AX_t$ .

In what follows,  $X$  is supposed to be a fixed *non-degenerated* Brownian motion in  $E$  and, as usual, we let  $\mathbb{P}_x = \mathcal{L}(x + X)$  and  $\mathbb{E}_x = \int (\cdot) d\mathbb{P}_x$ .

Below  $\mathcal{U}(E)$  denotes the class of all non-empty, open, and convex subsets of  $E$ . Moreover,  $\bar{\mathcal{U}}(E) = \{\bar{A}; A \in \mathcal{U}(E)\}$ ,  $\mathcal{U}_\infty(E) = \{A \in \mathcal{U}(E); A \text{ bounded}\}$ , and  $\bar{\mathcal{U}}_\infty(E) = \{\bar{A}; A \in \mathcal{U}_\infty(E)\}$ , respectively. If  $A_0, A_1 \subseteq E$ , and  $0 < \lambda < 1$ , we write  $A_\lambda = (1 - \lambda)A_0 + \lambda A_1$ . The same convention will be used for vectors in  $E$ . Given  $A_i \in \mathcal{U}(E)$ , concave functions  $f_i: A_i \rightarrow [0, +\infty]$ ,  $i = 0, 1$ , and  $\lambda \in [0, 1]$ , the so-called  $\lambda$ -supremum convolution :

$$f_0 \mid \lambda \mid f_1: A_\lambda \rightarrow [0, +\infty],$$

of  $f_0$  and  $f_1$  is defined by:

$$(f_0 \mid \lambda \mid f_1)(x_\lambda) = \sup \{ (1 - \lambda) f_0(x_0) + \lambda f_1(x_1); x_0 \in A_0, x_1 \in A_1 \}.$$

Here  $0 \cdot (+\infty) = 0$ . Of course,  $f_0 \mid \lambda \mid f_1$  is concave and by simple means one verifies:

$$(2.1) \quad f_0 \mid \theta_\lambda \mid f_1 = (f_0 \mid \theta_0 \mid f_1) \mid \lambda \mid (f_0 \mid \theta_1 \mid f_1), \quad \theta_0, \theta_1 \in [0, 1].$$

Next suppose  $\alpha \in \mathbb{R} \setminus \{0\}$ . Using the conventions  $0^\alpha = +\infty$  and  $(+\infty)^\alpha = 0$ , if  $\alpha < 0$ , a function  $f: A \rightarrow [0, +\infty](A \subseteq E)$  is said to be  $\alpha$ -convex ( $\alpha$ -concave) if  $f^\alpha$  is convex (concave). For this reason, a quasi-concave (log-concave) function is sometimes called  $-\infty$ -convex (0-convex or 0-concave). The same terminology is used for set functions on vector spaces. For future reference, recall that a Gaussian Radon measure on a locally convex Hausdorff vector space is log-concave (Borell [6]).

### 3. The main result

Consider the Feynman-Kac semi-group:

$$S_t f = \mathbb{E} \left( f(X(t)) \exp \left( - \int_0^t V(X(s)) ds \right) \right), \quad t > 0,$$

where the potential  $V: E \rightarrow [0, +\infty]$  is Borel measurable. If, in addition,  $V$  is convex, the log-concavity of Gaussian measures may be used to show that each  $S_t$  preserves log-concavity. Indeed, this property has many nice consequences (Brascamp, Lieb [9], [10], Lions [20]). The reader should note that if  $B = \text{dom } V \in \mathcal{U}(E)$ , then:

$$S_t f = \mathbb{E} \left( f(X(t)) \exp \left( - \int_0^t V(X(s)) ds \right); \tau_B \geq t \right), \quad t > 0.$$

THEOREM 3.1. — For  $i=0, 1$ , suppose  $A_i, B_i \in \mathcal{U}(E)$ ,  $x_i \in B_i$ , and let  $V_i: B_i \rightarrow [0, +\infty[$  be  $-1/2$ -concave. Set  $V_\lambda = (V_0^{-1/2} |\lambda| V_1^{-1/2})^{-2}$  and:

$$M(\lambda) = \mathbb{E}_{x_\lambda} \left( \exp \left( - \int_0^{\tau_{A_\lambda}} V_\lambda(X(s)) ds \right); \tau_{B_\lambda} \geq \tau_{A_\lambda} < +\infty \right), \quad 0 < \lambda < 1,$$

respectively. Then  $M$  is quasi-concave.

Interestingly enough, there are several relations between Theorem 3.1 and the Brunn-Minkowski theory of convex bodies but the interplay is not yet fully understood. In particular, one may ask if the log-concavity of Gaussian measures (on all measurable sets!) and Theorem 3.1 have a common source.

For some other geometrical estimates on Feynman-Kac semi-groups, see Borell [7] and Ehrhard [14].

Before giving the proof of Theorem 3.1, which is rather lengthy, we should like to discuss an example where  $-1/2$ -concave potentials arise in a natural way.

First, however, recall that if  $X$  is the usual Brownian motion in  $\mathbb{R}^n$ , then the expectation:

$$u(x) = \mathbb{E}_x \left( \exp \left( - \int_0^{\tau_A} V(X(s)) ds \right); \tau_B \geq \tau_A < +\infty \right), \quad x \in \bar{B},$$

solves the  $V$ -equilibrium potential equation:

$$\left\{ \begin{array}{l} \frac{1}{2} \Delta u - V u = 0 \quad \text{in } B, \\ u = 1 \quad \text{on } \bar{A}, \\ u = 0 \quad \text{on } \partial B, \end{array} \right.$$

where, for example,  $A, B \in \mathcal{U}(\mathbb{R}^n)$ ,  $\bar{A} \subseteq B$ , and  $V: B \rightarrow [0, +\infty[$  is continuous (see e. g. Dynkin [13], Chap. 13). (Here and elsewhere  $\Delta = \partial^2/\partial x_1^2 + \dots + \partial^2/\partial x_n^2$ .)

Example 3.1. — Consider a  $B \in \mathcal{U}(\mathbb{C})$ ,  $B \neq \mathbb{C}$ , equipped with the hyperbolic metric:

$$ds = \left| \frac{f'(z)}{\operatorname{Im} f(z)} \right| |dz|,$$

$f$  being an arbitrary one-to-one conformal map onto the upper half plane in  $\mathbb{C}$ . Note that:

$$\frac{1}{2} \left| \frac{f'(z)}{\operatorname{Im} f(z)} \right| = \lim_{\zeta \rightarrow z} d(z, \zeta) / |z - \zeta|,$$

where  $d(z, \zeta) = |(f(z) - f(\zeta)) / (f(z) - \overline{f(\zeta)})|$ ,  $z, \zeta \in B$ , is a strictly increasing function of the hyperbolic distance in  $B$  (see e. g. Ahlfors [1], [2]).

The following discussion is based on the fact that the Green function  $g(z, \zeta)$  of  $-1/2\Delta$  in  $B$  with the Dirichlet boundary condition zero is quasi-concave in  $(z, \zeta)$  (this may be known; for safety's sake the result is proved in Theorem 7. 1). Equivalently, if  $B(z; r)$  denotes the open  $d$ -ball with center  $z \in B$  and radius  $r > 0$ , then:

$$(1 - \lambda) B(z_0; r) + \lambda B(z_1; r) \subseteq B(z_\lambda; r), \quad 0 < \lambda < 1.$$

Accordingly, for reals  $t \neq 0$  close to zero:

$$\frac{1}{|t|} \left| \frac{f(z_\lambda + th_\lambda) - f(z_\lambda)}{f(z_\lambda + th_\lambda) - \overline{f(z_\lambda)}} \right| \leq \frac{1}{|t|} \left\{ \left| \frac{f(z_0 + th_0) - f(z_0)}{f(z_0 + th_0) - \overline{f(z_0)}} \right| \vee \left| \frac{f(z_1 + th_1) - f(z_1)}{f(z_1 + th_1) - \overline{f(z_1)}} \right| \right\},$$

and in the limit as  $t \rightarrow 0$ :

$$\left| \frac{f'(z_\lambda) h_\lambda}{\text{Im } f(z_\lambda)} \right| \leq \left| \frac{f'(z_0) h_0}{\text{Im } f(z_0)} \right| \vee \left| \frac{f'(z_1) h_1}{\text{Im } f(z_1)} \right|.$$

By choosing:

$$h_\nu = \left| \frac{\text{Im } f(z_\nu)}{f'(z_\nu)} \right|, \quad \nu = 0, 1,$$

the resulting inequality states that the function  $|\text{Im } f(z)/f'(z)|$  is concave.

Now recall that the Laplace-Beltrami operator  $\Delta_B$  in the hyperbolic  $B$  equals:

$$\Delta_B = \left| \frac{\text{Im } f(z)}{f'(z)} \right|^2 \Delta.$$

Consequently, if  $A \in \mathcal{U}_\infty(\mathbb{C})$  and  $\bar{A} \subseteq B$ , Theorem 3. 1 applies to the 1-equilibrium potential equation:

$$\begin{cases} \Delta_B u - u = 0 & \text{in } B \setminus \bar{A}, \\ u|_{\bar{A}} = 1, \end{cases}$$

and we conclude that  $u$  is quasi-concave. Moreover, if  $u_z$  denotes the 1-equilibrium potential of  $B(z; r)$ , then the map  $(z, \zeta) \rightsquigarrow u_z(\zeta)$  is quasi-concave too.  $\square$

#### 4. Reduction of Theorem 3. 1 to finite dimension

To begin with, we list a series of Lemmas, which are all well-known and easy to prove.

LEMMA 4. 1. — Suppose  $F_n$ ,  $n \in \mathbb{N}$ , are closed and  $F_n \downarrow F$ . Then  $\mathbb{P}(\tau_{F_n} \downarrow \tau_F) = 1$  on  $F^r \cup F^c$ .

Here  $F^r = \{\mathbb{P}(\tau_F = 0) = 1\}$  is the set of all regular points for  $F$ . Recall that  $\mathbb{P}(\tau_F = 0)$  vanishes on  $(F^r)^c$  by Blumenthal's zero-one law (see e. g. Port and Stone [22]).

LEMMA 4. 2. — If  $A \in \mathcal{U}(E)$ , then  $A^r = \bar{A}^r = \bar{A}$ . In addition,  $\tau_A = \tau_{\bar{A}}$  a. s.  $\mathbb{P}$ .

The reader should note that the last part of Lemma 4.2 depends on the strong Markov property of  $X$ . The next Lemma is a consequence of continuity of paths only.

LEMMA 4.3. — Let  $F_n, n \in \mathbb{N}$ , be closed and  $F_n \downarrow F$ . If  $B_n \in \mathcal{B}(E), n \in \mathbb{N}$ , and  $B_n \downarrow B$ , then:

$$\{ \tau_{B_n^c} \geq \tau_{F_n} < +\infty \} \downarrow \{ \tau_{B^c} \geq \tau_F < +\infty \}, \quad \text{a. s. } \mathbb{P}.(( \quad ) \cap \{ \tau_{B^c} < +\infty \}),$$

on  $F^r \cup F^c$ .

Here  $\mathcal{B}(E)$  denotes the Borel field in  $E$ .

LEMMA 4.4. — Suppose  $0 < \lambda < 1$ :

(a) If  $A_0, A_1 \in \mathcal{U}_\infty(E)$  and  $A_\lambda$  is contained in an open affine half-space  $H$ , then there exist open affine half-spaces  $H_0, H_1$ , satisfying  $H \supseteq H_\lambda, H_0 \supseteq A_0$ , and  $H_1 \supseteq A_1$ .

(b) Let  $B_i \in \mathcal{U}_\infty(E)$  and suppose  $f_i : B_i \rightarrow [0, +\infty[, i = 0, 1$ , are concave. If  $\zeta$  is a continuous affine function on  $E$  and  $\zeta|_{B_\lambda} \geq f_0 \mid \lambda \mid f_1$ , then there exist continuous affine functions  $\zeta_0, \zeta_1$  on  $E$  satisfying  $\zeta \geq \zeta_0 \mid \lambda \mid \zeta_1, \zeta_0|_{B_0} \geq f_0$ , and  $\zeta_1|_{B_1} \geq f_1$ .

LEMMA 4.5:

(a)  $\overline{A_0 + A_1} \subseteq \overline{A_0 + A_1}, A_0, A_1 \subseteq E$ ;

(b) If  $A_n, A \in \mathcal{U}(E), n \in \mathbb{N}$ , and  $A_n \downarrow A$ , then  $\overline{A_n} \downarrow \overline{A}$ .

*Proof of Theorem 3.1,  $\dim E < +\infty \Rightarrow$  Theorem 3.1.* In view of (2.1) it is enough to establish the following inequality:

$$M(\lambda) \geq M(0) \wedge M(1),$$

where  $0 < \lambda < 1$  is fixed. Furthermore, we may assume  $B_0, B_1 \in \mathcal{U}_\infty(E)$ .

Let  $j = 0, 1$ , or  $\lambda$  and set  $f_j = V_j^{-1/2}$ . By monotone convergence, there is no loss of generality if we only treat the case when the  $f_j$  are finite-valued. Suppose:

$$f_j = \inf_{n \in \mathbb{N}} \zeta_{jn} | B_j$$

and  $\zeta_{\lambda n} \geq \zeta_{0n} \mid \lambda \mid \zeta_{1n}$ , where the  $\zeta_{jn}$  are finite infimums of continuous affine functions on  $E$ . This construction is possible due to Lemma 4.4. By the same Lemma here exist open polyhedrons  $C_{jn}, n \in \mathbb{N}, C = A, B$ , satisfying:

$$C_{jn} \downarrow C_j \quad \text{as } n \rightarrow +\infty$$

and  $C_{\lambda n} \supseteq (1 - \lambda)C_{0n} + \lambda C_{1n}$ .

We now introduce:

$$f_{jn} = \inf_{0 \leq k \leq n} \zeta_{jk} | B_{jn} \cap \{ \zeta_{j0} > 0, \dots, \zeta_{jn} > 0 \}$$

and:

$$M_n(j) = \mathbb{E}_{x_j} \left( \exp \left( - \int_0^{\tau_{A_{jn}}} f_{jn}^{-2}(X(s)) ds \right); \tau_{B_{jn}^c} \geq \tau_{A_{jn}} < +\infty \right).$$

Granted the validity of Theorem 3. 1 in the finite-dimensional case, we have:

$$M_n(\lambda) \geq M_n(0) \wedge M_n(1)$$

and (4. 1) follows from Lemmas 4. 1-4. 4 and monotone convergence.  $\square$

**5. Proof of Theorem 3. 1,  $\dim E < +\infty$**

In the following lemma, the  $V_j, j=0, 1$ , or  $\lambda$ , are as in Theorem 3. 1.

LEMMA 5. 1. — *If  $J(r)=r, r>0$ , then:*

$$J^3 \otimes V_\lambda \leq (J^3 \otimes V_0) |\underline{\lambda}| (J^3 \otimes V_1), 0 < \lambda < 1.$$

*Proof.* — By the Hölder inequality the function  $(J \otimes 1)^3 / (1 \otimes J)^2$  is convex and the result follows at once.  $\square$

LEMMA 5. 2. — *Suppose  $A, B \in \mathcal{U}_\infty(\mathbb{R}^n)$  and  $0 \in \bar{A} \subseteq B$ . Let  $f: B \rightarrow ]0, \infty[$  be  $\mathcal{C}^\infty$  and concave and set  $V=f^{-2}$ . Then the solution of the Dirichlet problem:*

$$\left\{ \begin{array}{l} \Delta u - V u = 0 \quad \text{in } B \setminus \bar{A}, \\ u = 1 \quad \text{on } \partial A \\ u = 0 \quad \text{on } \partial B, \quad u \in \mathcal{C}(\bar{B}), \end{array} \right.$$

*has a non-vanishing gradient in  $B \setminus \bar{A}$ .*

*Proof.* — The solution  $u$  is  $\mathcal{C}^\infty$  (see e. g. Gilbarg and Trudinger [17], Theorem 6. 17).

We first prove that the function  $v(x)=x; \nabla u(x), x \in B \setminus \bar{A}$ , is non-positive.

To see this, let  $\alpha > 1$  satisfy  $\alpha \bar{A} \subseteq B$  and note that:

$$\Delta [u(x/\alpha)] - \alpha^{-2} V(x/\alpha) u(x/\alpha) = 0 \quad \text{in } B \setminus \alpha \bar{A}.$$

Moreover, as:

$$f(x/\alpha) \geq \alpha^{-1} f(x) + (1 - \alpha^{-1}) f(0) \quad \text{in } B,$$

we have  $\alpha f(x/\alpha) \geq f(x), x \in B$ , and hence:

$$\Delta [u(x/\alpha)] - V(x) u(x/\alpha) \leq 0 \quad \text{in } B \setminus \alpha \bar{A}.$$

Thus:

$$\Delta [u(x) - u(x/\alpha)] - V(x) [u(x) - u(x/\alpha)] \geq 0 \quad \text{in } B \setminus \bar{A}$$

and as  $(u - u(\cdot/\alpha))|_{\partial(B \setminus \alpha \bar{A})} \leq 0$ , the maximum principle ([17], cor. 3. 2) gives

$$(u - u(\cdot/\alpha))|_{B \setminus \alpha \bar{A}} \leq 0.$$

But then  $v \leq 0$ .



In the next step we show that  $v$  is strictly negative.

A computation yields:

$$\Delta v = x; \nabla(\Delta u) + 2\Delta u = x; \nabla(\nabla V u) + 2\nabla V u = (x; \nabla V)u + V(x; \nabla u) + 2\nabla V u,$$

that is:

$$\Delta v - Vv = (2\nabla V + x; \nabla V)u.$$

But:

$$2\nabla V + x; \nabla V = \frac{2}{f^3}(f - x; \nabla f) \geq \frac{2}{f^3}f(0) > 0$$

and so  $\Delta v - Vv > 0$ . Since  $v \leq 0$ , the strong maximum principle ([17], Th. 35) gives  $v < 0$  and accordingly  $v \neq 0$  in  $B \setminus \bar{A}$ .  $\square$

The main points in the proof which follows are due to Gabriel ([15], [16]). The Brunn-Minkowski aspect was added for the first time in [4]. The Gabriel differential method also applies to certain time-dependent [5] and non-linear (Lewis [19]) problems.

*Proof of Theorem 3.1,  $\dim E < +\infty$ .* — There is no loss of generality in assuming:

- (i)  $X$  is the usual Brownian motion in  $\mathbb{R}^n$ ,  $n \geq 1$ ;
- (ii)  $0 \in \bar{A}_0 \cap \bar{A}_1$ ,  $B_0, B_1 \in \mathcal{U}_\infty(\mathbb{R}^n)$ ;
- (iii) the functions  $f_i = V_i^{-1/2}$  have concave  $\mathcal{C}^\infty$  extensions  $\tilde{f}_i: B_i + B(0; \delta) \rightarrow ]0, +\infty[$ ,  $i=0,1$  ( $\delta > 0$  fixed) and from (iii) and Lemma 4.3;
- (iv)  $\bar{A}_i \subseteq B_i$ ,  $i=0,1$ .

Next let  $0 < \lambda < 1$  be fixed. Moreover, suppose:

$\tilde{V}_\lambda: B_\lambda \rightarrow ]0, +\infty[$  is  $-1/2$ -concave and  $\mathcal{C}^\infty$  and  $\tilde{V}_\lambda \leq V_\lambda$ .

Set:

$$u_i(x) = \mathbb{E}_x \left( \exp \left( - \int_0^{\tau_{A_i}} \tilde{V}_i(X(s)) ds \right); \tau_{B_i^c} \geq \tau_{A_i} \right), \quad x \in \bar{B}_i, \quad i=0,1,$$

and:

$$u_\lambda(x) = \mathbb{E}_x \left( \exp \left( - \int_0^{\tau_{A_\lambda}} \tilde{V}_\lambda(X(s)) ds \right); \tau_{B_\lambda^c} \geq \tau_{A_\lambda} \right), \quad x \in \bar{B}_\lambda.$$

It now only remains to prove that:

$$u_\lambda(x_\lambda) \geq u_0(x_0) \wedge u_1(x_1), \quad x_0 \in \bar{B}_0, \quad x_1 \in \bar{B}_1.$$

Let  $u_\lambda^*(x_\lambda) = \sup \{ u_0(x_0) \wedge u_1(x_1); x_0 \in \bar{B}_0, x_1 \in \bar{B}_1 \}$ . If  $\neg(u_\lambda^* \leq u_\lambda)$ , then:

$$\sup(u_\lambda^* - u_\lambda) = u_\lambda^*(\hat{x}_\lambda) - u_\lambda(\hat{x}_\lambda) > 0,$$

for a suitable  $\hat{x}_\lambda \in \bar{B}_\lambda$ . Suppose  $u_\lambda^*(\hat{x}_\lambda) = u_0(\hat{x}_0) \wedge u_1(\hat{x}_1)$ , where  $\hat{x}_\lambda = (1-\lambda)\hat{x}_0 + \lambda\hat{x}_1$ . Certainly,  $(\hat{x}_0, \hat{x}_1) \in (B_0 \times B_1) \setminus (\bar{A}_0 \times \bar{A}_1)$ . Also it is easy to see that the relation  $\hat{x}_0 \notin A_0$ ,

$\hat{x}_1 \in A_1$  is contradictory. Indeed, arbitrarily close to  $\hat{x}_0$  there are points where  $u_0$  exceeds  $u_0(\hat{x}_0)$ , by the maximum principle. Thus, by symmetry,  $(\hat{x}_0, \hat{x}_1) \in (B_0 \setminus \bar{A}_0) \times (B_1 \setminus \bar{A}_1)$ .

In the following, let  $i=0$  or  $1$  and  $j=0, 1$ , or  $\lambda$ .

Suppose  $h \in \mathbb{R}^n$  and  $h; \nabla u_i(\hat{x}_i) > 0$  ( $i$  fixed). Then, if  $s > 0$  is small,  $u_i(\hat{x}_i + sh) > u_i(\hat{x}_i)$  and, hence,  $u_\lambda^*(\hat{x}_\lambda + s\lambda_i h) > u_\lambda^*(\hat{x}_\lambda)$ , where  $\lambda_i = (2i-1)\lambda + 1 - i$ , so that  $u_\lambda(\hat{x}_\lambda + s\lambda_i h) \geq u_\lambda(\hat{x}_\lambda)$ . Accordingly,  $h; \nabla u_\lambda(\hat{x}_\lambda) \geq 0$  and it follows that the non-zero vectors  $\nabla u_i(\hat{x}_i)$  and  $\nabla u_\lambda(\hat{x}_\lambda)$  are parallel. Let  $a_j = |\nabla u_j(\hat{x}_j)|$  and  $v = \nabla u_j(\hat{x}_j)/a_j$ .

From now on we assume that  $u_\lambda^*(\hat{x}_\lambda) = u_0(\hat{x}_0)$ . The case  $u_\lambda^*(\hat{x}_\lambda) = u_1(\hat{x}_1)$  may be treated in a similar way.

Let  $h \in \mathbb{R}^n$  be such that  $\kappa = h; v \neq 0$ . For each  $s$  close to  $0$  there exists a unique  $r = r(s)$ , with  $|r|$  minimal, satisfying the equation :

$$u_0(\hat{x}_0 + sh/a_0) - u_0(\hat{x}_0) = u_1(\hat{x}_1 + rh/a_1) - u_1(\hat{x}_1).$$

Writing:

$$\hat{x}_\lambda(s) = (1-\lambda)(\hat{x}_0 + sh/a_0) + \lambda(\hat{x}_1 + r(s)h/a_1) = \hat{x}_\lambda + [(1-\lambda)s/a_0 + \lambda r(s)/a_1]h,$$

we have:

$$u_0(\hat{x}_0 + sh/a_0) - u_\lambda(\hat{x}_\lambda(s)) \leq u_\lambda^*(\hat{x}_\lambda(s)) - u_\lambda(\hat{x}_\lambda(s)) \leq u_0(\hat{x}_0) - u_\lambda(\hat{x}_\lambda)$$

and, in particular:

$$D_s^k(u_0(\hat{x}_0 + sh/a_0) - u_\lambda(\hat{x}_\lambda(s)))|_{s=0} = \begin{cases} 0, & k=1 \\ \leq 0, & k=2. \end{cases}$$

Next suppose:

$$u_j(\hat{x}_j + sh/a_j) = u_j(\hat{x}_j) + \kappa s + b_j s^2 + o(s^2) \quad \text{as } s \rightarrow 0.$$

Then:

$$r(s) = s + \kappa^{-1}(b_0 - b_1)s^2 + o(s^2) \quad \text{as } s \rightarrow 0$$

and introducing  $p = (1-\lambda)/a_0 + \lambda/a_1$  we have:

$$\begin{cases} a_\lambda p = 1, \\ \left(1 - \lambda \frac{a_\lambda}{a_1}\right) b_0 + \lambda \frac{a_\lambda}{a_1} b_1 - b_\lambda \leq 0. \end{cases}$$

Thus:

$$\sum_{1 \leq \alpha, \beta \leq n} \left[ \frac{1-\lambda}{a_0^3} D_{\alpha\beta} u_0(\hat{x}_0) + \frac{\lambda}{a_1^3} D_{\alpha\beta} u_1(\hat{x}_1) - \frac{1}{a_\lambda^3} D_{\alpha\beta} u_\lambda(\hat{x}_\lambda) \right] h_\alpha h_\beta \leq 0$$

and, accordingly:

$$\frac{1-\lambda}{a_0^3} V_0(\hat{x}_0) u_0(\hat{x}_0) + \frac{\lambda}{a_1^3} V_1(\hat{x}_1) u_1(\hat{x}_1) \leq p^3 \tilde{V}_\lambda(\hat{x}_\lambda) u_\lambda(\hat{x}_\lambda).$$

Finally, noting that  $u_\lambda(\hat{x}_\lambda) < u_0(\hat{x}_0) \wedge u_1(\hat{x}_1)$  we get:

$$\frac{1-\lambda}{a_0^3} V_0(\hat{x}_0) + \frac{\lambda}{a_1^3} V_1(\hat{x}_1) < p^3 V_\lambda(\hat{x}_\lambda),$$

which contradicts Lemma 5.1. Hence  $u_\lambda^* \leq u_\lambda$ .  $\square$

### 6. Quasi-concavity of V-harmonic measures restricted to supporting hyperplanes

We first recall some known properties of quasi-concave measures on Banach spaces. All the results may be found in the author's papers [6] and [8].

A non-negative finite Borel measure  $\mu$  on  $E$  is quasi-concave if:

$$(6.1) \quad \mu(A_\lambda) \geq \mu(A_0) \wedge \mu(A_1),$$

for all  $0 < \lambda < 1$  and all  $A_0, A_1 \in \mathcal{B}(E)$  = the Borel field in  $E$ . It turns out that a non-negative finite Borel measure  $\mu$  on  $E$  is quasi-concave if (6.1) holds for all  $0 < \lambda < 1$  and all  $A_0, A_1 \in \mathcal{U}(E)$ .

Next suppose  $0 < \lambda < 1$  is fixed and suppose  $\mu_0, \mu_1, \mu_\lambda$  are quasi-concave measures on  $E$ . If:

$$(6.2) \quad \mu_\lambda(A_\lambda) \geq \mu_0(A_0) \wedge \mu_1(A_1),$$

for all  $A_0, A_1 \in \mathcal{U}(E)$ , then (6.2) is true for all  $A_0, A_1 \in \mathcal{B}(E)$ . Moreover, if  $E = \mathbb{R}^n$  and  $d\mu_j = f_j dx$ ,  $j=0, 1, \lambda$ , where the  $f_j: E \rightarrow [0, +\infty]$  are semi-continuous from below, then (6.2) holds for all Borel sets  $A_0, A_1$  in  $\mathbb{R}^n$  if and only if:

$$f_\lambda^{-1/n}(x_\lambda) \leq (1-\lambda) f_0^{-1/n}(x_0) + \lambda f_1^{-1/n}(x_1), \quad x_0, x_1 \in \mathbb{R}^n.$$

The above makes it possible to pass from convex bodies to Borel sets in a very special but still interesting case of Theorem 3.1.

**THEOREM 6.1.** — *Let  $B \in \mathcal{U}(E)$  and suppose  $F$  is a supporting hyperplane ( $0 \in F$ ) of  $\bar{B}$ . If  $V: B \rightarrow [0, +\infty[$  is  $-1/2$ -concave, then the V-harmonic measure:*

$$\kappa_x(A) = \mathbb{E}_x \left( \exp \left( - \int_0^{\tau_{B^c}} V(X(s)) ds \right); X(\tau_{B^c}) \in A \right), \quad A \in \mathcal{B}(B^c),$$

at  $x \in B$  satisfies:

$$\kappa_{x_\lambda}(A_\lambda) \geq \kappa_{x_0}(A_0) \wedge \kappa_{x_1}(A_1), \quad 0 < \lambda < 1, \quad A_0, A_1 \in \mathcal{B}(F).$$

In particular,  $\kappa_{x|\mathcal{B}(F)}$  is quasi-concave.

*Proof.* — First note that for any closed  $A \subseteq B^c$ :

$$\kappa_x(A) = \mathbb{E}_x \left( \exp \left( - \int_0^{\tau_A} V(X(s)) ds \right); \tau_{B^c} \geq \tau_A < +\infty \right),$$

because  $x \in B$  is non-regular for  $B^c$ . Hence the inequality we shall prove is true for all  $A_0, A_1 \in \mathcal{U}(F)$  and Theorem 6.1 follows from what we said above.  $\square$

*Example 6.1.* — Let  $G$  be a Borel measurable additive subgroup of  $F$ , where we abide by the various assumptions in Theorem 6.1. Then  $\kappa_x(G)$  or  $\kappa_x(F \setminus G) = 0$  from the zero-one law of quasi-concave measures [6]. A direct proof of this fact is rather simple but we do not know any proof independent of the zero-one law of quasi-concave measures.  $\square$

*Example 6.2.* — Let  $E = \mathbb{R}^n$  but otherwise assume the same conditions as in Theorem 6.1.

If  $\bar{B} \cap F = C$  is  $(n-1)$ -dimensional, then an appropriate version of the restricted Poisson kernel  $(d\kappa_x/d\sigma_{\partial B})(y), (x, y) \in B \times C$ , is  $-1/(n-1)$ -convex.  $\square$

*Example 6.3.* — If  $C_0, C_1 \in \mathcal{U}_\infty(\mathbb{R}^n)$ , then the original Brunn-Minkowski inequality states that:

$$(6.3) \quad |C_0 + C_1|^{1/n} \geq |C_0|^{1/n} + |C_1|^{1/n}.$$

To deduce this estimate from (1.1) we let  $B_0 = B_1 = \{x_{n+1} > 0\} \subseteq \mathbb{R}^{n+1}$ ,  $x = x_0 = x_1 = (\alpha, \dots, \alpha, 1)$ , and get:

$$|\alpha|^{n+1} \int_{C_\lambda} \frac{dy}{\|x-y\|^{n+1}} \geq |\alpha|^{n+1} \left( \int_{C_0} \frac{dy}{\|x-y\|^{n+1}} \wedge \int_{C_1} \frac{dy}{\|x-y\|^{n+1}} \right), \quad 0 < \lambda < 1.$$

As  $|\alpha| \rightarrow +\infty$ , we obtain  $|C_\lambda| \geq |C_0| \wedge |C_1|$  or, due to homogeneity, (6.3). In fact, already Minkowski's ideas entail (6.3) for arbitrary Borel sets but the Gabriel differential method seems to collapse beyond star-shaped bodies.  $\square$

### 7. Quasi-concavity of V-Newtonian potentials of very thin bodies

Consider, for  $\dim E \geq 3$ , the Newtonian potential of  $A \in \mathcal{B}(E)$ :

$$v_x(A) = E. \left( \int_0^\infty 1_A(X(t)) dt \right),$$

that is, the expected amount of time the Brownian motion spends in  $A$ . If  $x \in E$  is fixed, the measure  $v_x$  is not quasi-concave, although, by ([8], Th. 5.1):

$$v_{x_0+x_1}(A_0 + A_1) \geq v_{x_0}(A_0) \wedge v_{x_1}(A_1),$$

or, stated otherwise:

$$v_{x_{1/2}}(A_{1/2}) \geq \frac{1}{4} [v_{x_0}(A_0) \wedge v_{x_1}(A_1)],$$

for all  $x_0, x_1 \in E$  and all  $A_0, A_1 \in \mathcal{B}(E)$ . The convexity behaviour of  $v_x(A)$ , with  $A \in \mathcal{U}(E)$  fixed, is unknown to us.

The main questions we focus on in this section have no direct meaning without restriction on  $\dim E$ . We therefore assume throughout that  $E = \mathbb{R}^n$ ,  $n \geq 2$ .

Now suppose  $B \in \mathcal{U}(\mathbb{R}^n)$  and that  $V: B \rightarrow [0, +\infty[$  is  $-1/2$ -concave. Moreover, we suppose  $B \neq \mathbb{R}^2$  if  $n=2$  and  $V=0$  so that  $B$  becomes a Greenian domain for the operator  $-1/2 \Delta + V$  with the Dirichlet boundary condition zero. Let:

$$v_x(A) = \mathbb{E}_x \left( \int_0^{\tau_B^c} 1_A(X(t)) \exp \left( - \int_0^t V(X(s)) ds \right) dt \right) = \int_A g(x, y) dy, \quad x \in B,$$

be the  $V$ -Newtonian potential of  $A \in \mathcal{B}(B)$ ,  $g$  being the corresponding Green function. The reader should note that  $g: B \times B \rightarrow [0, +\infty[$  is continuous (see e. g. [13], Chap. 13). In particular, given a  $k$ -dimensional affine manifold  $F$  in  $\mathbb{R}^n$  possessing Lebesgue measure  $m^F (m^{(a)} = \delta_a)$ , the  $V$ -Newtonian potential of any  $A \in \mathcal{B}(F \cap B)$ , viz:

$$v_x^F(A) = \int_A g(x, y) dm^F(y), \quad x \in B,$$

becomes well-defined.

**THEOREM 7.1.** — *If  $\dim F = n - 2$ , then:*

$$v_{x_i}^{c_i + F}(A_\lambda) \geq v_{x_0}^{c_0 + F}(A_0) \wedge v_{x_1}^{c_1 + F}(A_1), \quad 0 < \lambda < 1,$$

where  $A_i \in \mathcal{B}((c_i + F) \cap B)$ ,  $c_i \in \mathbb{R}^n$ , and  $x_i \in B$ ,  $i=0, 1$ , are arbitrary.

Before presenting the proof of Theorem 7.1, we recall some basic facts from potential theory.

Suppose  $A \in \mathcal{U}_\infty(\mathbb{R}^n)$  and  $\bar{A} \subseteq B$ . Then there exists a unique non-negative measure  $\mu_A$  in  $\bar{A}$ , called the  $V$ -equilibrium measure of  $A$ , such that:

$$\int g(x, y) d\mu_A(y) = \mathbb{E}_x \left( \exp \left( - \int_0^{\tau_A} V(X(s)) ds \right); \tau_B^c \geq \tau_A < +\infty \right), \quad x \in B.$$

The total mass  $\mu_A(\bar{A}) = \mathcal{C}(A)$  is termed the  $V$ -capacity of  $A$  and, moreover, writing  $g\mu = (\mu(g(x, \cdot)))_{x \in B}$  if  $\mu$  is a non-negative measure in  $B$ :

$$\mathcal{C}(A) = \sup \{ \mu(B); \text{supp } \mu \subseteq A, g\mu \leq 1 \}$$

(see e. g. Blumental, Gettoor [3], Chap. 6.4).

*Proof of Theorem 7.1.* — We shall prove that  $g$  is  $-1/(n-2)$ -convex. By eventually diminishing  $V$  and using the Dini theorem, there is no loss of generality in assuming  $\sup V = q < +\infty$ .

In the following, we sometimes write  $g^{B,V}$ ,  $\mathcal{C}^{B,V}$ ,  $\mu_A^{B,V}$  instead of  $g$ ,  $\mathcal{C}$ , and  $\mu_A$ , respectively, and assume, as we may, that  $X$  is the standard Brownian motion.

Case  $n \geq 3$ . — Letting  $\mathcal{C}^{\mathbb{R}^n}(\mathbf{B}(0; r)) = c_n r^{n-2}$ , we claim that:

$$(7.1) \quad \lim_{r \rightarrow 0^+} \frac{\mathcal{C}^{\mathbf{B}, \mathbf{V}}(\mathbf{B}(y; r))}{c_n r^{n-2}} = 1, \quad y \in \mathbf{B}.$$

To see this, let  $y \in \mathbf{B}$  be fixed and write  $\mathbf{B}_r = \mathbf{B}(y; r)$  for brevity. Then, if  $\mathbf{B}_r \subseteq \bar{\mathbf{B}}_R \subseteq \mathbf{B}$ , certainly:

$$c_n r^{n-2} \leq \mathcal{C}^{\mathbf{B}, \mathbf{V}}(\mathbf{B}_r) \leq \mathcal{C}^{\mathbf{B}_R, q}(\mathbf{B}_r).$$

We next integrate:

$$g^{\mathbf{B}_R, 0} = g^{\mathbf{B}_R, q} + q g^{\mathbf{B}_R, 0} g^{\mathbf{B}_R, q},$$

with respect to  $\mu_{\mathbf{B}_r}^{\mathbf{B}_R, 0} \otimes \mu_{\mathbf{B}_r}^{\mathbf{B}_R, q}$ , arriving at:

$$\mathcal{C}^{\mathbf{B}_R, q}(\mathbf{B}_r) \leq \mathcal{C}^{\mathbf{B}_R, 0}(\mathbf{B}_r) + q d_n R^n,$$

where  $d_n = \text{Vol } \mathbf{B}(0; 1)$ . Moreover, by integrating:

$$g^{\mathbf{B}_R, 0}(x, \xi) = g^{\mathbb{R}^n, 0}(x, \xi) - \mathbb{E}_x g^{\mathbb{R}^n, 0}(X(\tau_{\mathbf{B}_R^c}), \xi)$$

with respect to  $\mu_{\mathbf{B}_r}^{\mathbf{B}_R, 0}(dx) \otimes \mu_{\mathbf{B}_r}^{\mathbb{R}^n, 0}(d\xi)$ , we get:

$$\mathcal{C}^{\mathbf{B}_R, 0}(\mathbf{B}_r) = c_n r^{n-2} (1 - (r/R)^{n-2})^{-1}.$$

Finally, by choosing  $R = r^{1-1/n}$  in the above estimates (7.1) follows at once.

Writing  $g = g^{\mathbf{B}, \mathbf{V}}$  as above we have for all  $r_0, r_1 > 0$ ,  $0 < \lambda < 1$ , and  $\varepsilon > 0$ :

$$\varepsilon^{2-n} (g \mu_{\mathbf{B}(y_\lambda; \varepsilon r_\lambda)})(x_\lambda) \geq \varepsilon^{2-n} [(g \mu_{\mathbf{B}(y_0; \varepsilon r_0)})(x_0) \wedge (g \mu_{\mathbf{B}(y_1; \varepsilon r_1)})(x_1)],$$

by Theorem 3.1, and in the limit as  $\varepsilon \rightarrow 0^+$ :

$$g(x_\lambda, y_\lambda) r_\lambda^{n-2} \geq g(x_0, y_0) r_0^{n-2} \wedge g(x_1, y_1) r_1^{n-2}.$$

Thus, choosing  $r_i = (g(x_i, y_i))^{-1/(n-2)}$ , if  $x_i \neq y_i$ ,  $i=0,1$ , the resulting inequality becomes:

$$g^{-1/(n-2)}(x_\lambda, y_\lambda) \leq (1-\lambda) g^{-1/(n-2)}(x_0, y_0) + \lambda g^{-1/(n-2)}(x_1, y_1),$$

and it follows at once that  $g$  is  $-1/(n-2)$ -convex.

Case  $n=2$ . — If Theorem 7.1 is true in  $\mathbb{R}^{n_0+1}$ ,  $n_0 \geq 2$ , then we may use the theory of  $\alpha$ -convex measures to prove Theorem 7.1 in  $\mathbb{R}^{n_0}$ . Indeed, set  $\tilde{\mathbf{V}}(x, \xi) = \mathbf{V}(x)$ ,  $(x, \xi) \in \mathbf{B} \times \mathbb{R}$  and note that:

$$g(x, y) = \int_{-\infty}^{\infty} g^{\mathbf{B} \times \mathbb{R}, \tilde{\mathbf{V}}}(x, 0, y, \eta) d\eta.$$

If  $g^{\mathbf{B} \times \mathbb{R}, \tilde{\mathbf{V}}}$  is  $-1/(n_0-1)$ -convex it follows from ([8], Th. 3.1) that  $g$  is  $-1/(n_0-2)$ -convex.  $\square$

In the following two examples we suppose in addition to the above assumptions that  $\partial B$  is  $\mathcal{C}^\infty$  and that  $V$  has a  $\mathcal{C}^\infty$  extension to a neighbourhood of  $\bar{B}$ .

*Example 7.1.* — For each  $y \in \partial B$ , let  $n_i(y) = n_i^B(y)$  denote the inner unit normal of  $\bar{B}$  at  $y$  and set:

$$p(x, y) = \lim_{\varepsilon \rightarrow 0^+} g(x, y + \varepsilon n_i(y)) / 2\varepsilon.$$

If  $n_i(y_0) = n_i(y_1)$ , then  $n_i(y_\lambda) = n_i(y_0)$ ,  $0 < \lambda < 1$ , and the  $-1/(n-2)$ -convexity of  $g$  gives:

$$p^{-1/(n-1)}(x_\lambda, y_\lambda) \leq (1-\lambda)p^{-1/(n-1)}(x_0, y_0) + \lambda p^{-1/(n-1)}(x_1, y_1),$$

employing the same type of argument as in the proof of Theorem 7.1. Noting that  $p(x, y) d\sigma_{\partial B}(y)$  is the  $V$ -harmonic measure at  $x$  (use ([17], Th. 6.14) and the Green formula) we have thus complemented Example 6.2.  $\square$

*Example 7.2.* — Let  $A \in \mathcal{U}_\infty(\mathbb{R}^n)$ ,  $\bar{A} \subseteq B$ , and assume  $\partial A \in \mathcal{C}^\infty$ . Moreover, suppose  $F$  is a supporting hyperplane of  $\bar{A}$  such that  $\bar{A} \cap F = C$  is  $(n-1)$ -dimensional. Then:

$$d\mu_{A|F(C)} = f d\sigma_C,$$

where  $f$  is  $-1$ -concave.

To see this, we apply the Green formula once more to get:

$$-\frac{1}{2} \frac{\partial u_A}{\partial n_e} d\sigma_{\partial A} = d\mu_A - 1_A \nabla dm,$$

where  $m$  is Lebesgue measure,  $u_A = g \mu_A$ , and  $n_e = -n_i^A$ . However, as  $u_A$  is quasi-concave  $-\partial u_A / \partial n_e$  is  $-1$ -concave on  $C$ .  $\square$

In the planar case, we shall complement Theorem 7.1 in the following way.

**THEOREM 7.2.** — Let for  $A \in \bar{\mathcal{U}}_\infty(C)$ ,  $g_A \leq 0$  be the Green function of  $\Delta$  in  $C \setminus A$  with pole at  $\infty$  and with the Dirichlet boundary condition zero. Then:

$$g_{A_\lambda}(z_\lambda) \geq g_{A_0}(z_0) \wedge g_{A_1}(z_1), \quad 0 < \lambda < 1.$$

*Proof.* — Assuming  $0 \in A$ ,  $g = g_A$  possesses the following characteristic properties:

- (i)  $g$  is harmonic in  $C \setminus A$ ;
- (ii)  $g$  is continuous in  $C$  and  $g|_A = 0$ ,
- (iii)  $g(z) = 1/n \frac{1}{|z|} - 1/n \frac{1}{\mathcal{C}_2(A)} + \mathcal{O}\left(\frac{1}{|z|}\right)$  as  $|z| \rightarrow +\infty$ .

The constant  $\mathcal{C}_2(A)$  is the logarithmic capacity of  $A$  [1]. If  $B(0; R) \supseteq A$  and  $u_A^{B(0; R)}$  denotes the equilibrium potential of  $A$  relative to  $B(0; R)$  we thus have:

$$(u_A^{B(0; R)}(z) - 1/n \frac{R}{\mathcal{C}_2(A)} - g_A(z)) = \mathcal{O}\left(\frac{1}{R}\right) \text{ as } R \rightarrow +\infty$$

and, consequently:

$$g_A(z) = \lim_{R \rightarrow +\infty} (u_A^{B(0; R)}(z) - 1) \frac{1}{n} \frac{R}{\mathcal{C}_2(A)}.$$

From this representation formula Theorem 7.2 follows at once using Theorem 3.1.  $\square$

*Example 7.3.* —  $\mathcal{C}_2$  is concave on  $\bar{\mathcal{U}}_\infty(\mathbb{C})$ :

$$(7.2) \quad \mathcal{C}_2(A_0 + A_1) \geq \mathcal{C}_2(A_0) + \mathcal{C}_2(A_1), \quad A_0, A_1 \in \bar{\mathcal{U}}_\infty(\mathbb{C}).$$

Indeed, as:

$$1/n \mathcal{C}_2(A) = \lim_{|z| \rightarrow +\infty} (g_A(z) + 1/n|z|).$$

Theorem 7.2 gives:

$$\mathcal{C}_2(A_i) \geq \mathcal{C}_2(A_0) \wedge \mathcal{C}_2(A_1),$$

and (7.2) follows by homogeneity.  $\square$

The next example is mainly a preparation for Example 7.5.

*Example 7.4.* — By an exercise in Pólya and Szegő [21], Aufg. [124] :

$$(7.3) \quad \mathcal{C}_2(A) \leq \frac{1}{2\pi} \text{length } \partial A, \quad A \in \bar{\mathcal{U}}_\infty(\mathbb{C}).$$

A possible solution reads as follows.

Let  $H_A$  be the support function of  $A$ :

$$H_A(\xi) = \sup_{x \in A} \langle x, \xi \rangle, \quad \xi \in \mathbb{C},$$

and remember that:

$$(7.4) \quad \int_0^{2\pi} H_A(e^{i\theta} \xi) d\theta / 2\pi = \frac{\|\xi\|}{2\pi} \text{length } \partial A, \quad \xi \in \mathbb{C}.$$

We next approximate the average in the left-hand side by:

$$\sum_{k=1}^p H_A(e^{i\theta_k} \xi) \lambda_k \quad (0 < \lambda_k < 1, \lambda_1 + \dots + \lambda_p = 1),$$

that is, by the support function of  $\sum_{k=1}^p \lambda_k e^{-i\theta_k} A$ . However,

$$\mathcal{C}_2 \left( \sum_{k=1}^p \lambda_k e^{-i\theta_k} A \right) \geq \mathcal{C}_2(A)$$

from Example 7.3 and as the right-hand side of (7.4) is the support function of a ball of radius  $1/2\pi \text{length } \partial A$ , we have (7.3).  $\square$



*Example 7.5.* — Consider an  $A \in \overline{\mathcal{U}}_\infty(\mathbb{R}^3)$  with principal radius  $R_1$  and  $R_2$  and mean curvature:

$$\mathcal{M}(A) = \frac{1}{2} \int_{\partial A} \left( \frac{1}{R_1} + \frac{1}{R_2} \right) d\sigma(\xi).$$

Then by a Theorem of Szegő [23], Satz III:

$$(7.5) \quad \mathcal{C}_3(A) \leq \frac{1}{4\pi} \mathcal{M}(A),$$

where  $\mathcal{C}_3$  is the Newtonian capacity normalized so that  $\mathcal{C}_3(B(0; 1)) = 1$ . A very important ingredient in Szegő's proof is the following inequality for mixed volumes due to Minkowski:

$$\mathcal{M}^2(A) \geq 4\pi \text{ area } \partial A.$$

Noting that  $\mathcal{C}_3$  is concave on  $\overline{\mathcal{U}}_\infty(\mathbb{R}^3)$  [4] due to (1.1) we, alternatively, obtain (7.5) as in the previous example. The  $n$ -dimensional counterpart of (7.5) is now obvious: if  $\mathcal{C}_n$  denotes the Newtonian capacity in  $\mathbb{R}^n$  ( $n \geq 3$ ,  $\mathcal{C}_n(B(0; 1)) = 1$ ) and if  $Z_n$  is a uniformly distributed random vector on  $S^{n-1}$ , then:

$$\mathbb{E} H_A(Z_n) \geq \mathcal{C}_n^{1/(n-2)}(A), \quad A \in \overline{\mathcal{U}}_\infty(\mathbb{R}^n).$$

Certainly, the Szegő line of reasoning leads to the same estimate.  $\square$

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